

ECEN689: Special Topics in High-Speed Links Circuits and Systems Spring 2010

Lecture 15: RX Circuits



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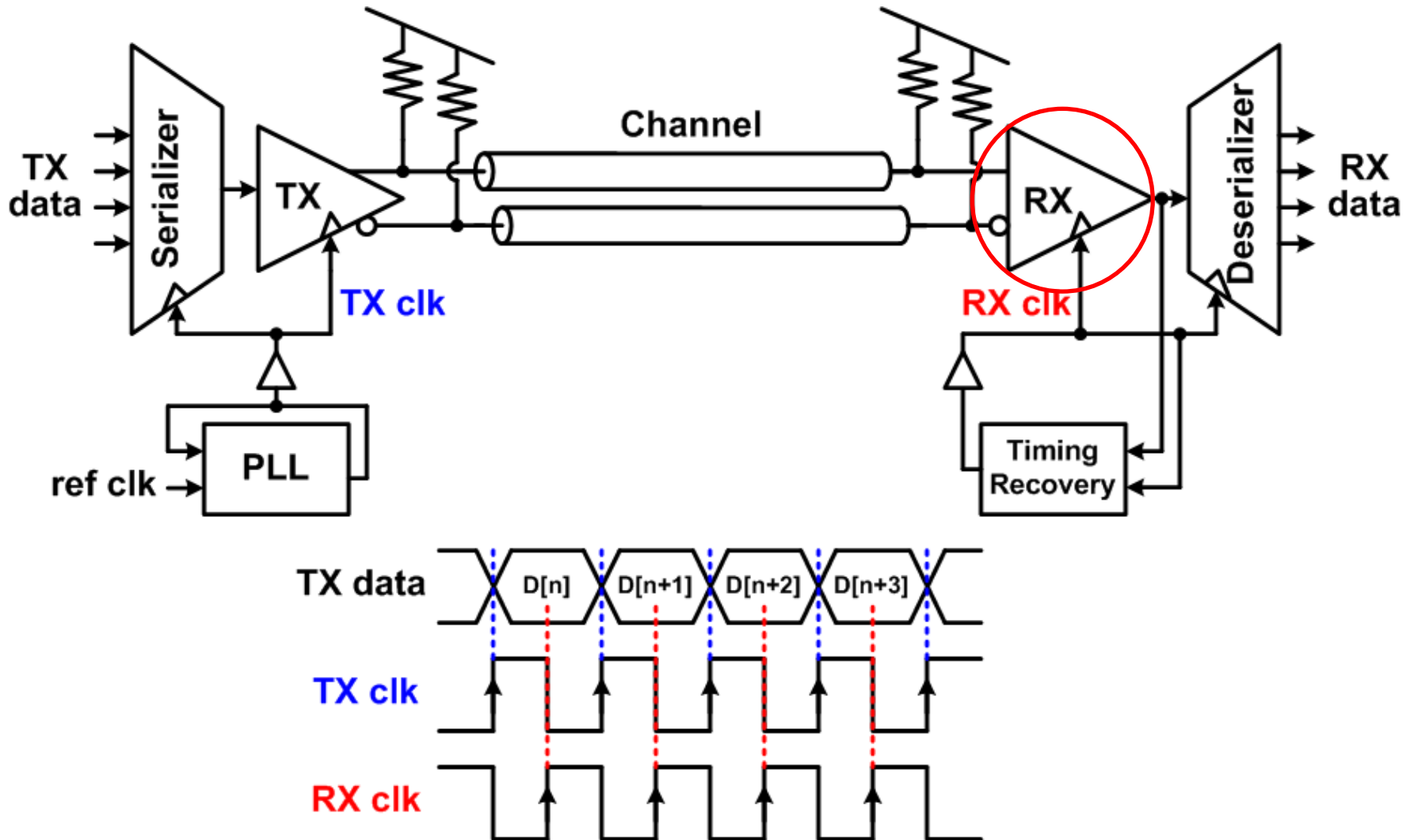
Announcements

- HW4 due Wednesday 5PM
 - Involves transistor-level circuit design
 - Use 90nm or more advanced CMOS technology
 - Instructions on how to access 90nm CMOS models on website for students who don't already have access to a design kit
- Exam 1 is March 12
 - 9:10-10:10AM (10 extra minutes)
 - Closed book w/ one standard note sheet
 - 8.5"x11" front & back
 - Bring your calculator
- Reading
 - Dally 11.1-11.3
 - Papers posted on TX drivers and RX comparator analysis

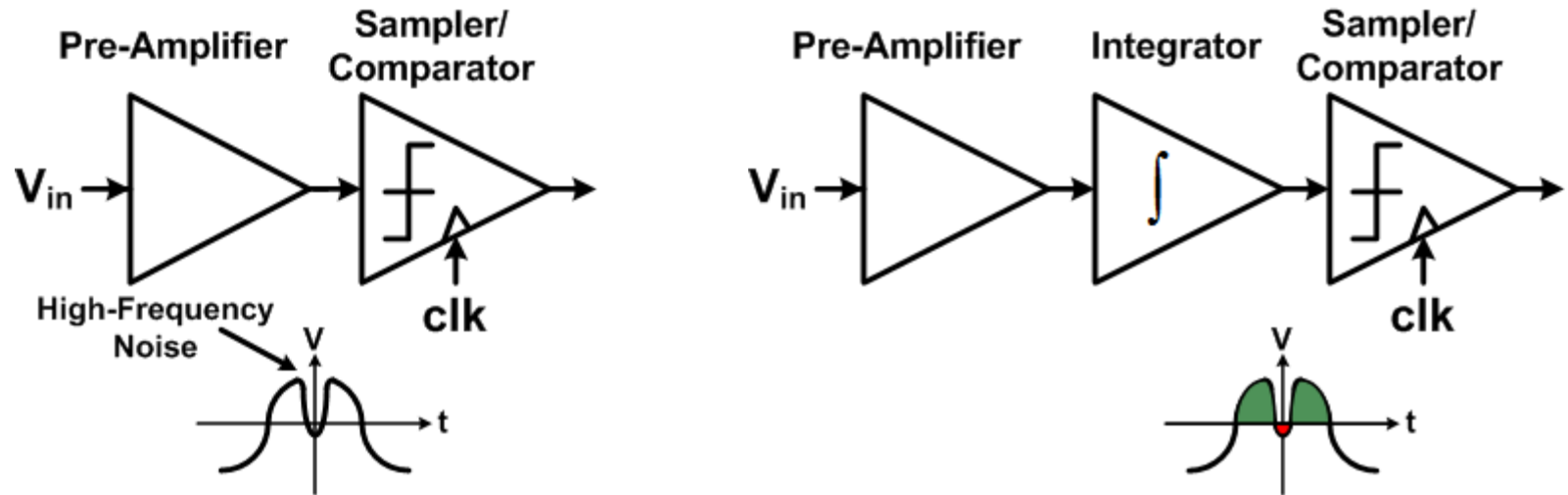
Agenda

- RX Circuits
 - Integrating receivers
 - RX sensitivity
 - Offset correction
 - Demultiplexing receivers

High-Speed Electrical Link System

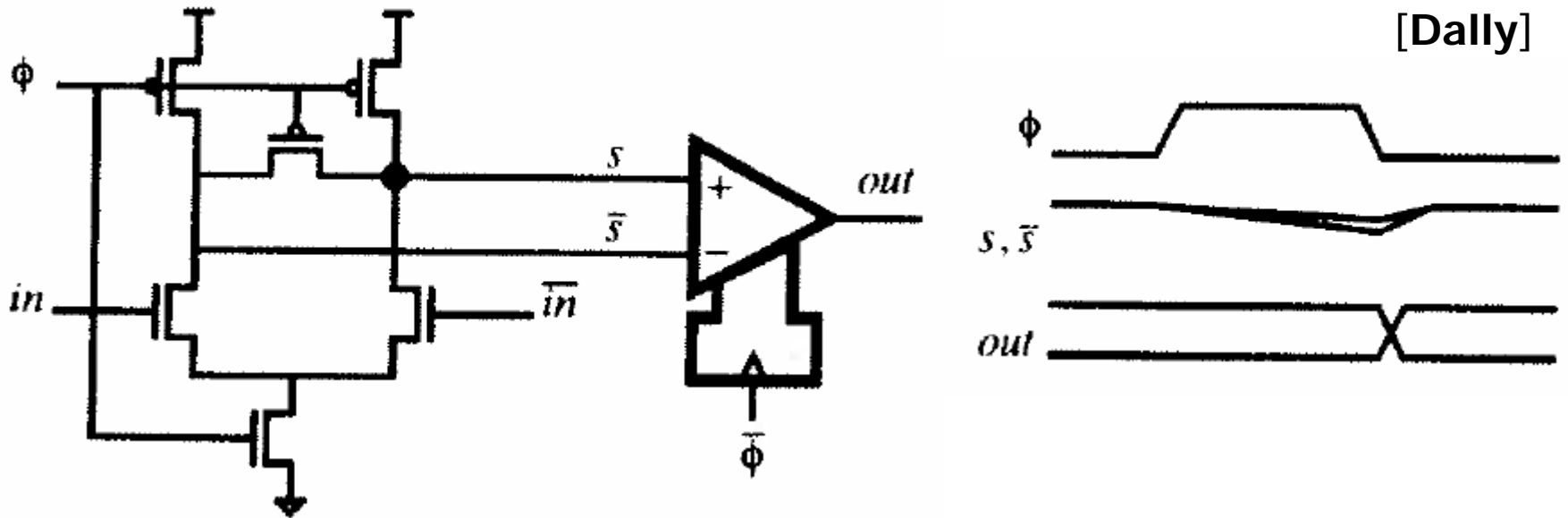


Integrating RX & High-Frequency Noise



- A small aperture time is desired in most receiver samplers
- However, high-frequency noise can degrade performance at sampling time
 - Can be an issue in single-ended systems with excessive LdI/dt switching noise
- Integrating the input signal over a sampling interval reduces the high-frequency noise impact

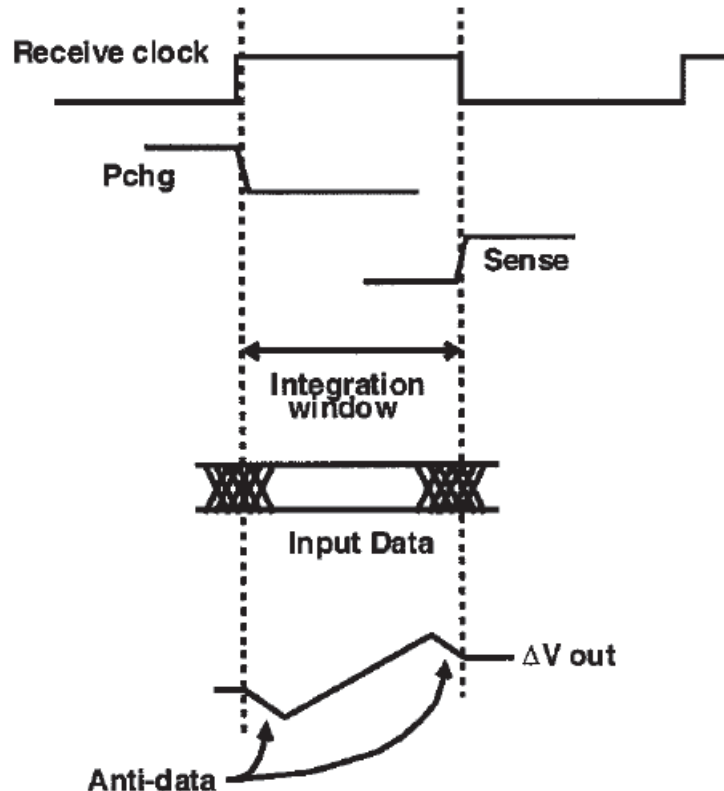
Integrating Amplifier



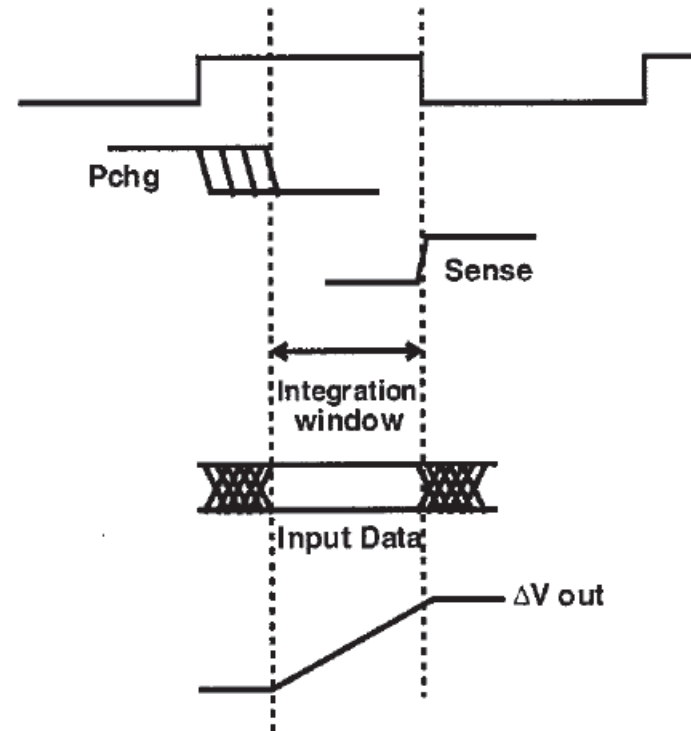
- Differential input voltage converted to a differential current that is integrated on the sense nodes' capacitance

Windowed Integration

No time windowing –
Integrating over complete bit



Windowed Integration



[Zerbe JSSC 2001]

- Windowing integration time can minimize transition noise and maximize integration of valid data

RX Sensitivity

- RX sensitivity is a function of the input referred noise, offset, and minimum latch resolution voltage

$$v_S^{pp} = 2v_n^{rms} \sqrt{SNR} + v_{min} + v_{offset*}$$

- Gaussian (unbounded) input referred noise comes from input amplifiers, comparators, and termination
 - A minimum signal-to-noise ratio (SNR) is required for a given bit-error-rate (BER)

$$\text{For BER} = 10^{-12} (\sqrt{SNR} = 7)$$

- Minimum latch resolution voltage comes from hysteresis, finite regeneration gain, and bounded noise sources

$$\text{Typical } v_{min} < 5mV$$

- Input offset is due to circuit mismatch (primarily V_{th} mismatch) & is most significant component if uncorrected

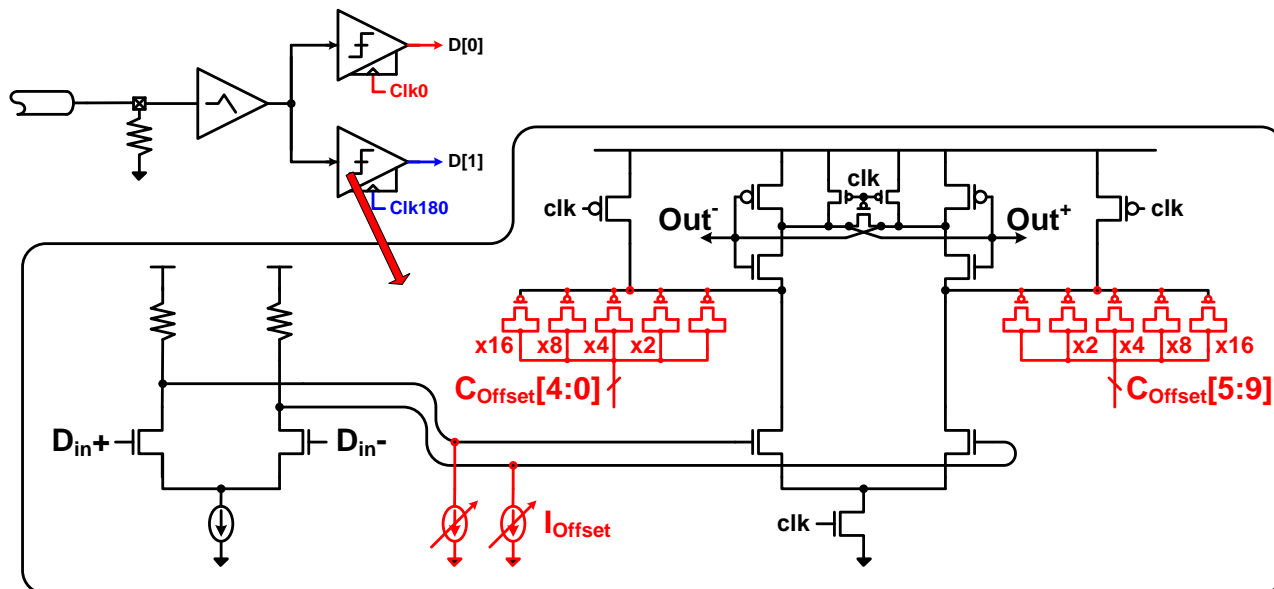
RX Sensitivity & Offset Correction

- RX sensitivity is a function of the input referred noise, offset, and min latch resolution voltage

$$v_S^{pp} = 2v_n^{rms} \sqrt{SNR} + v_{\min} + v_{offset*} \quad \text{Typical Values : } v_n^{rms} = 1mV_{rms}, v_{\min} + v_{offset*} < 6mV$$

$$\text{For BER} = 10^{-12} (\sqrt{SNR} = 7) \Rightarrow v_S^{pp} = 20mV_{pp}$$

- Circuitry is required to reduce input offset from a potentially large uncorrected value (>50mV) to near 1mV



Input Referred Offset

- The input referred offset is primarily a function of V_{th} mismatch and a weaker function of β (mobility) mismatch

$$\sigma_{V_t} = \frac{A_{V_t}}{\sqrt{WL}}, \quad \sigma_{\Delta\beta/\beta} = \frac{A_{\beta}}{\sqrt{WL}}$$

- To reduce input offset 2x, we need to increase area 4x
 - Not practical due to excessive area and power consumption
 - Offset correction necessary to efficiently achieve good sensitivity
- Ideally the offset "A" coefficients are given by the design kit and Monte Carlo is performed to extract offset sigma
- If not, here are some common values:
 - $A_{V_t} = 1\text{mV}\mu\text{m}$ per nm of t_{ox}
 - For our default 90nm technology, $t_{ox}=2.8\text{nm} \rightarrow A_{V_t} \sim 2.8\text{mV}\mu\text{m}$
 - A_{β} is generally near $2\%\mu\text{m}$

Offset Correction Range & Resolution

- Generally circuits are designed to handle a minimum variation range of $\pm 3\sigma$ for 99.7% yield
- Example: Input differential transistors $W=4\mu\text{m}$, $L=150\text{nm}$

$$\sigma_{V_t} = \frac{A_{V_t}}{\sqrt{WL}} = \frac{2.8\text{mV}\mu\text{m}}{\sqrt{4\mu\text{m} \cdot 150\text{nm}}} = 3.6\text{mV}, \quad \sigma_{\Delta\beta/\beta} = \frac{A_{\beta}}{\sqrt{WL}} = \frac{2\% \mu\text{m}}{\sqrt{4\mu\text{m} \cdot 150\text{nm}}} = 2.6\%$$

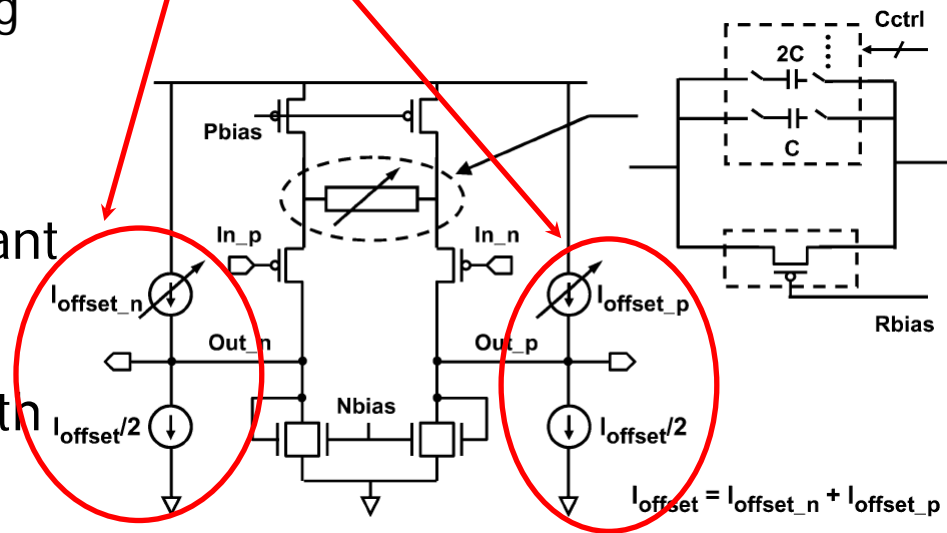
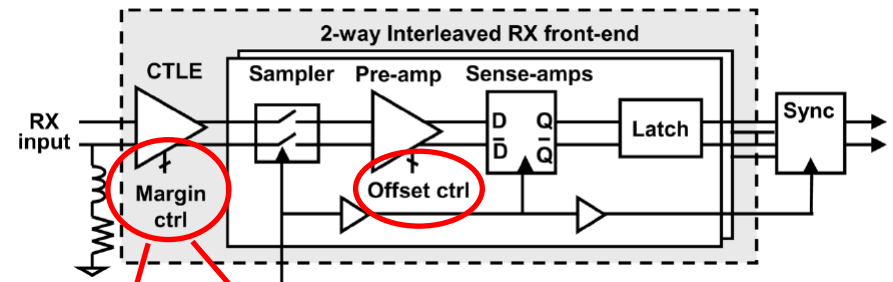
- If we assume (optimistically) that the input offset is only dominated by the input pair V_t mismatch, we would need to design offset correction circuitry with a range of about $\pm 11\text{mV}$
- If we want to cancel within 1mV , we would need an offset cancellation resolution of 5bits, resulting in a worst-case offset of

$$1\text{LSB} = \frac{\text{Offset Correction Range}}{2^{\text{Resolution}} - 1} = \frac{22\text{mV}}{2^5 - 1} = 0.65\text{mV}$$

Current-Mode Offset Correction Example

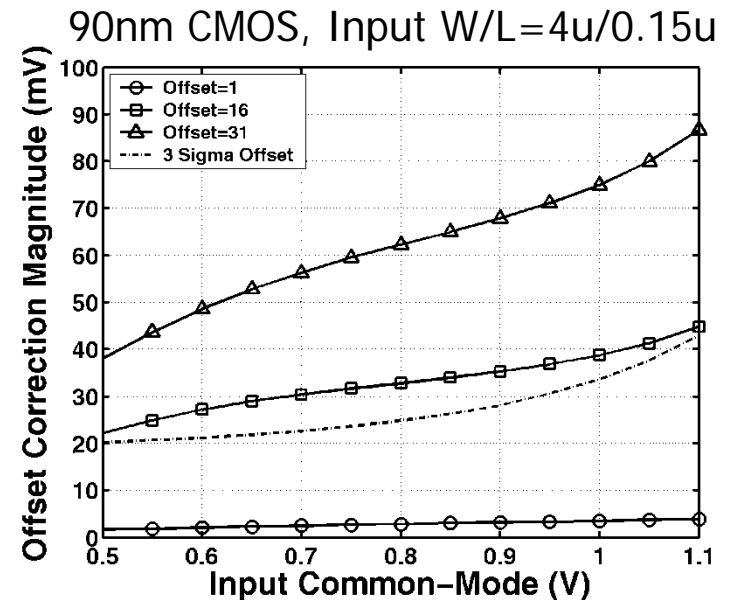
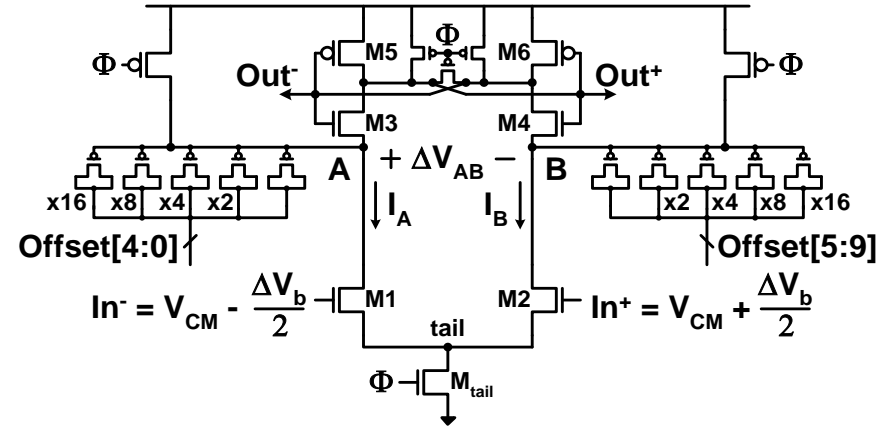
- Differential current injected into input amplifier load to induce an input-referred offset that can cancel the inherent amplifier offset
 - Can be made with extended range to perform link margining
- Passing a constant amount of total offset current for all the offset settings allows for constant output common-mode level
- Offset correction performed both at input amplifier and in individual receiver segments of the 2-way interleaved architecture

[Balamurugan JSSC 2008]



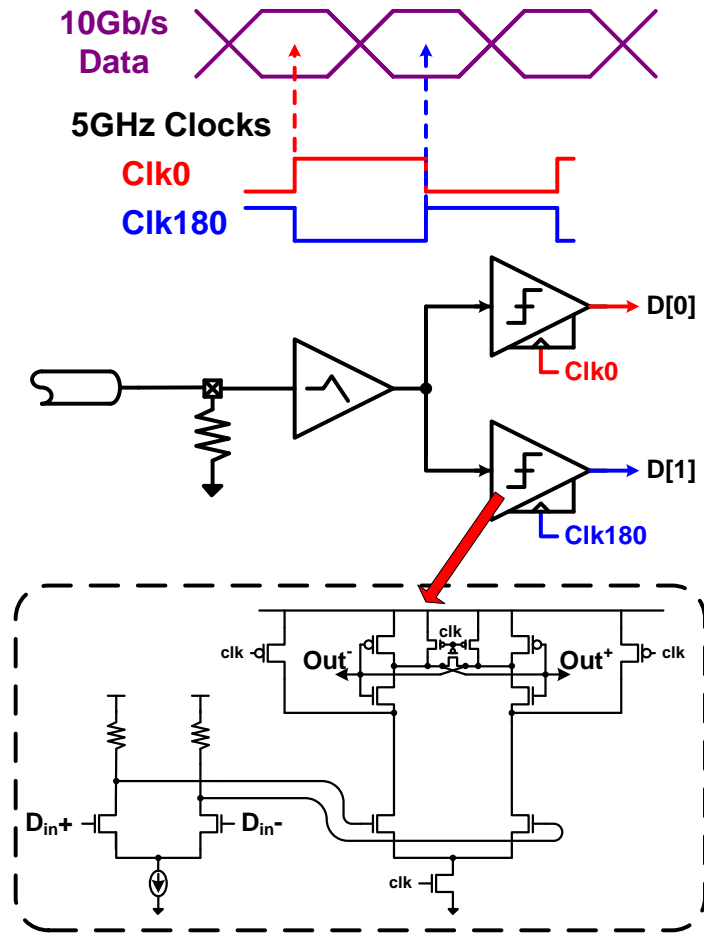
Capacitive Offset Correction Example

- A capacitive imbalance in the sense-amplifier internal nodes induces an input-referred offset
- Pre-charges internal nodes to allow more integration time for more increased offset range
- Additional capacitance does increase sense-amp aperture time
- Offset is trimmed by shorting inputs to a common-mode voltage and adjusting settings until an even distribution of "1"s and "0"s are observed
- Offset correction settings can be sensitive to input common-mode

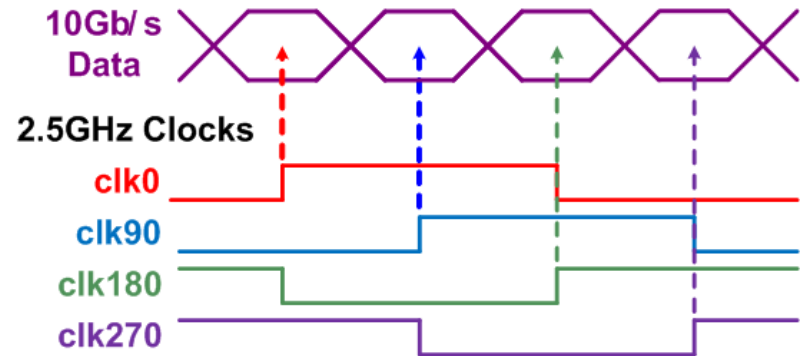
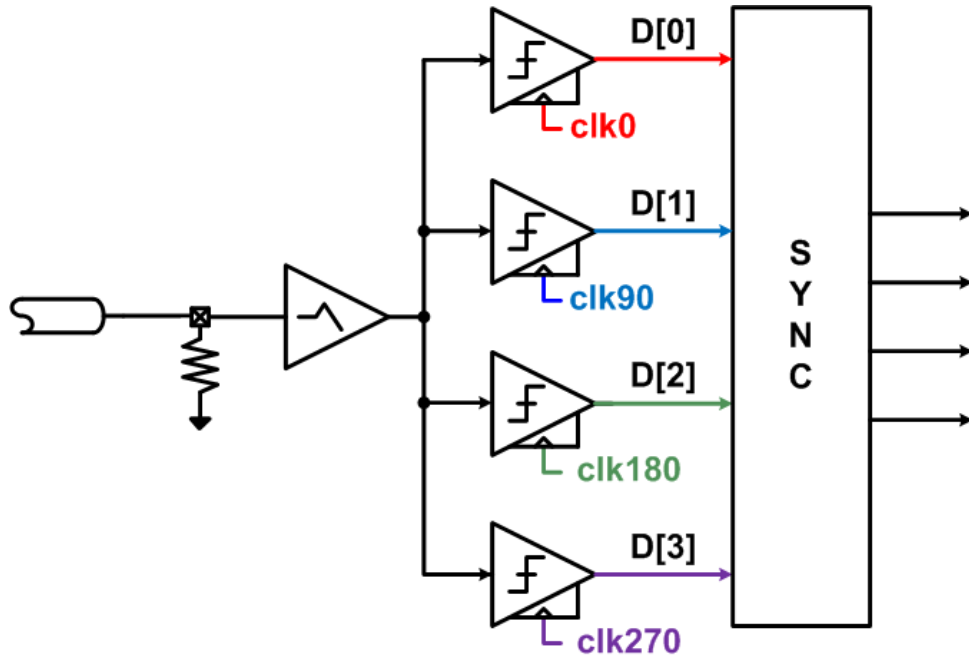


Demultiplexing RX

- Demultiplexing allows for lower clock frequency relative to data rate
- Gives extra regeneration and pre-charge time in comparators
- Need precise phase spacing, but not as sensitive to duty-cycle as TX multiplexing



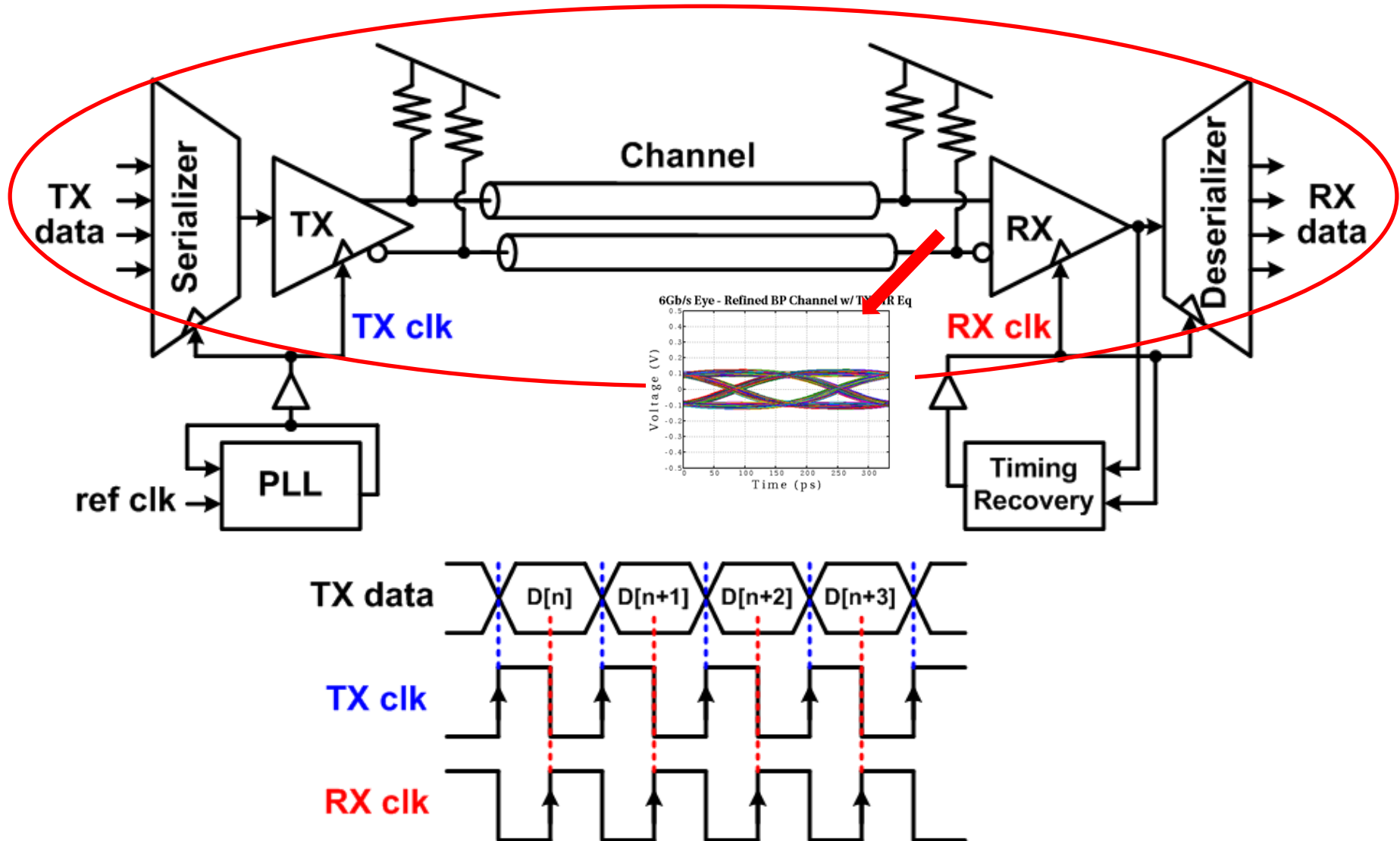
1:4 Demultiplexing RX Example



- Increased demultiplexing allows for higher data rate at the cost of increased input or pre-amp load capacitance
- Higher multiplexing factor more sensitive to phase offsets in degrees

End Exam 1 Material

High-Speed Electrical Link System



Next Time

- Equalization theory and circuits
 - Equalization overview
 - Equalization implementations
 - TX FIR
 - RX FIR
 - RX CTLE
 - RX DFE
 - Setting coefficients
 - Equalization effectiveness
 - Alternate/future approaches