ECEN689: Special Topics in High-Speed Links Circuits and Systems
Spring 2010

Lecture 23: Jitter

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Announcements

- HW6 due Wednesday April 7 (in class)
- Exam 2 will be either April 28 or 30
- Reading
  - Will post some jitter application notes
  - Majority of today's material from Hall reference

Agenda

- Noise Budget Example
- Jitter

Noise Source Classifications

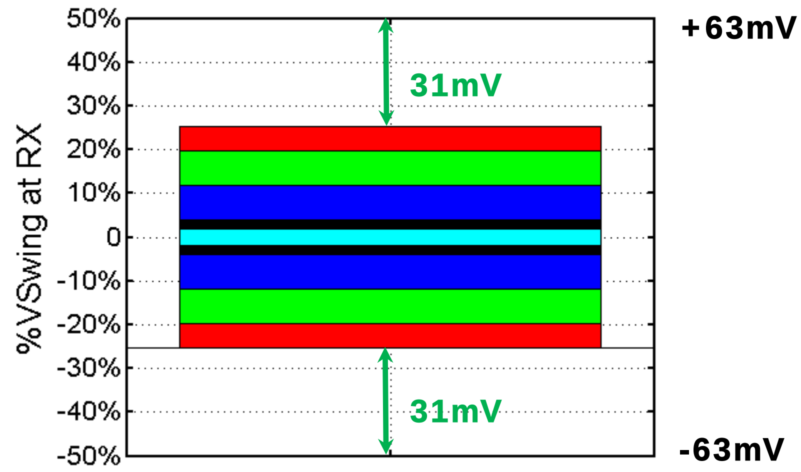
- Determining whether noise source is
  - Proportional vs Independent
  - Bounded vs Statistical
- is important in noise budgeting

	Proportional	Independent
Bounded	Residual ISI Crosstalk	RX Offset RX Sensitivity Power Supply Noise
Statistical	Large-Channel Crosstalk	Random Noise

Noise Budget Example

- Peak TX differential swing of $400mV_{ppd}$ equalized down 10dB
  - ±200mV → ±63mV

Parameter	**K_n**	**RMS**	**Value (BER=10^{-12})**
Peak Differential Swing			0.4V
RX Offset + Sensitivity			5mV
Power Supply Noise			5mV
Residual ISI	0.05		20mV
Crosstalk	0.05		20mV
Random Noise		1mV	14mV
Attenuation	10dB = 0.684		0.274V
Total Noise			0.338V
Differential Eye Height Margin			**62mV**

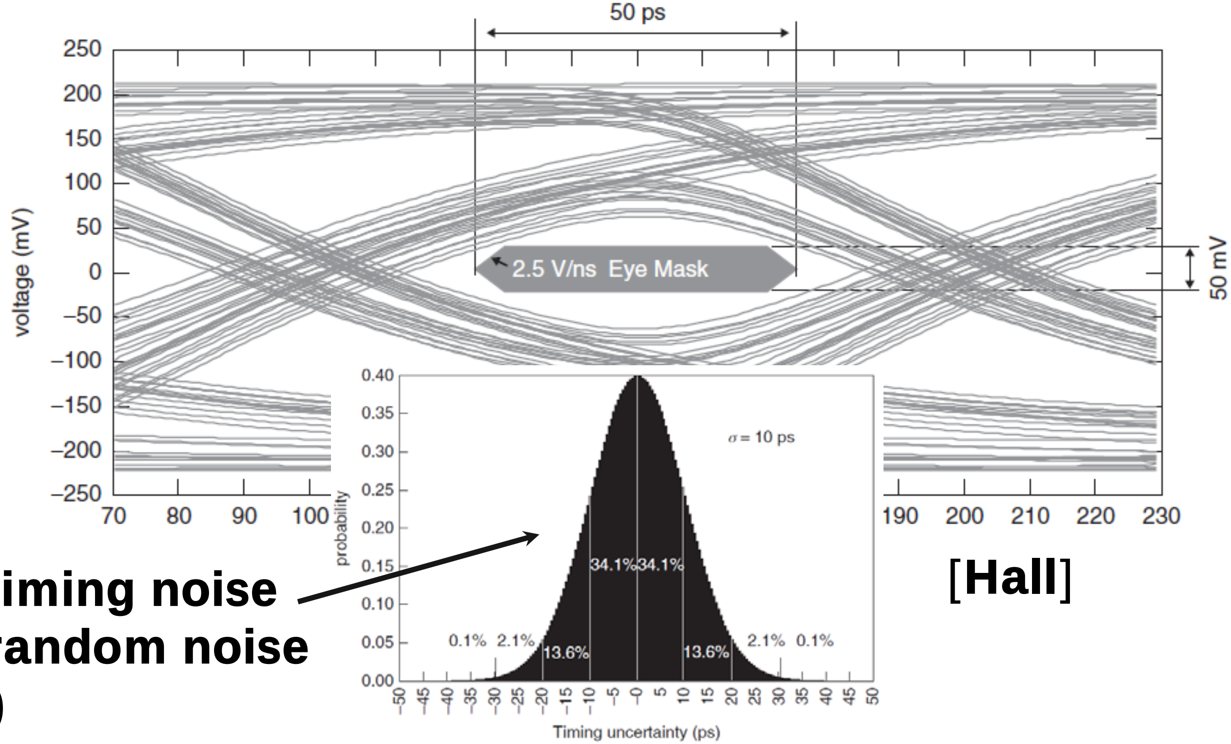


- Conservative analysis
  - Assumes all distributions combine at worst-case
- Better technique is to use statistical BER link simulators

Eye Diagram and Spec Mask

- Links must have margin in both the voltage AND timing domain for proper operation
- For independent design (interoperability) of TX and RX, a spec eye mask is used

Eye at RX sampler



RX clock timing noise or jitter (random noise only here)

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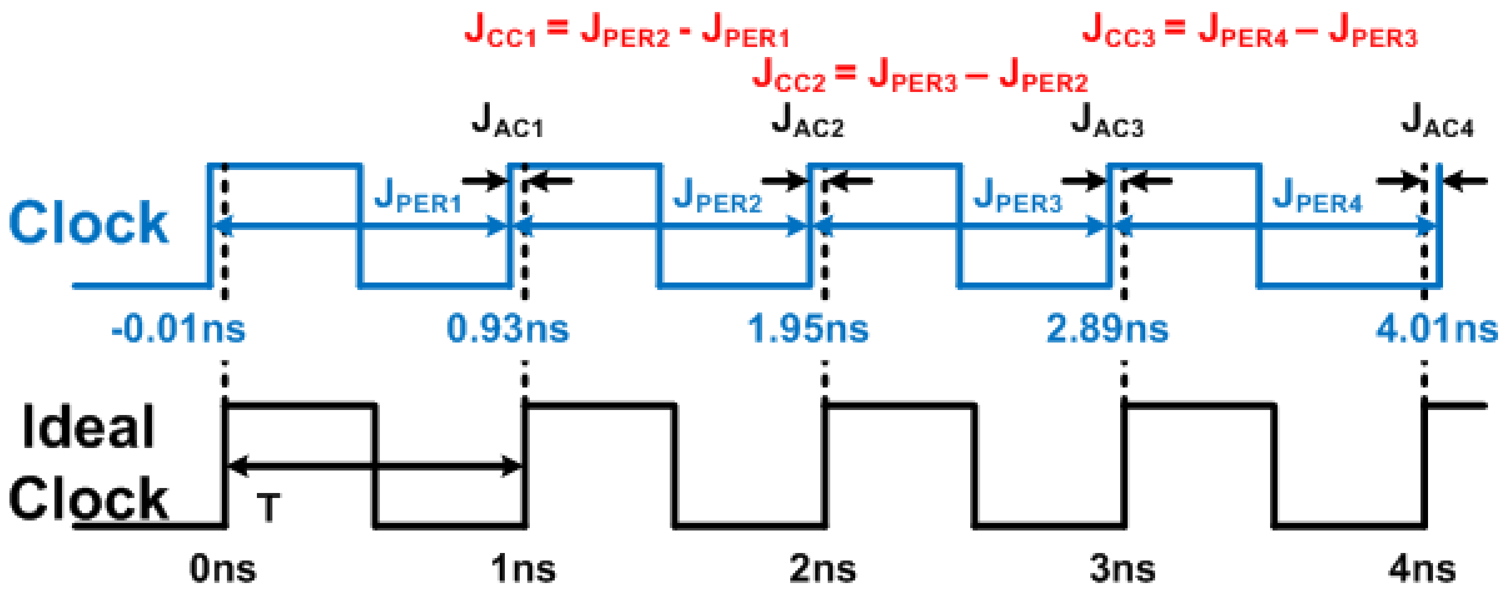
Jitter Definitions

- Jitter can be defined as “the short-term variation of a signal with respect to its ideal position in time”
- Jitter measurements
  - Period Jitter (J_{PER})
    - Time difference between measured period and ideal period
  - Cycle to Cycle Jitter (J_{CC})
    - Time difference between two adjacent clock periods
    - Important for budgeting on-chip digital circuits cycle time
  - Accumulated Jitter (J_{AC})
    - Time difference between measured clock and ideal trigger clock
    - Jitter measurement most relative to high-speed link systems

Jitter Statistical Parameters

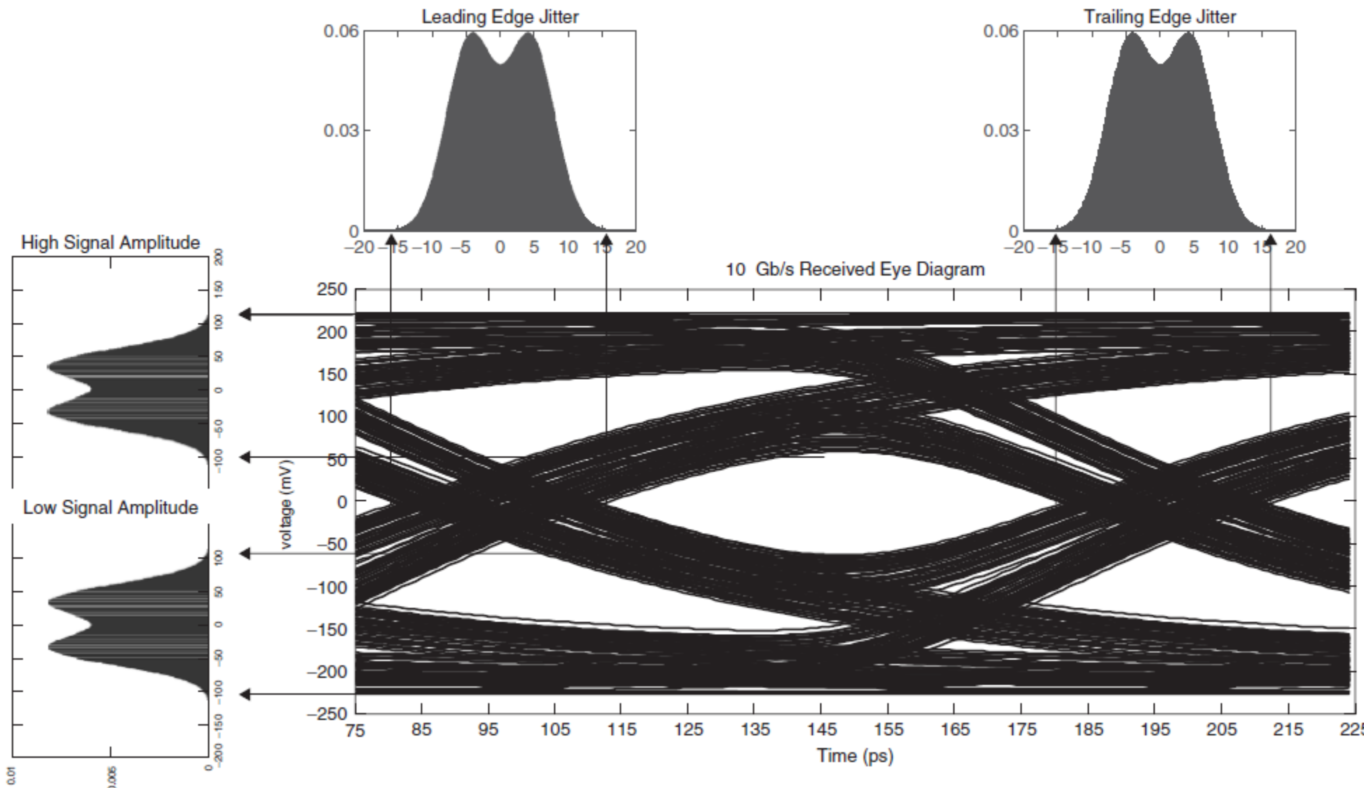
- Mean Value
  - Can be interpreted as a fixed timing offset or “skew”
  - Generally not important, as usually can corrected for
- RMS Jitter
  - Useful for characterizing random component of jitter
- Peak-to-Peak Jitter
  - Function of both deterministic (bounded) and random (unbounded) jitter components
  - Must be quoted at a giver BER to account for random (unbounded) jitter

Jitter Calculation Examples



n	1	2	3	4	Mean	RMS	PP
J_{PER}	-0.06	0.02	-0.06	0.12	0.005	0.085	0.18
J_{CC}	0.08	-0.08	0.18	-	0.06	0.131	0.26
J_{AC}	-0.07	-0.05	-0.11	0.01	-0.055	0.05	0.12

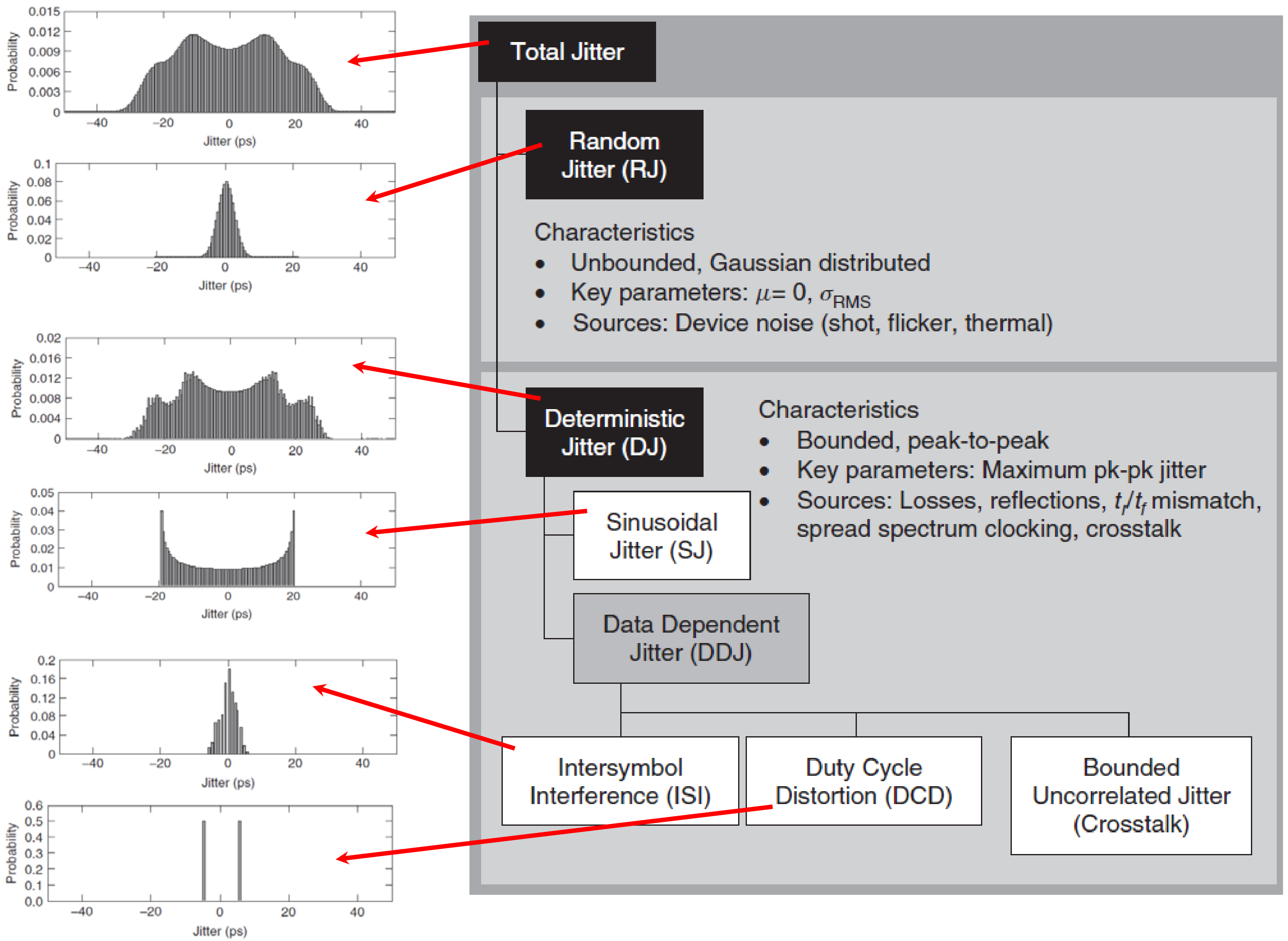
Jitter Histogram



[**Hall**]

- Used to extract the jitter PDF
- Consists of both deterministic and random components
  - Need to decompose these components to accurately estimate jitter at a given BER

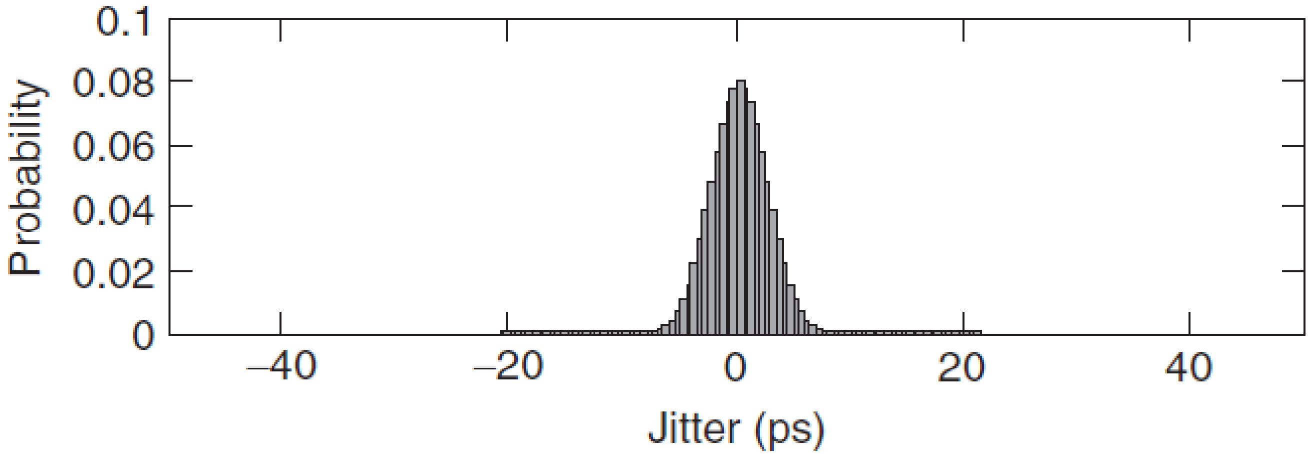
Jitter Categories



Random Jitter (RJ)

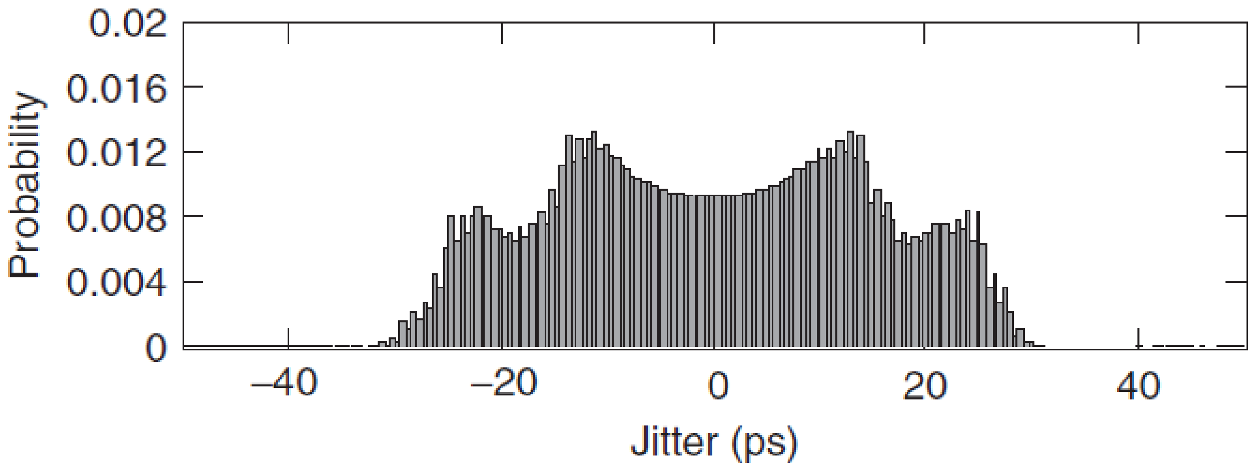
- Unbounded and modeled with a gaussian distribution
  - Assumed to have zero mean value
  - Characterized by the rms value, σ_{RJ}
  - Peak-to-peak value must be quoted at a given BER
- Originates from device noise
  - Thermal, shot, flicker noise

$$RJ(t) = \frac{1}{\sqrt{2\pi}\sigma_{RJ}} e^{\frac{-t^2}{2\sigma_{RJ}^2}}$$



Deterministic Jitter (DJ)

- Bounded with a peak-to-peak value that can be predicted
- Caused by transmission-line losses, duty-cycle distortion, spread-spectrum clocking, crosstalk
- Categories
  - Sinusoidal Jitter (SJ or PJ)
  - Data Dependent Jitter (DDJ)
    - Intersymbol Interference (ISI)
    - Duty Cycle Distortion (DCD)
    - Bounded Uncoirrelated Jitter (BUJ)



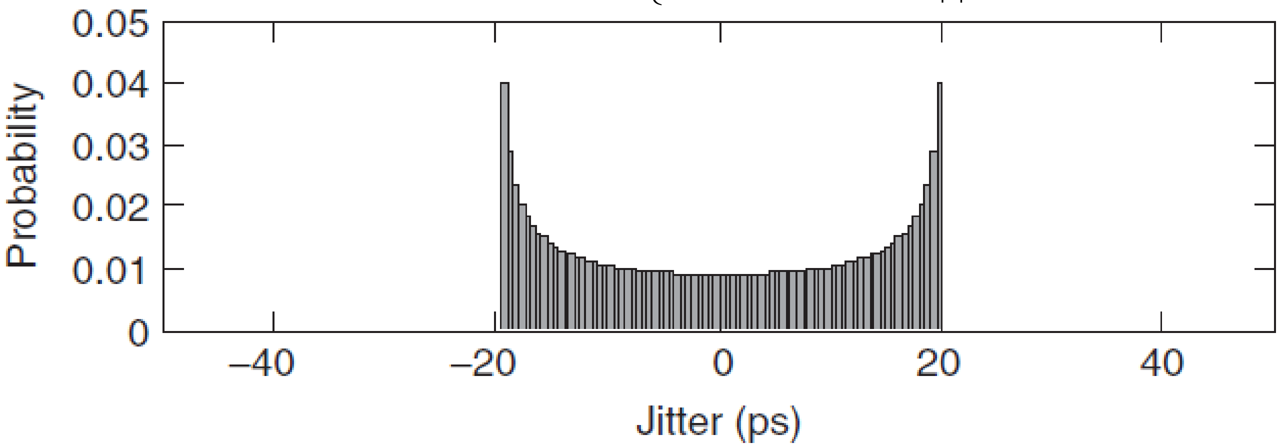
Sinusoidal or Periodic Jitter (SJ or PJ)

- Repeats at a fixed frequency due to modulating effects
  - Spread spectrum clocking
  - PLL reference clock feedthrough
- Can be decomposed into a Fourier series of sinusoids

$$SJ(t) = \sum_i A_i \cos(\omega_i t + \theta_i)$$

- The jitter produced by an individual sinusoid is

$$PDF_{SJ}(t) = \begin{cases} \dfrac{1}{\pi\sqrt{A^2 - t^2}} & A > |t| \\ 0 & A \le |t| \end{cases}$$



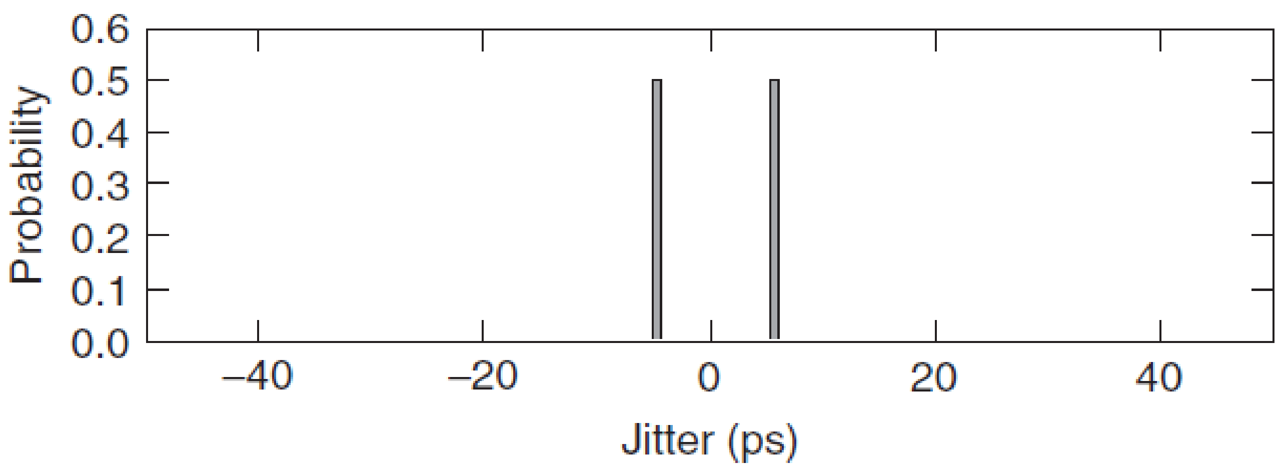
Data Dependent Jitter (DDJ)

- Data dependent jitter is correlated with either the transmitted data pattern or aggressor (crosstalk) data patterns
- Caused by phenomena such as phase errors in serialization clocks, channel filtering, and crosstalk
- Categories
  - Duty Cycle Distortion (DCD)
  - Intersymbol Interference (ISI)
  - Bounded Uncorrelated Jitter (BUJ)

Duty Cycle Distortion (DCD)

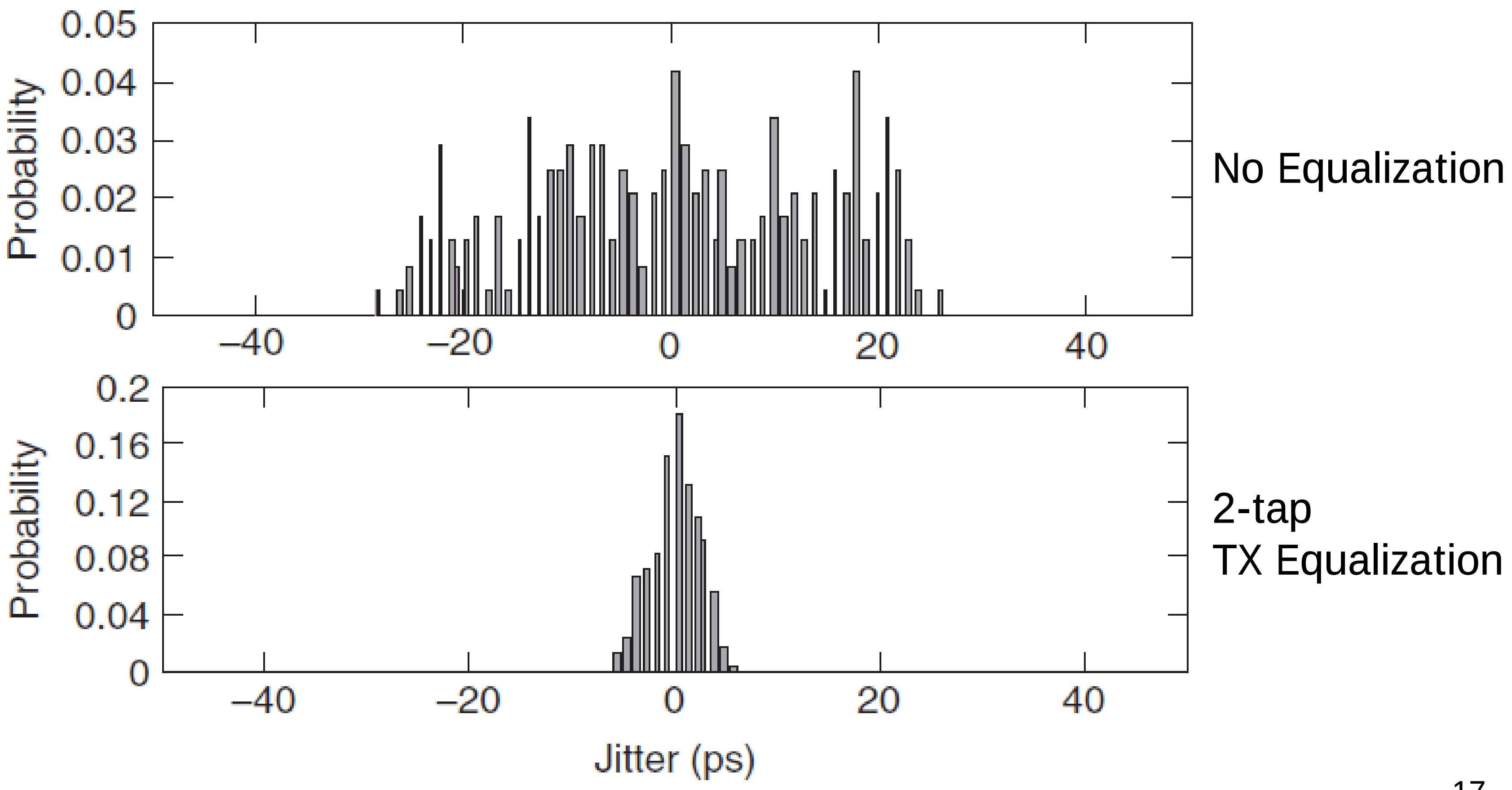
- Caused by duty cycle errors in TX serialization clocks and rise/fall delay mismatches in post-serialization buffers
- Resultant PDF from a peak-to-peak duty cycle distortion (α_{DCD}) is the sum of two delta functions

$$PDF_{DCD}(t) = \frac{1}{2}\left[\delta\left(t - \frac{\alpha_{DCD}}{2}\right) + \delta\left(t + \frac{\alpha_{DCD}}{2}\right)\right]$$



Intersymbol Interference (ISI)

- Caused by channel loss, dispersion, and reflections
- Equalization can improve ISI jitter



Bounded Uncorrelated Jitter (BUJ)

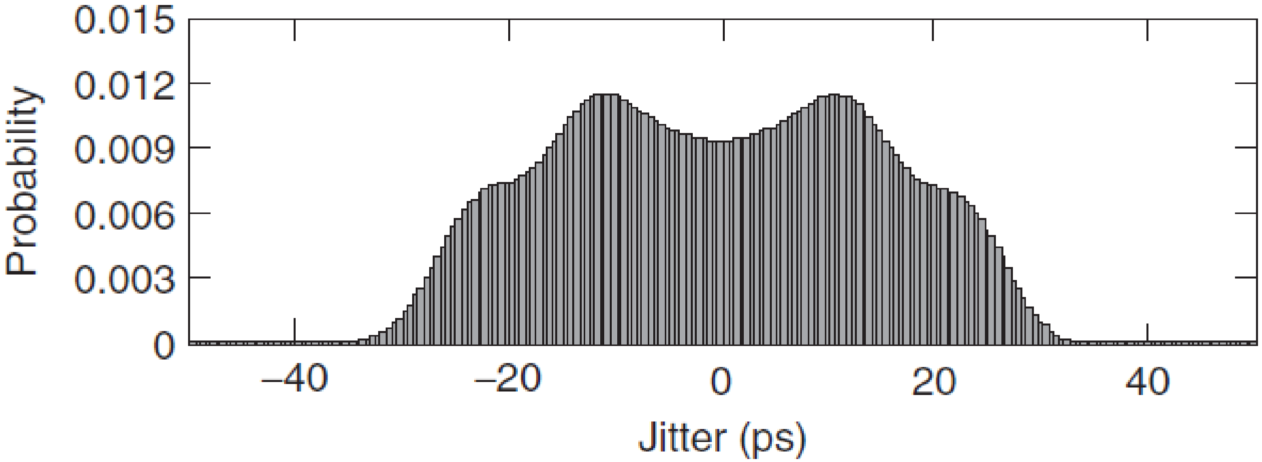
- Not aligned in time with the data stream
- Most common source is crosstalk
- Classified as uncorrelated due to being correlated to the aggressor signals and not the victim signal or data stream
- While uncorrelated, still a bounded source with a quantifiable peak-to-peak value

Total Jitter (TJ)

- The total jitter PDF is produced by convolving the random and deterministic jitter PDFs

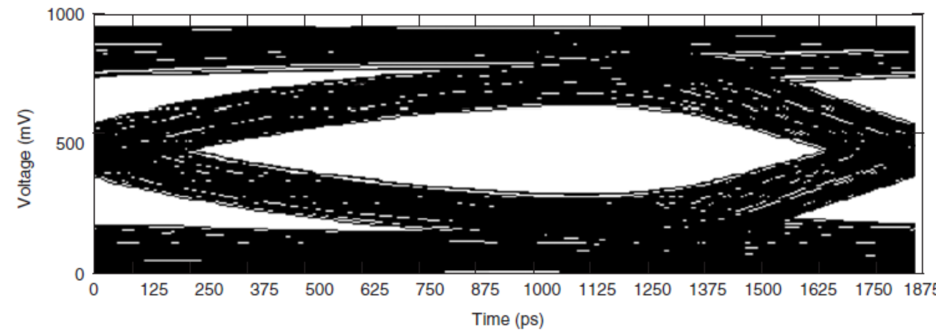
$$PDF_{JT}(t) = PDF_{RJ}(t) * PDF_{DJ}(t)$$

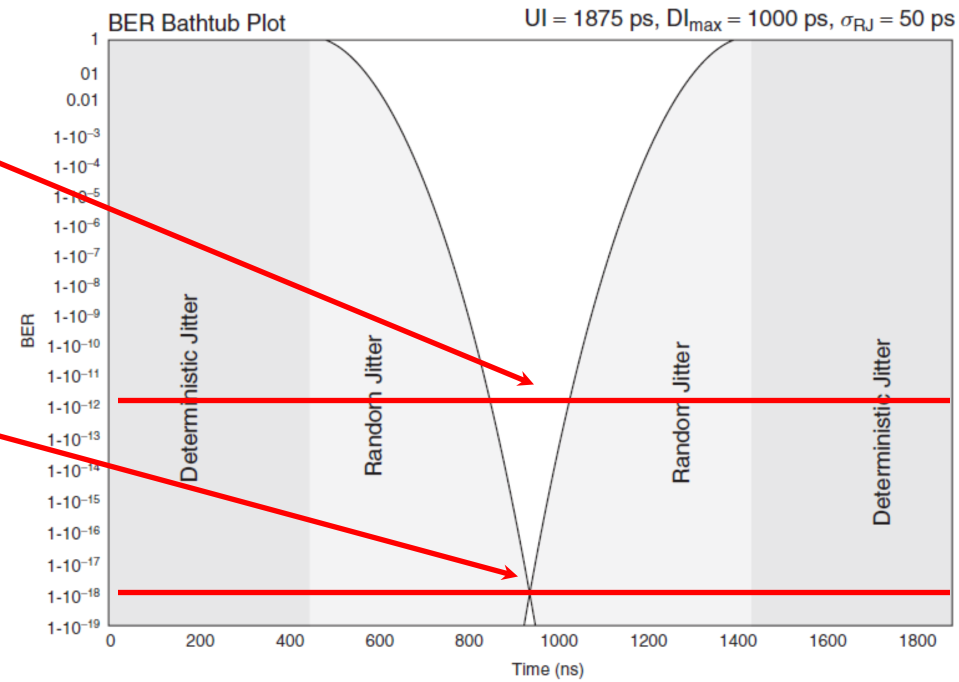
where $PDF_{DJ}(t) = PDF_{SJ}(t) * PDF_{DCD}(t) * PDF_{ISI}(t) * PDF_{BUJ}(t)$



Jitter and Bit Error Rate

- Jitter consists of both deterministic and **random** components
- Total jitter must be quoted at a given BER
  - At BER=10^{-12}, jitter ~1675ps and eye width margin ~200ps
  - System can potentially achieve BER=10^{-18} before being jitter limited





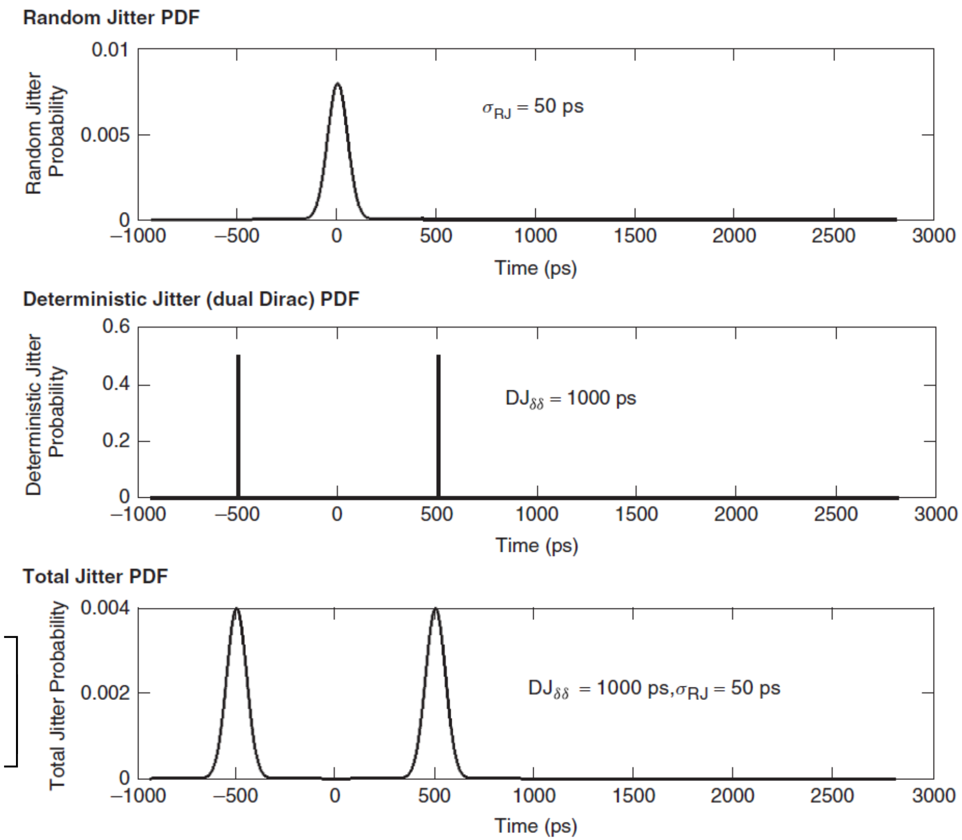
Dual Dirac Jitter Model

- For system-level jitter budgets, the dual Dirac model allows for the budgeting of deterministic and random jitter components

$$RJ(t) = \frac{1}{\sqrt{2\pi}\sigma_{RJ}} e^{\frac{-t^2}{2\sigma_{RJ}^2}}$$

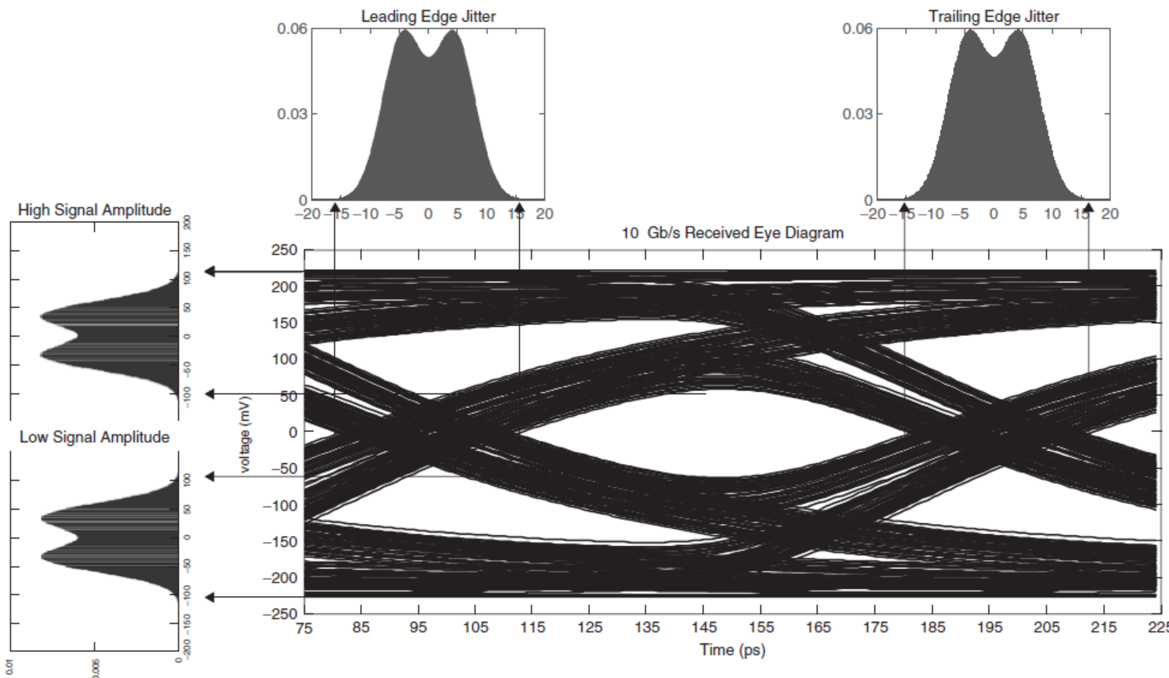
$$DJ(t) = \frac{\delta(t - DJ_{\delta\delta}/2)}{2} + \frac{\delta(t + DJ_{\delta\delta}/2)}{2}$$

$$JT(t) = RJ(t) * DJ(t) = \frac{1}{2\sqrt{2\pi}\sigma_{RJ}}\left[e^{-\frac{t-DJ_{\delta\delta}/2}{2\sigma_{RJ}^2}} + e^{-\frac{t+DJ_{\delta\delta}/2}{2\sigma_{RJ}^2}}\right]$$



Dual Dirac Jitter Model

- Jitter at a given BER is computed considering both leading and trailing edges

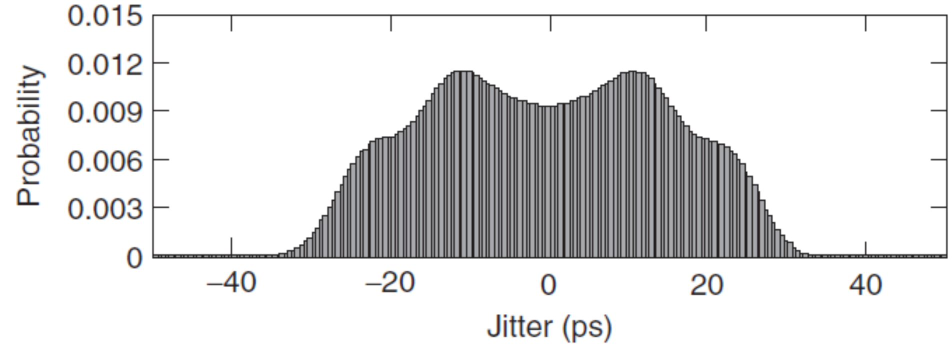


$$BER_{lead}(t) = 0.5\left[erfc\left(\frac{t - DJ_{\delta\delta}/2}{\sqrt{2}\sigma_{RJ}}\right) + erfc\left(\frac{t + DJ_{\delta\delta}/2}{\sqrt{2}\sigma_{RJ}}\right)\right],\ BER_{trail}(t) = 0.5\left[erfc\left(\frac{UI - t - DJ_{\delta\delta}/2}{\sqrt{2}\sigma_{RJ}}\right) + erfc\left(\frac{UI - t + DJ_{\delta\delta}/2}{\sqrt{2}\sigma_{RJ}}\right)\right]$$

$$\textbf{where } erfc(t) = \frac{2}{\sqrt{\pi}}\int_t^{\infty} e^{-x^2}\,dx$$

Dual Dirac Jitter Model Example

- Plot measured jitter PDF vs Q-scale

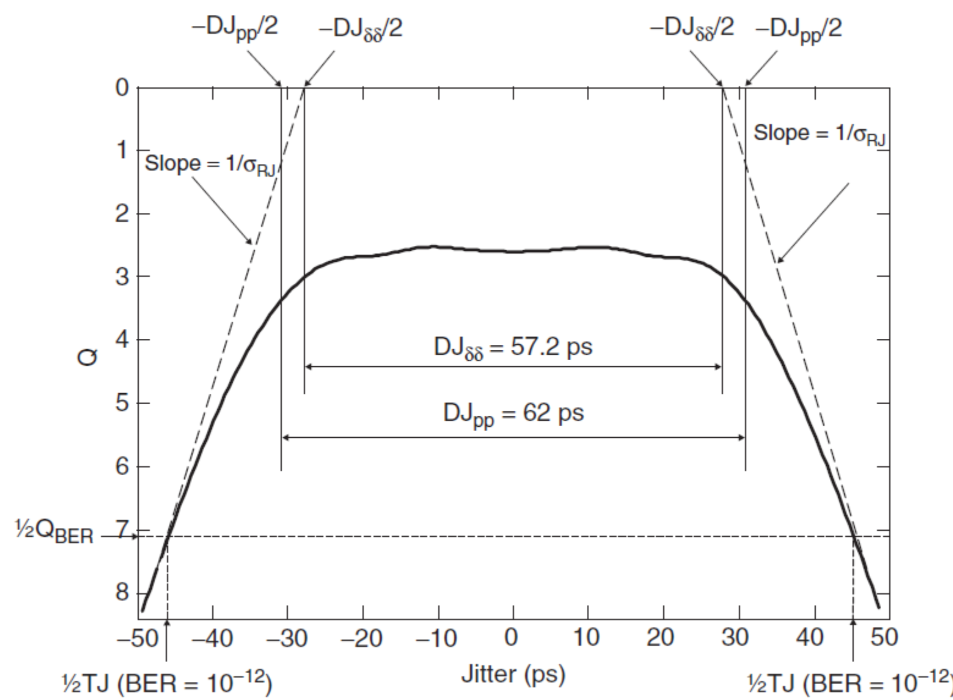


$$Q_{BER}(BER) = \sqrt{2}\,erf^{-1}\left(1 - \frac{BER}{\rho_T}\right)$$

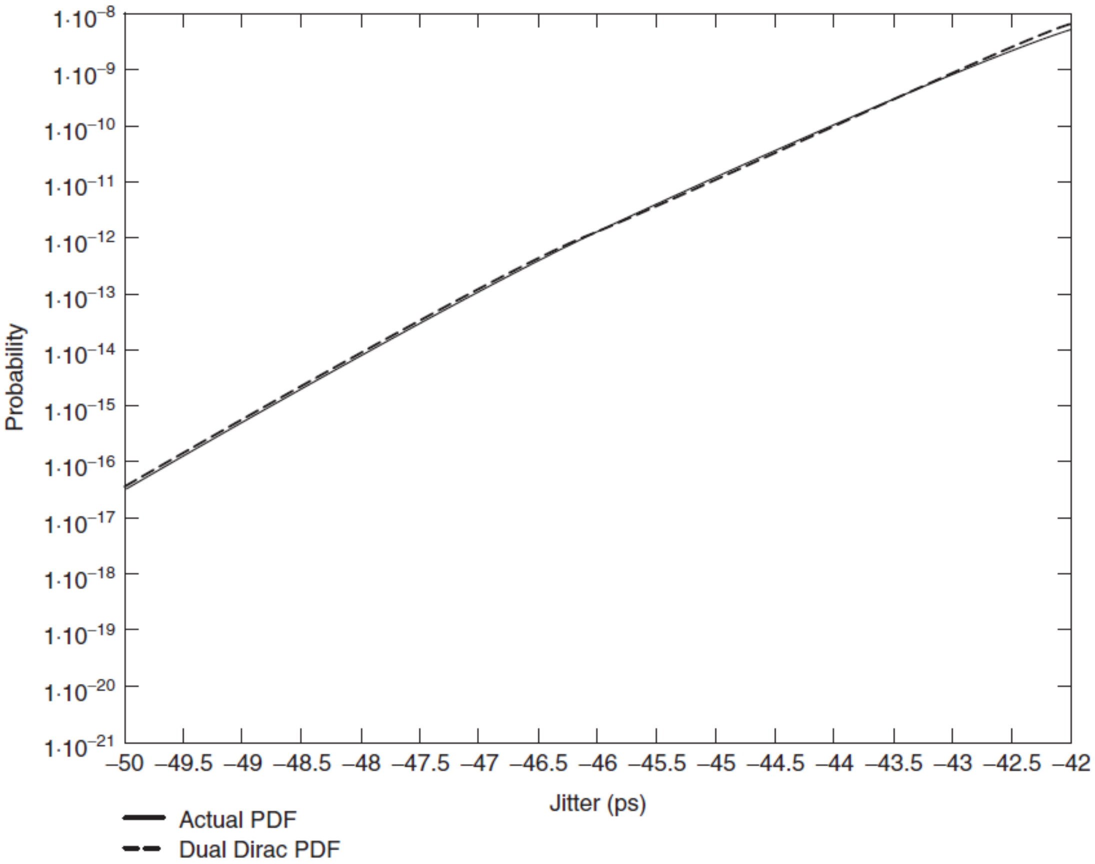
where ρ_T is the transition density, typically 0.5

- Tails are used to extract σ_{RJ}

- Extrapolate to Q(0) to extract DJ bounds



Dual Dirac Jitter Model Example



- Extracted dual Dirac model matches well with measured jitter PDF

Next Time

- Statistical BER Analysis Tool Overview
- Timing Circuits