

# ECEN689: Special Topics in High-Speed Links Circuits and Systems Spring 2010

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## Lecture 4: Transmission Line Examples



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# Announcements

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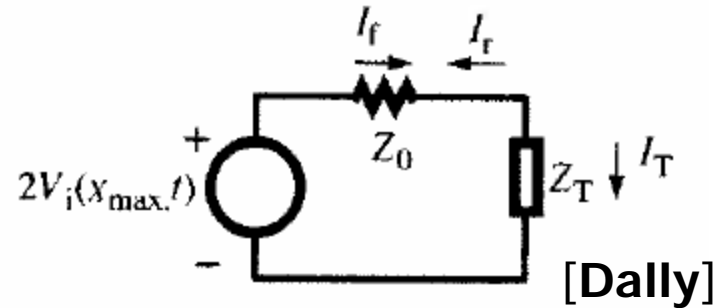
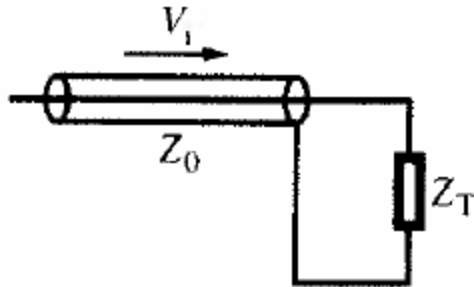
- HW1 due 1/29
  - One page summary of recent link design paper
- Current Reading
  - Chapter 3.3 – 3.4
- For next time
  - Chapter 3.6 – 3.7

# Agenda

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- Transmission Lines
  - Termination examples
  - Differential transmission lines
- Majority of today's material from Dally Chapter 3.3-3.4

# Reflections & Telegrapher's Eq.



- With a Thevenin-equivalent model of the line:

Termination Current: 
$$I_T = \frac{2V_i}{Z_0 + Z_T}$$

- KCL at Termination:

$$I_r = I_f - I_T$$

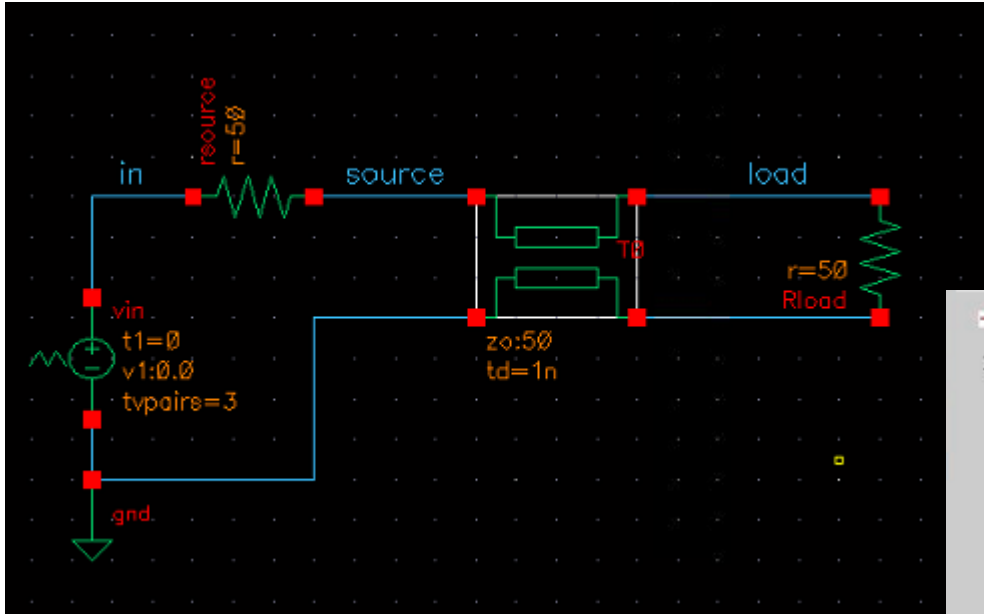
$$I_r = \frac{V_i}{Z_0} - \frac{2V_i}{Z_T + Z_0}$$

$$I_r = \frac{V_i}{Z_0} \left( \frac{Z_T - Z_0}{Z_T + Z_0} \right)$$

Telegrapher's Equation or  
**Reflection Coefficient**

$$k_r = \frac{I_r}{I_i} = \frac{V_r}{V_i} = \frac{Z_T - Z_0}{Z_T + Z_0}$$

# Termination Examples - Ideal



$$R_S = 50\Omega$$

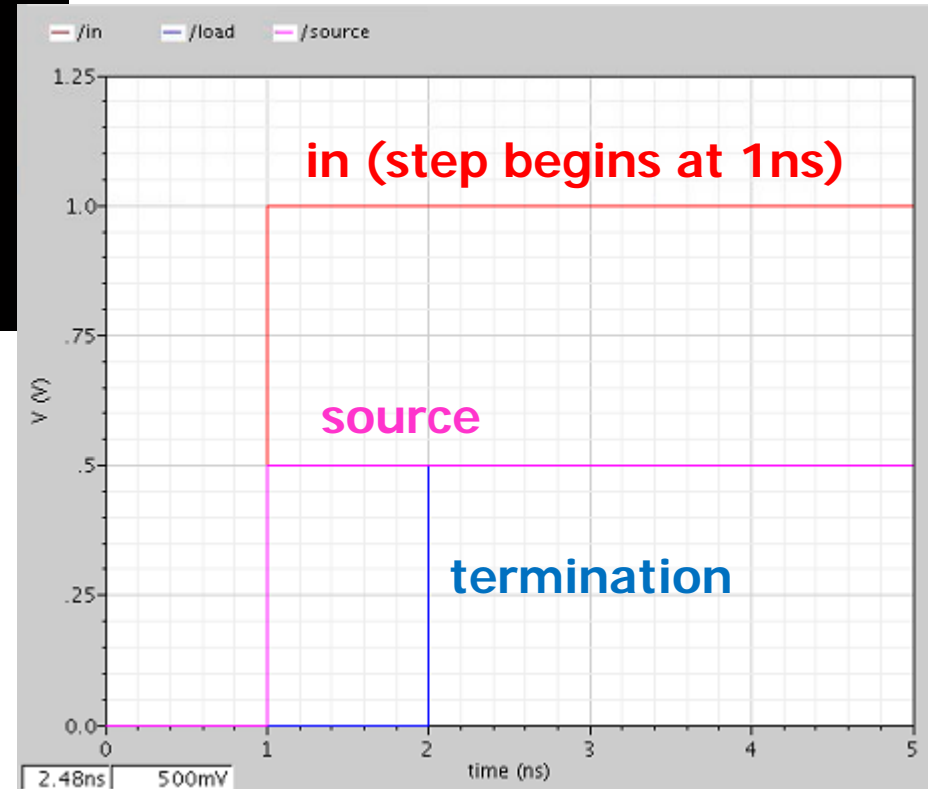
$$Z_0 = 50\Omega, t_d = 1\text{ns}$$

$$R_T = 50\Omega$$

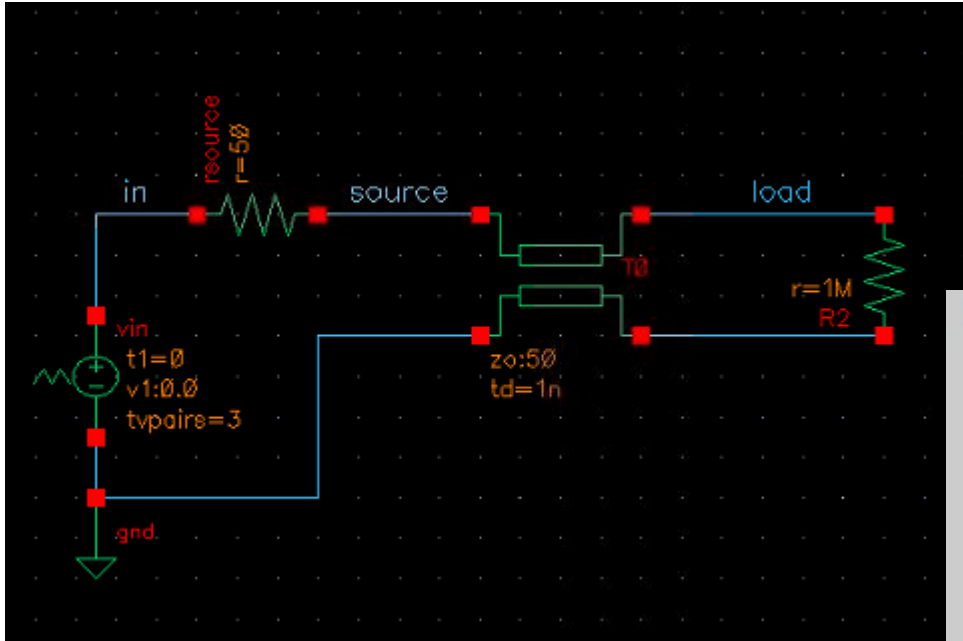
$$V_i = 1V \left( \frac{50}{50 + 50} \right) = 0.5V$$

$$k_{rT} = \frac{50 - 50}{50 + 50} = 0$$

$$k_{rS} = \frac{50 - 50}{50 + 50} = 0$$



# Termination Examples - Open



$$R_S = 50\Omega$$

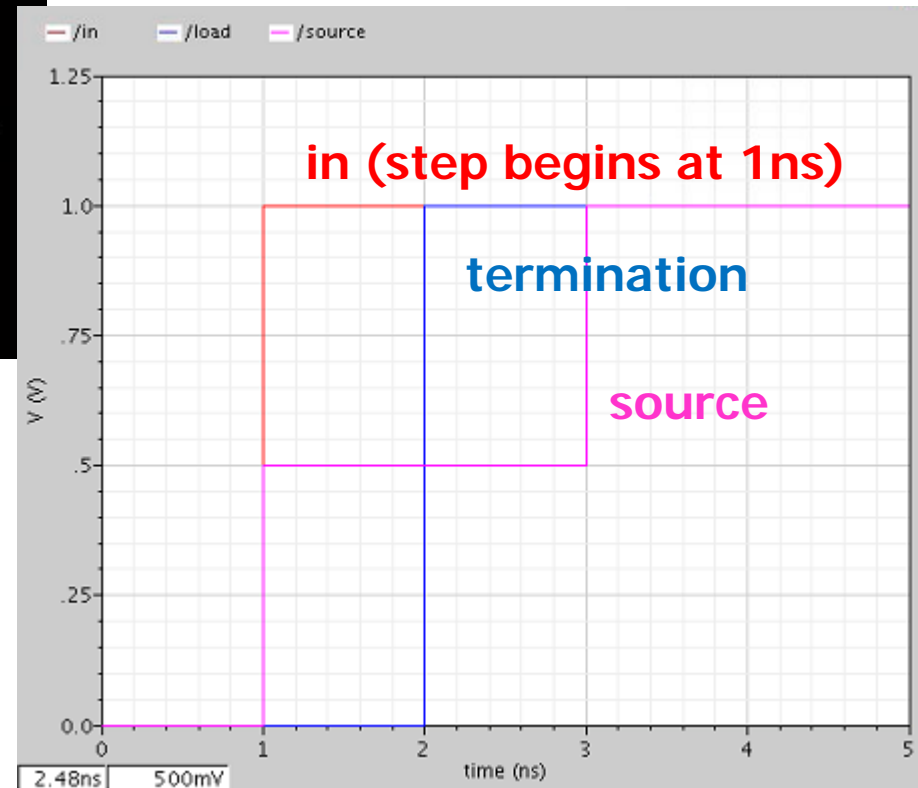
$$Z_0 = 50\Omega, t_d = 1\text{ns}$$

$$R_T \sim \infty (1\text{M}\Omega)$$

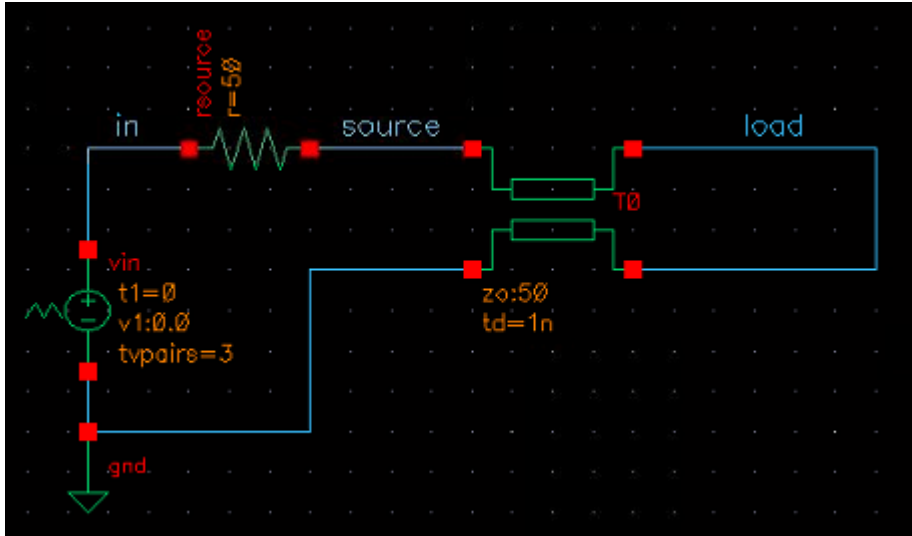
$$V_i = 1V \left( \frac{50}{50 + 50} \right) = 0.5V$$

$$k_{rT} = \frac{\infty - 50}{\infty + 50} = +1$$

$$k_{rS} = \frac{50 - 50}{50 + 50} = 0$$



# Termination Examples - Short



$$R_S = 50\Omega$$

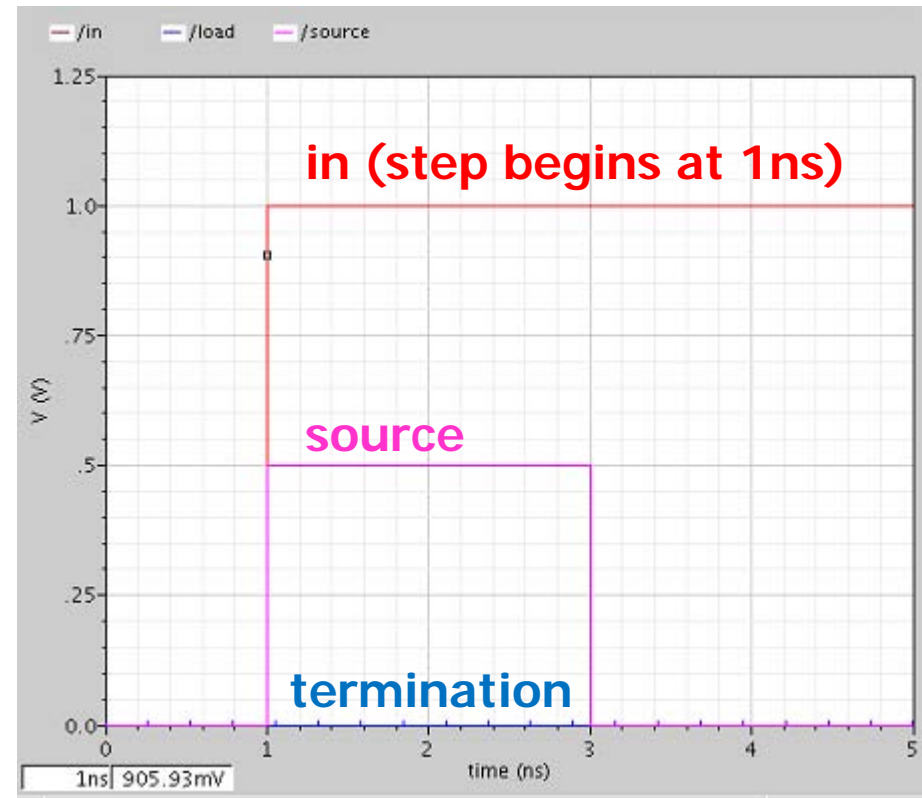
$$Z_0 = 50\Omega, t_d = 1\text{ns}$$

$$R_T = 0\Omega$$

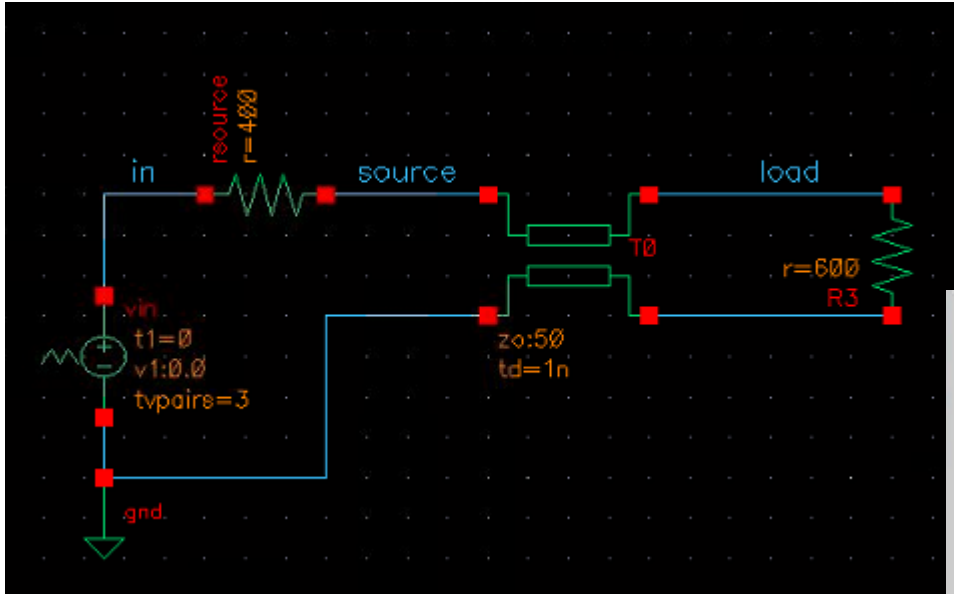
$$V_i = 1V \left( \frac{50}{50 + 50} \right) = 0.5V$$

$$k_{rT} = \frac{0 - 50}{0 + 50} = -1$$

$$k_{rS} = \frac{50 - 50}{50 + 50} = 0$$



# Arbitrary Termination Example



$$R_S = 400\Omega$$

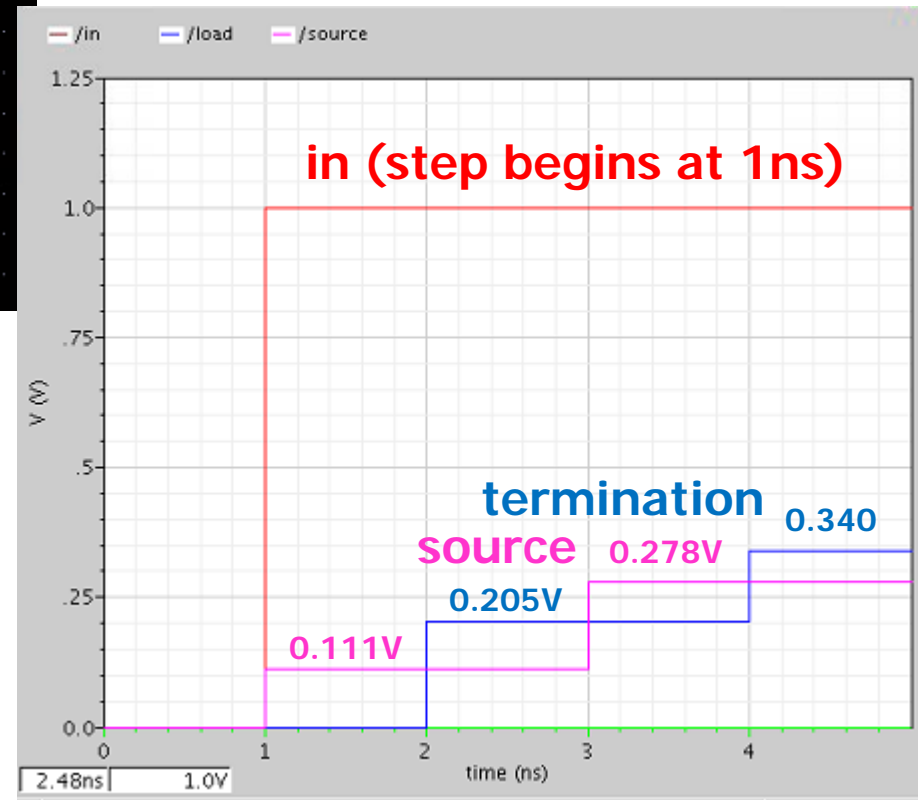
$$Z_0 = 50\Omega, t_d = 1\text{ns}$$

$$R_T = 600\Omega$$

$$V_i = 1V \left( \frac{50}{400 + 50} \right) = 0.111V$$

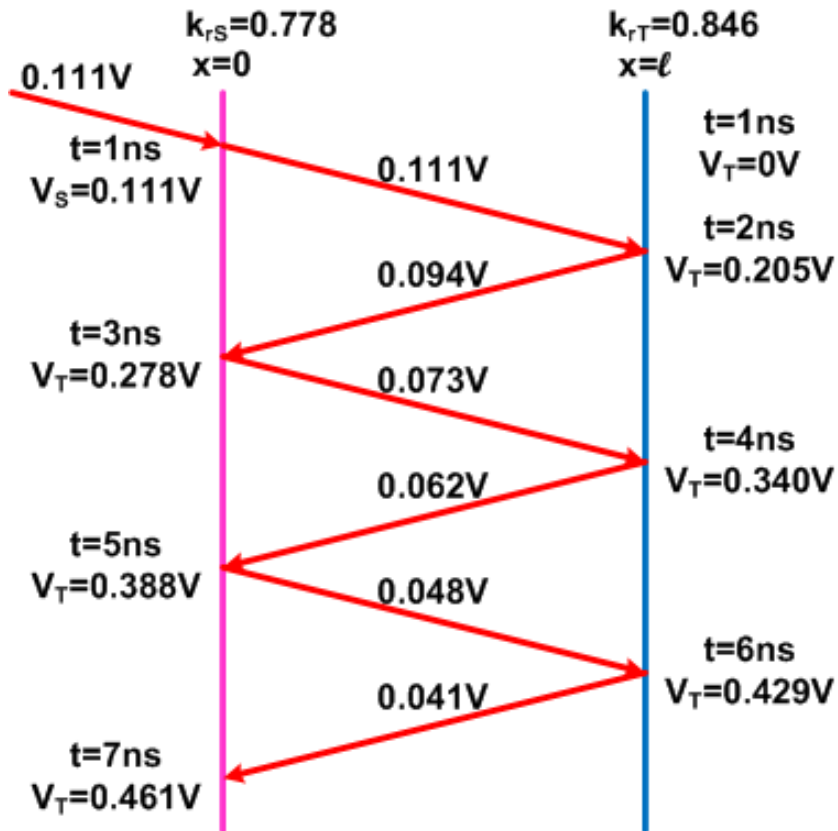
$$k_{rT} = \frac{600 - 50}{600 + 50} = 0.846$$

$$k_{rS} = \frac{400 - 50}{400 + 50} = 0.778$$





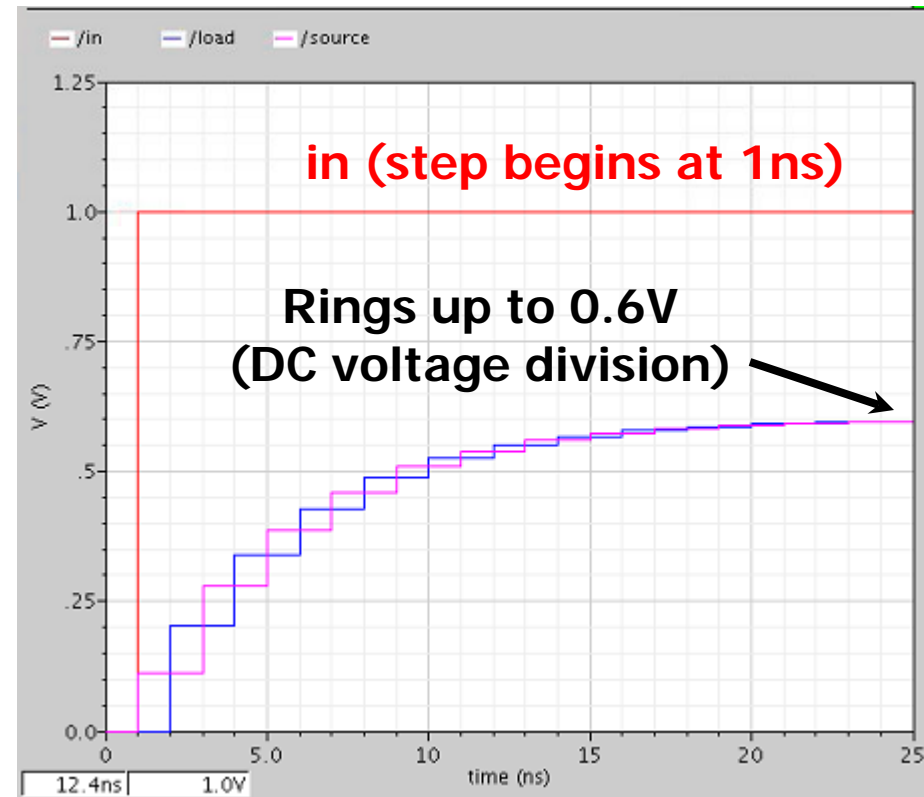
# Lattice Diagram



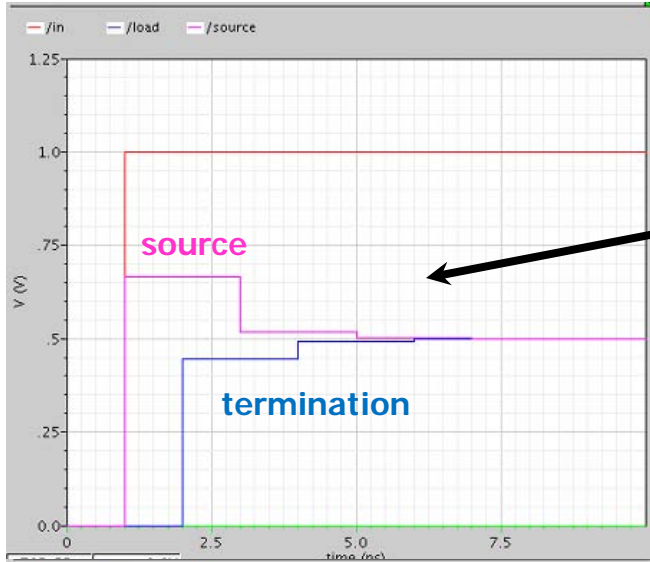
$$R_S = 400\Omega$$

$$Z_0 = 50\Omega, t_d = 1\text{ns}$$

$$R_T = 600\Omega$$



# Termination Reflection Patterns



$R_S = 25\Omega, R_T = 25\Omega$

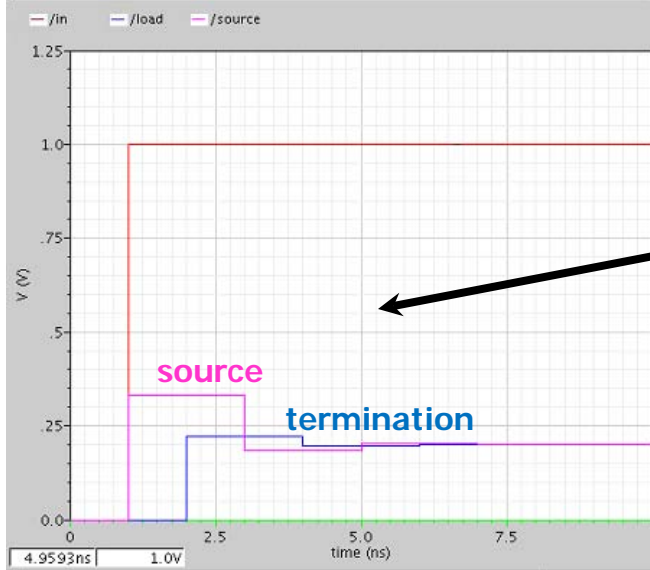
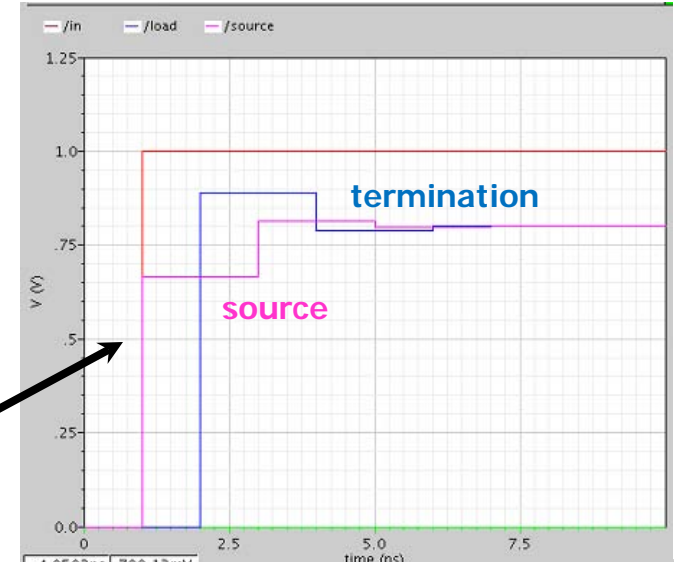
$kr_S \text{ \& } kr_T < 0$

Voltages Converge

$R_S = 25\Omega, R_T = 100\Omega$

$kr_S < 0 \text{ \& } kr_T > 0$

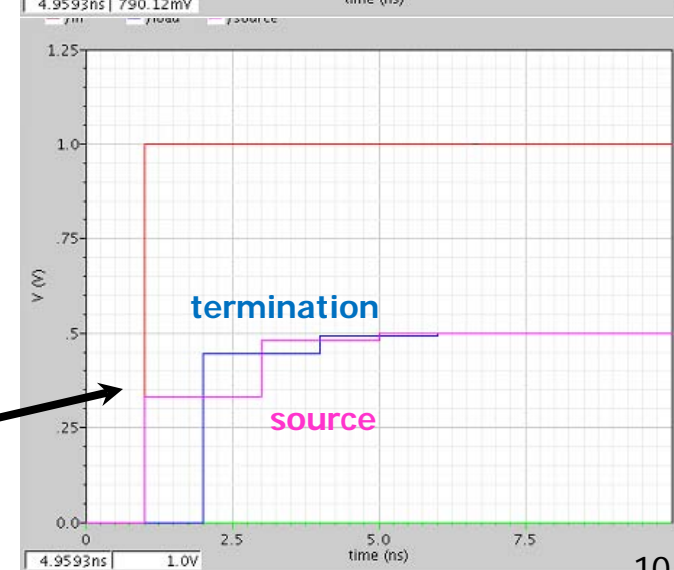
Voltages Oscillate



$R_S = 100\Omega, R_T = 25\Omega$

$kr_S > 0 \text{ \& } kr_T < 0$

Voltages Oscillate



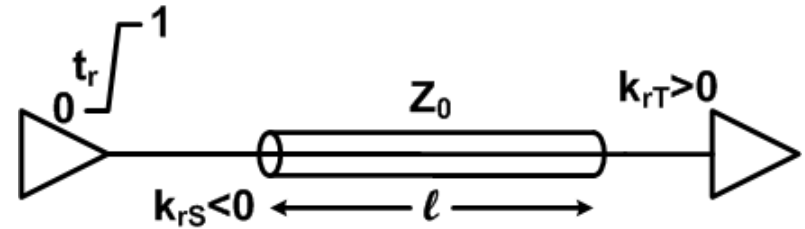
$R_S = 100\Omega, R_T = 100\Omega$

$kr_S > 0 \text{ \& } kr_T < 0$

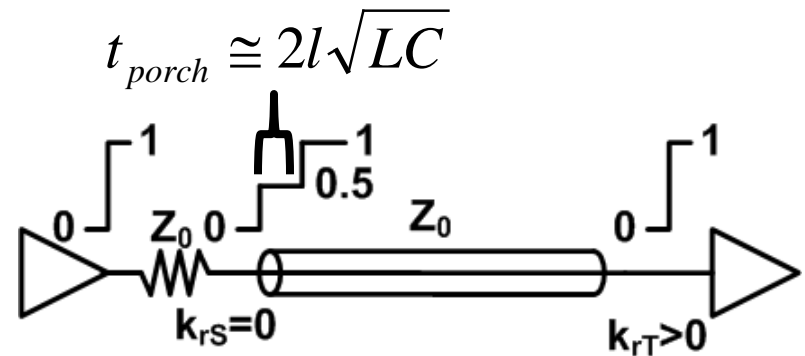
Voltages Ring Up

# Termination Schemes

- No Termination
  - Little to absorb line energy
  - Can generate oscillating waveform
  - Line must be **very short** relative to signal transition time
    - $n = 4 - 6$
  - Limited off-chip use
- Source Termination
  - Source output takes 2 steps up
  - Used in moderate speed point-to-point connections



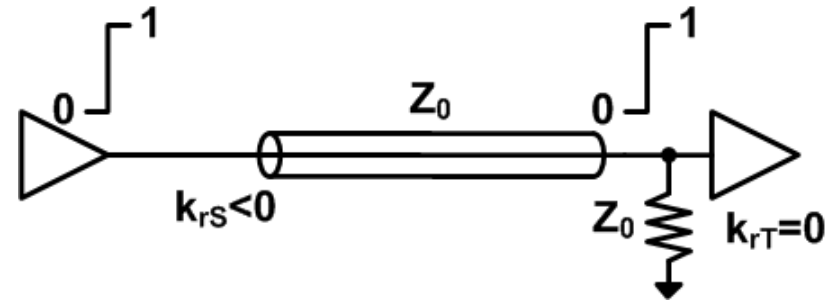
$$t_r > nT_{\text{round-trip}} = 2nl\sqrt{LC}$$



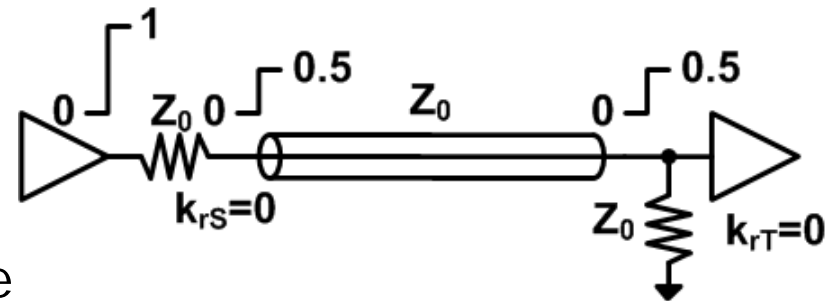
$$t_{\text{porch}} \cong 2l\sqrt{LC}$$

# Termination Schemes

- Receiver Termination
  - No reflection from receiver
  - Watch out for intermediate impedance discontinuities
    - Little to absorb reflections at driver

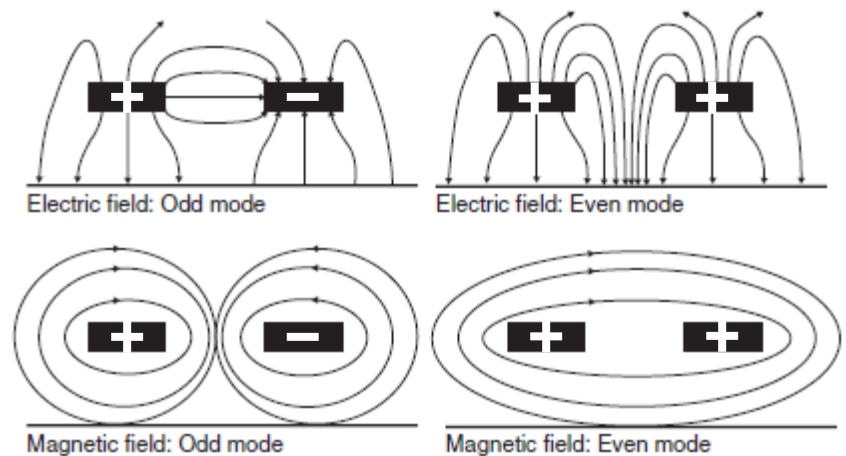


- Double Termination
  - Best configuration for min reflections
    - Reflections absorbed at both driver and receiver
  - Get half the swing relative to single termination
  - Most common termination scheme for high performance serial links



# Differential Transmission Lines

- Differential signaling advantages
  - Self-referenced
  - Common-mode noise rejection
  - Increased signal swing
  - Reduced self-induced power-supply noise
- Requires 2x the number of signaling pins relative to single-ended signaling
  - But, smaller ratio of supply/signal (return) pins
  - Total pin overhead is typically 1.3-1.8x (vs 2x)

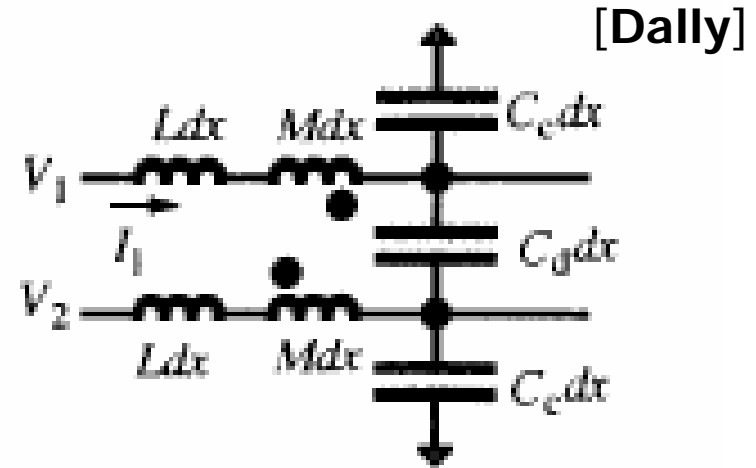


[Hall]

# Balanced Transmission Lines

- Even (common) mode excitation
  - Effective  $C = C_C$
  - Effective  $L = L + M$
- Odd (differential) mode excitation
  - Effective  $C = C_C + 2C_d$
  - Effective  $L = L - M$

$$Z_{DIFF} = 2Z_{even}, \quad Z_{CM} = \frac{Z_{odd}}{2}$$

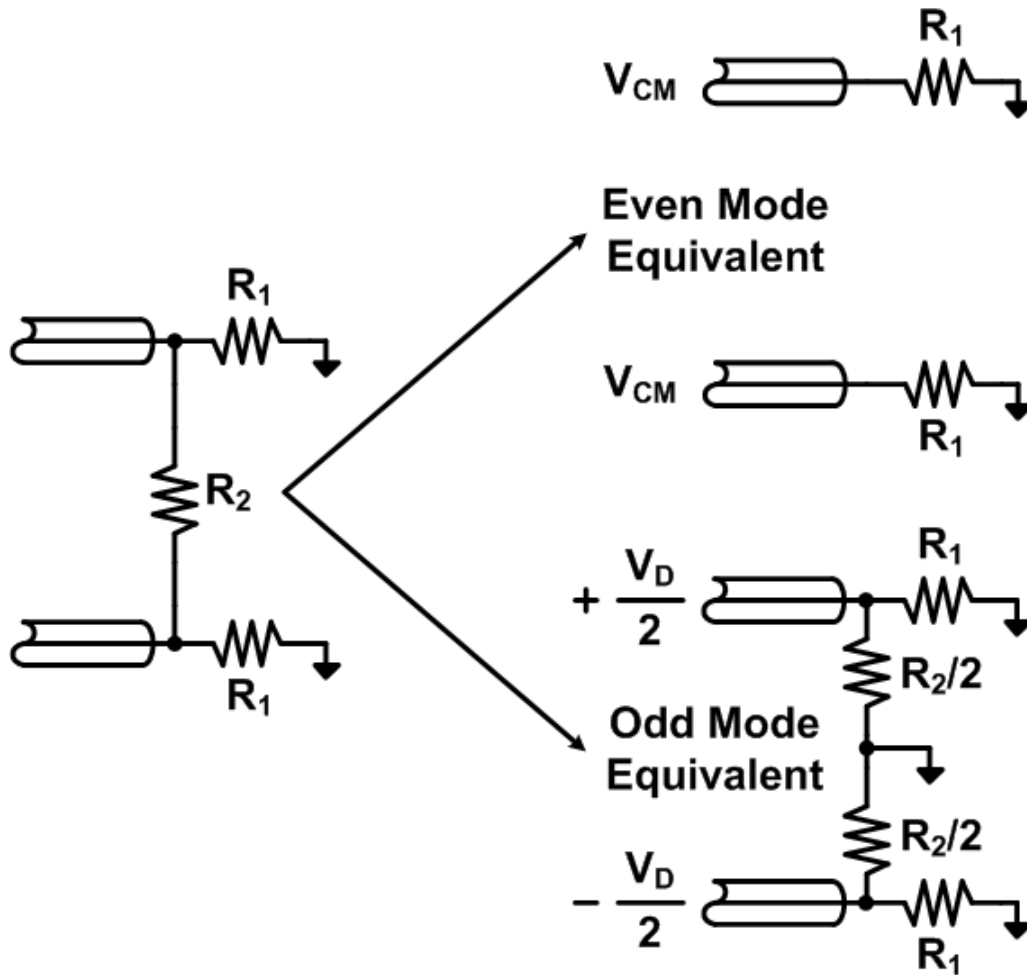


(a) Model of a Balanced Line

$$Z_{even} = \left( \frac{L + M}{C_c} \right)^{1/2}$$

$$Z_{odd} = \left( \frac{L - M}{C_c + 2C_d} \right)^{1/2}$$

# PI-Termination

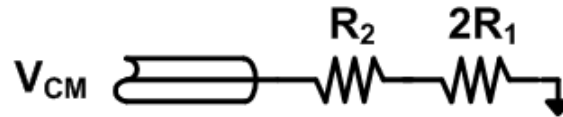


$$Z_{even} = R_1$$

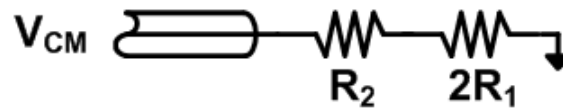
$$Z_{odd} = R_1 \parallel R_2/2 = Z_{even} \parallel R_2/2$$

$$R_2 = 2 \left( \frac{Z_{odd} Z_{even}}{Z_{even} - Z_{odd}} \right)$$

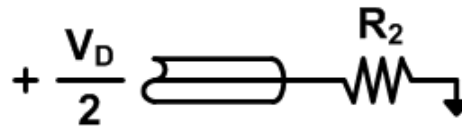
# T-Termination



Even Mode  
Equivalent



$$Z_{odd} = R_2 + 2R_1$$

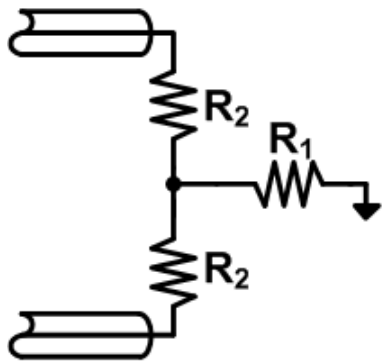


Odd Mode  
Equivalent



$$Z_{odd} = R_2$$

$$R_1 = \frac{1}{2}(Z_{even} - Z_{odd})$$





# Next Time

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- Channel modeling
  - Time domain reflectometer (TDR)
  - Network analysis