

# ECEN474/704: (Analog) VLSI Circuit Design Spring 2018

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## Lecture 14: Feedback & Stability



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# Announcements

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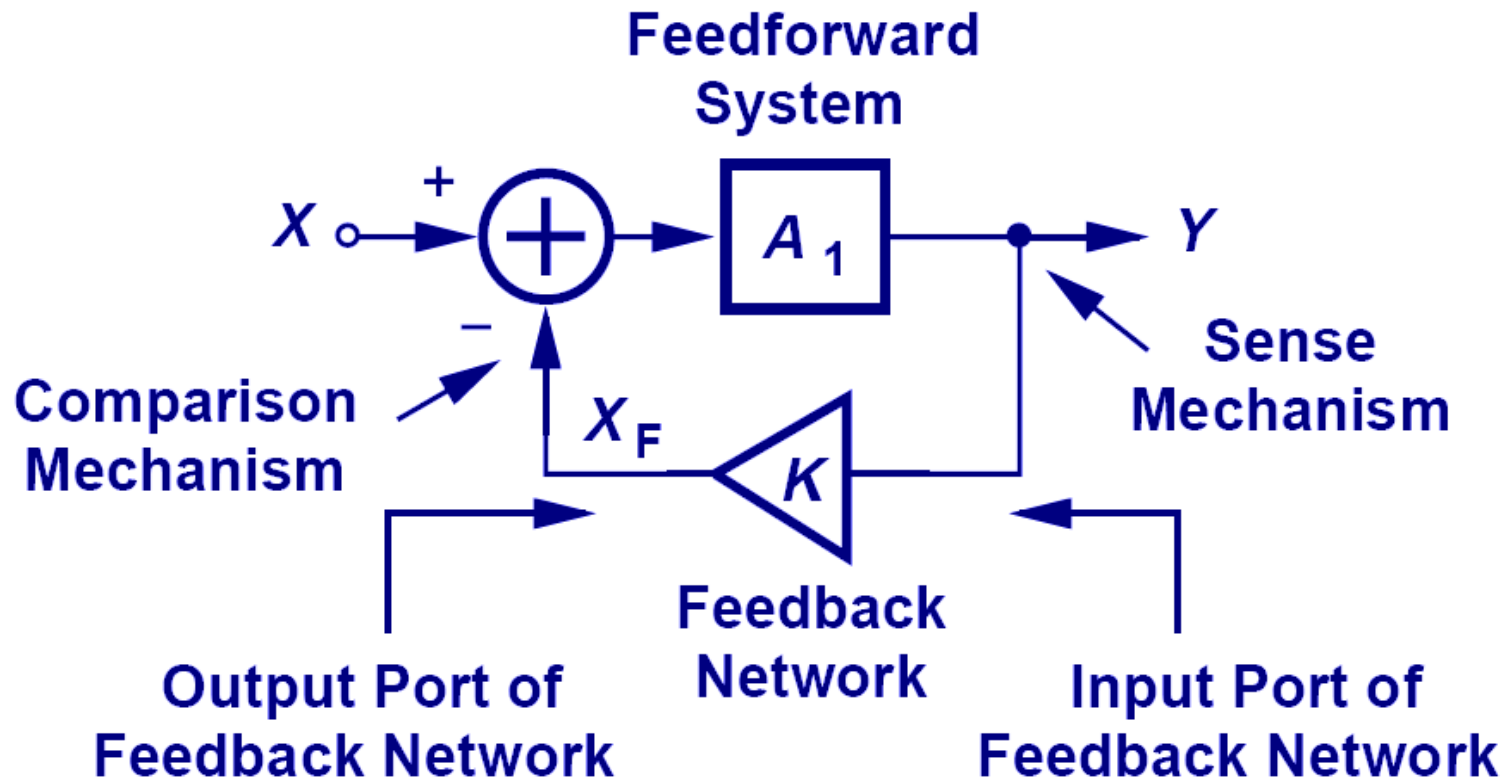
- Exam2 is on Apr. 10
  - 11:10-12:35PM (10 extra minutes)
  - Closed book w/ one standard note sheet
  - 8.5"x11" front & back
  - Bring your calculator
  - Covers material through lecture 11
  - Previous years' Exam 2s are posted on the website for reference
- Project description is posted on website
  - Preliminary Report (HW4) due on Apr. 17

# Announcements & Agenda

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- Feedback in Opamp Circuits
- Stability Considerations
  - Nyquist Criteria
  - Phase & Gain Margin

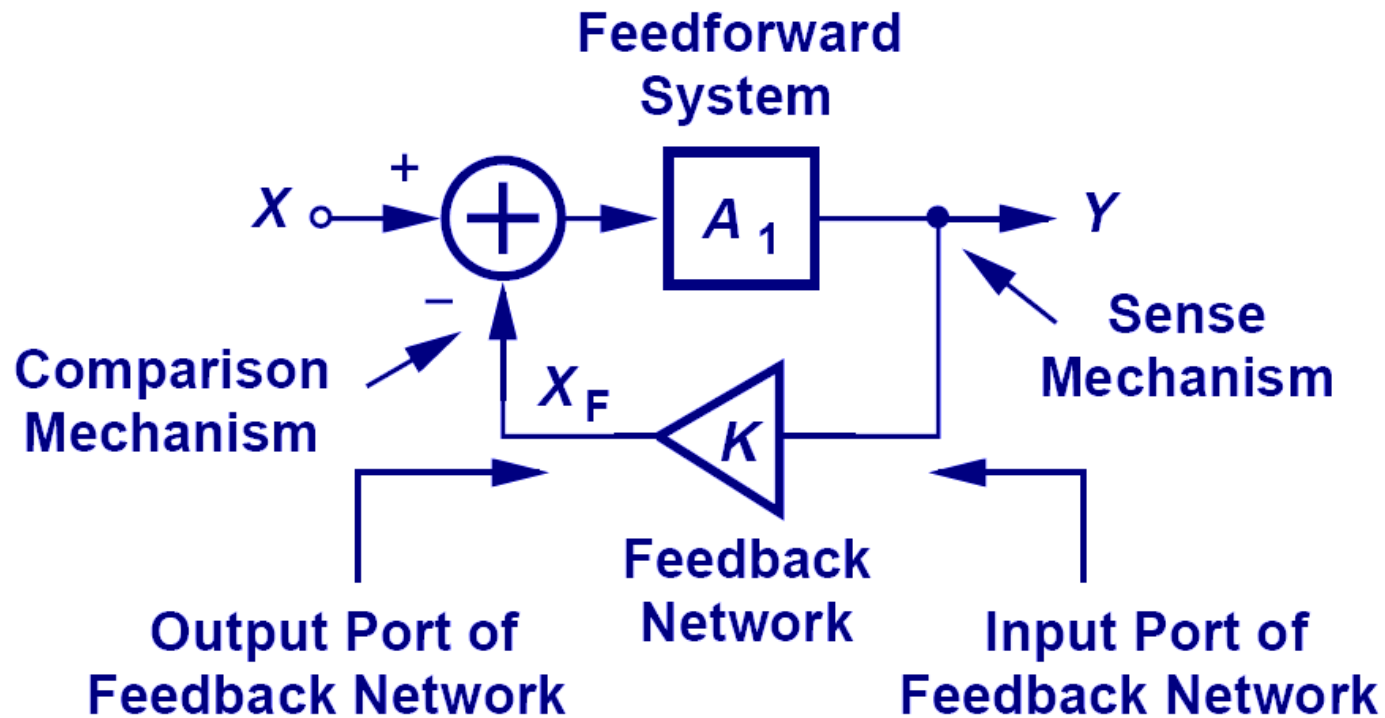
# Negative Feedback System



$$\text{Feedback Factor } K = \frac{X_F}{Y}$$

- A negative feedback system consists of four components: 1) feedforward system, 2) sense mechanism, 3) feedback network, and 4) comparison mechanism.

# Close-loop Transfer Function

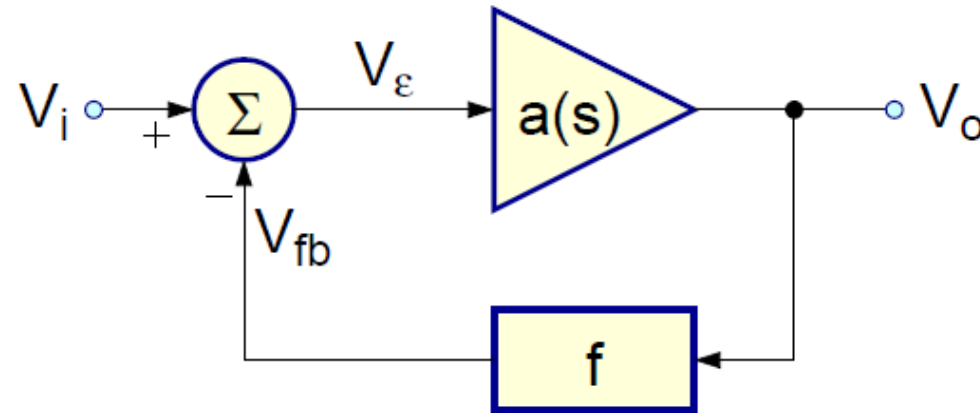


Closed-Loop Gain

$$Y = (X - X_F)A_1 = (X - YK)A_1$$
$$Y(1 + KA_1) = XA_1$$

$$\frac{Y}{X} = \frac{A_1}{1 + KA_1}$$

# Feedback Configuration



[Karsilayan]

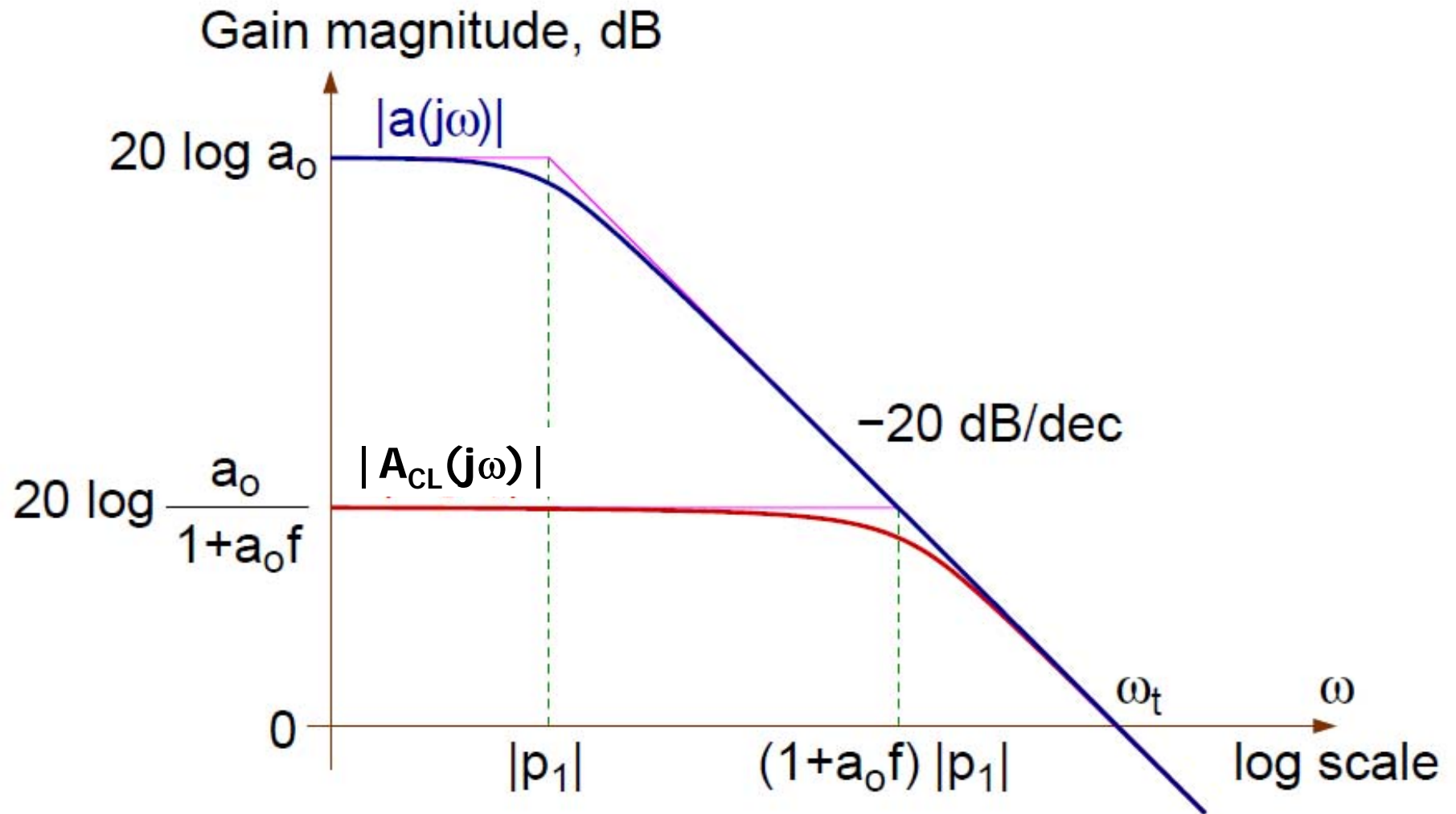
Here  $f$  = feedback factor (K in previous slides)

$$a(s) = \frac{V_o}{V_\epsilon}(s) = \frac{a_o}{1 - \frac{s}{p_1}}$$

$$A_{CL}(s) = \frac{V_o}{V_i}(s) = \frac{a(s)}{1 + a(s)f} = \frac{\frac{a_o}{1 + a_o f}}{1 - \frac{s}{(1 + a_o f)p_1}}$$

# Gain-Bandwidth

[Karsilayan]



# Instability and the Nyquist Criterion

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[Karsilayan]

Transfer function of a 3-pole amplifier:

$$a(s) = \frac{a_o}{\left(1 - \frac{s}{p_1}\right) \left(1 - \frac{s}{p_2}\right) \left(1 - \frac{s}{p_3}\right)}$$

Nyquist criterion for stability of the amplifier:

*Consider a feedback amplifier with a stable  $\mathbf{T}(s)$ . If the Nyquist plot of  $\mathbf{T}(j\omega)$  encircles the point  $(-1,0)$ , the feedback amplifier is unstable.*

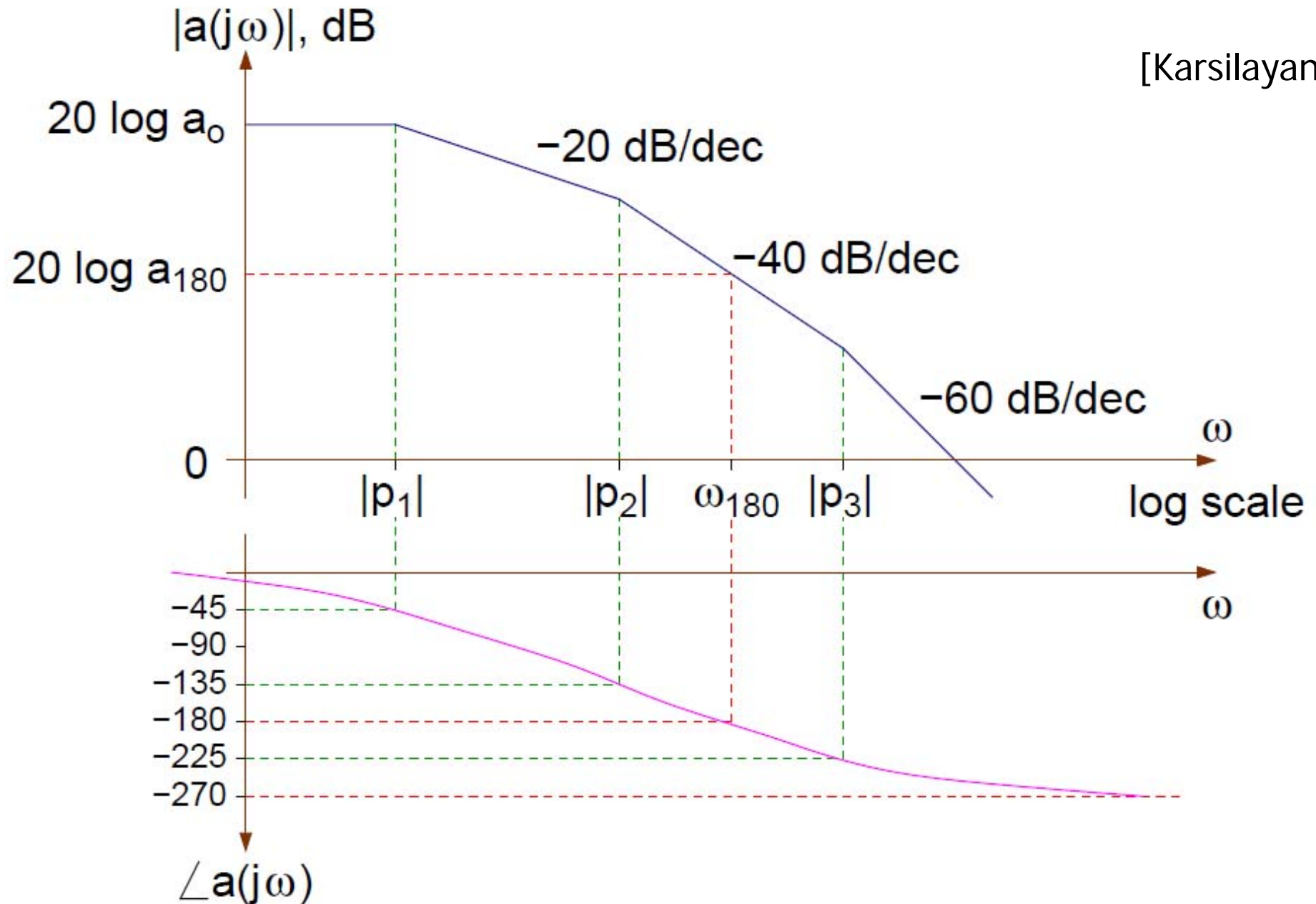
Recall  $T(s)$  is the loop gain

$$T(s) = A(s)K(s) = a(s)f$$



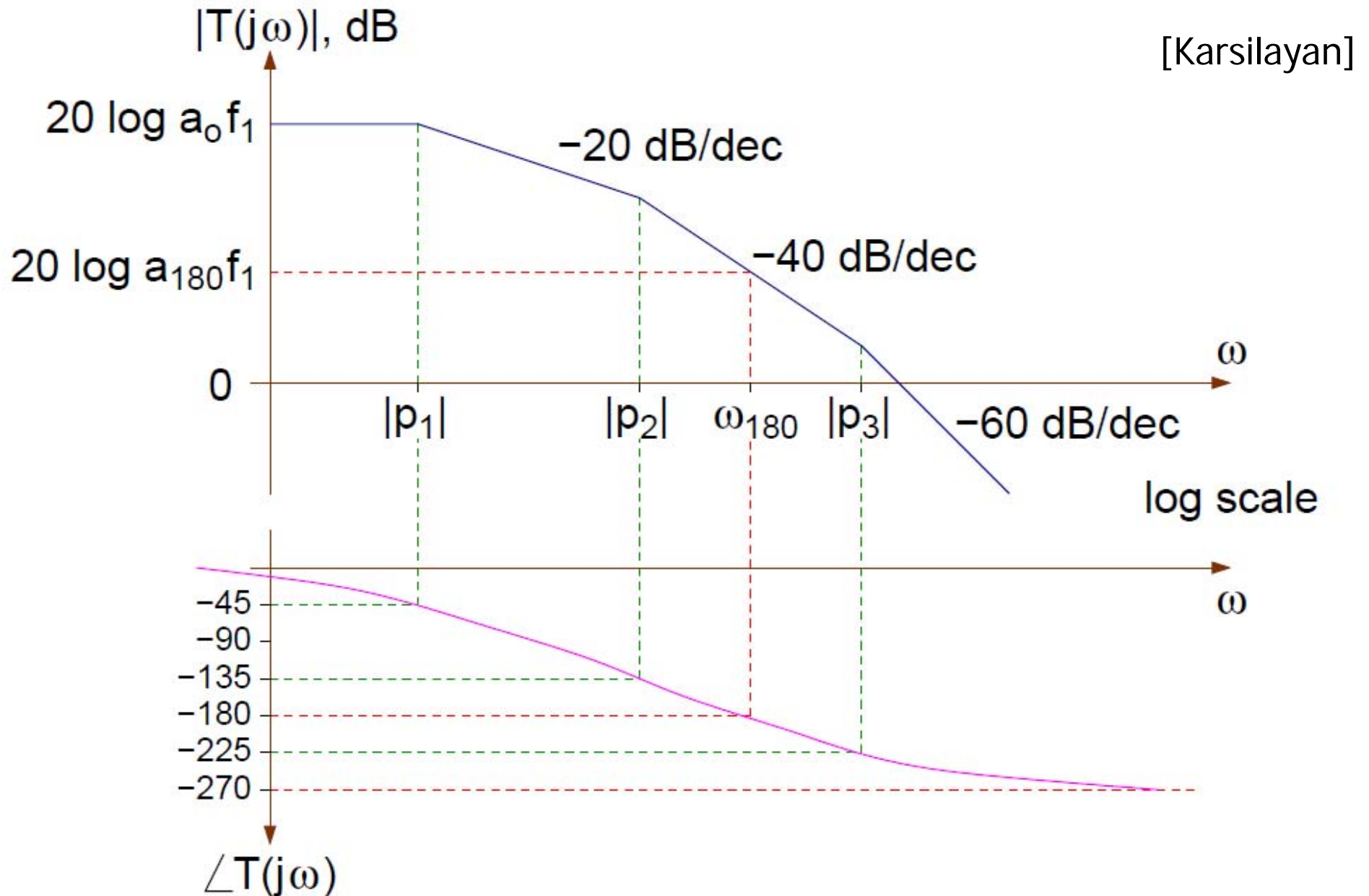
# Magnitude & Phase

3-pole amplifier



# Magnitude & Phase

$$T(s) = a(s)f_1$$

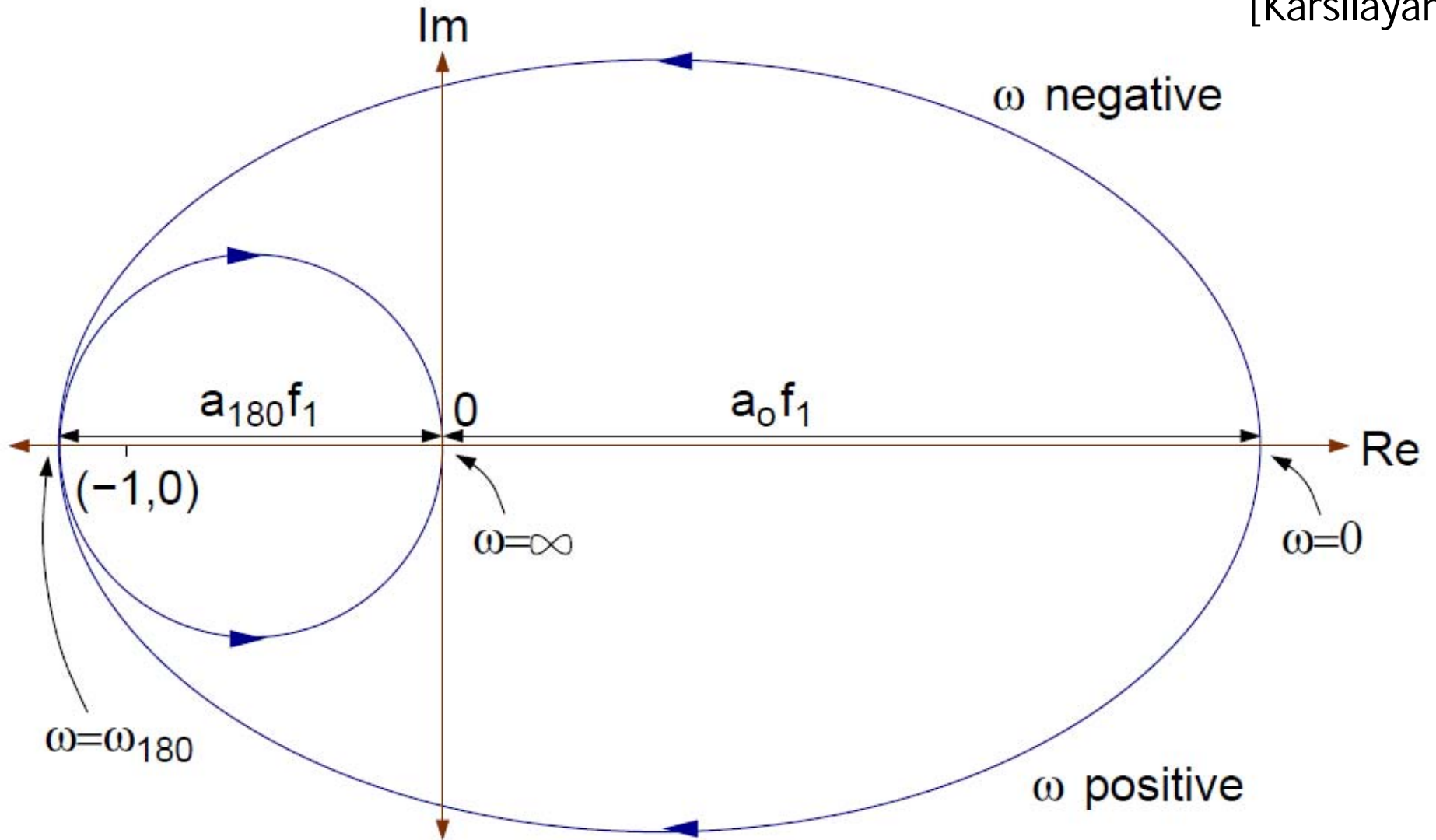


# Nyquist Plot

$$T(s) = a(s)f_1$$

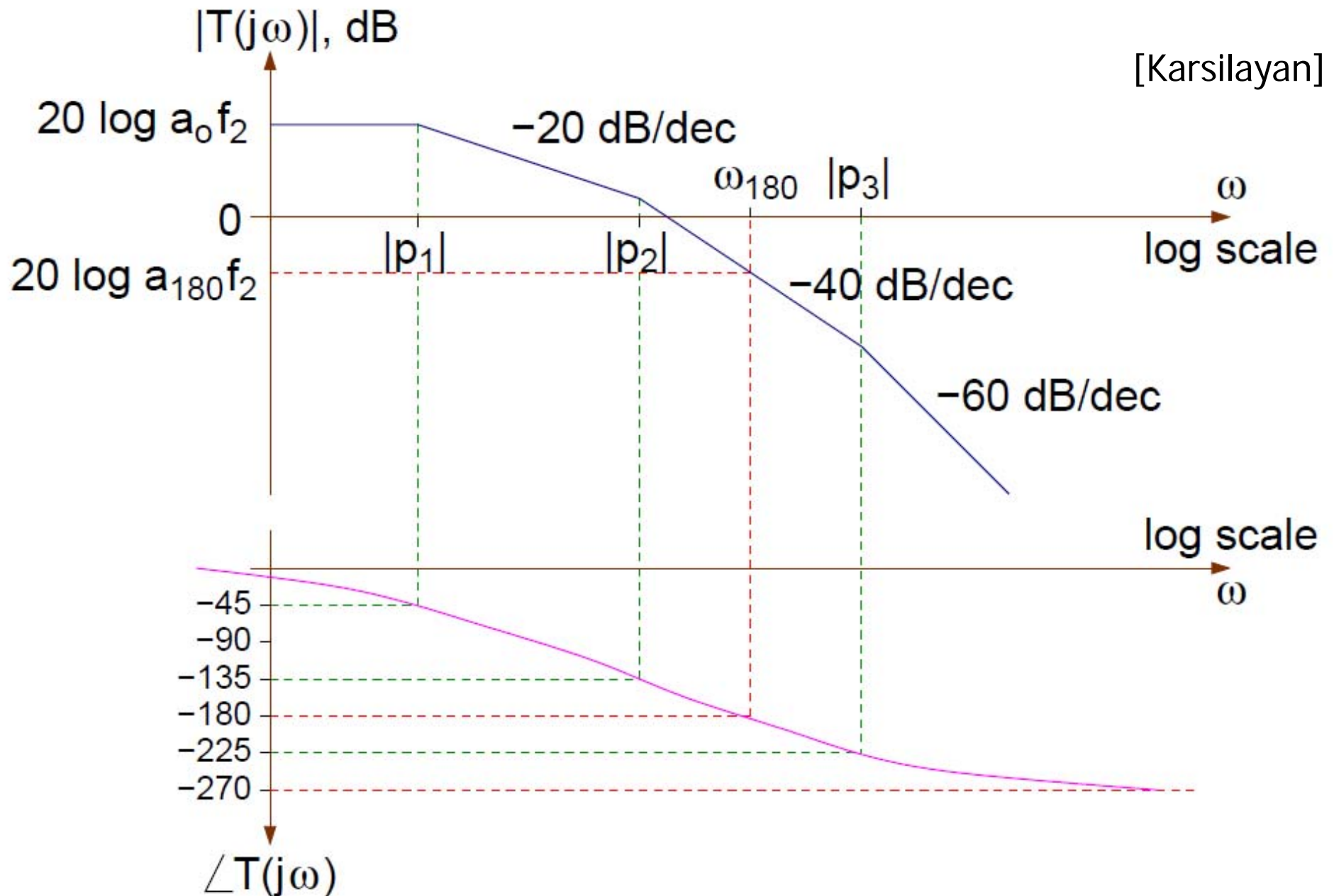
Frequency Sweep of Loop Gain,  $T(s)$

[Karsilayan]



# Magnitude & Phase

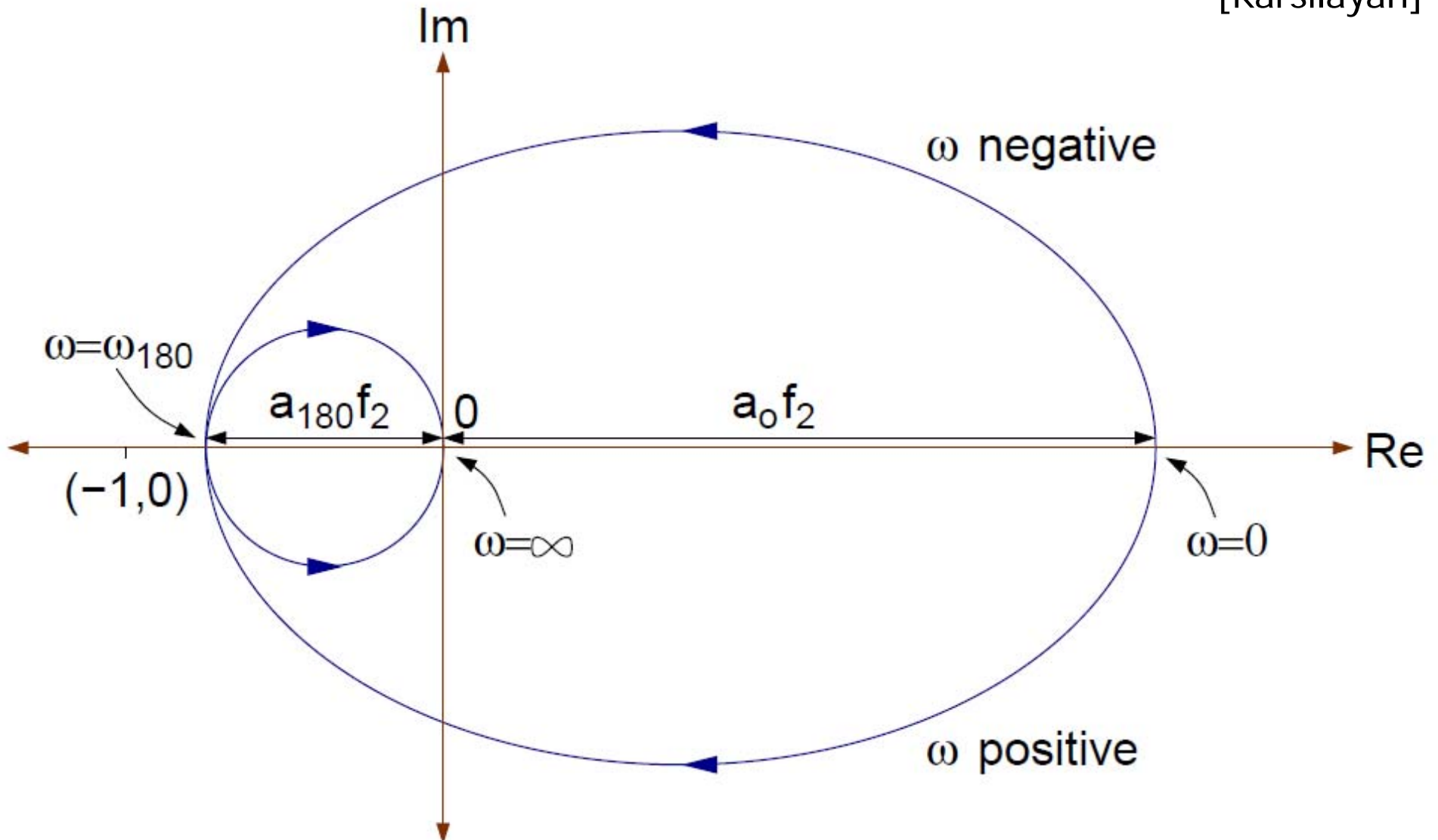
$$T(s) = a(s)f_2$$



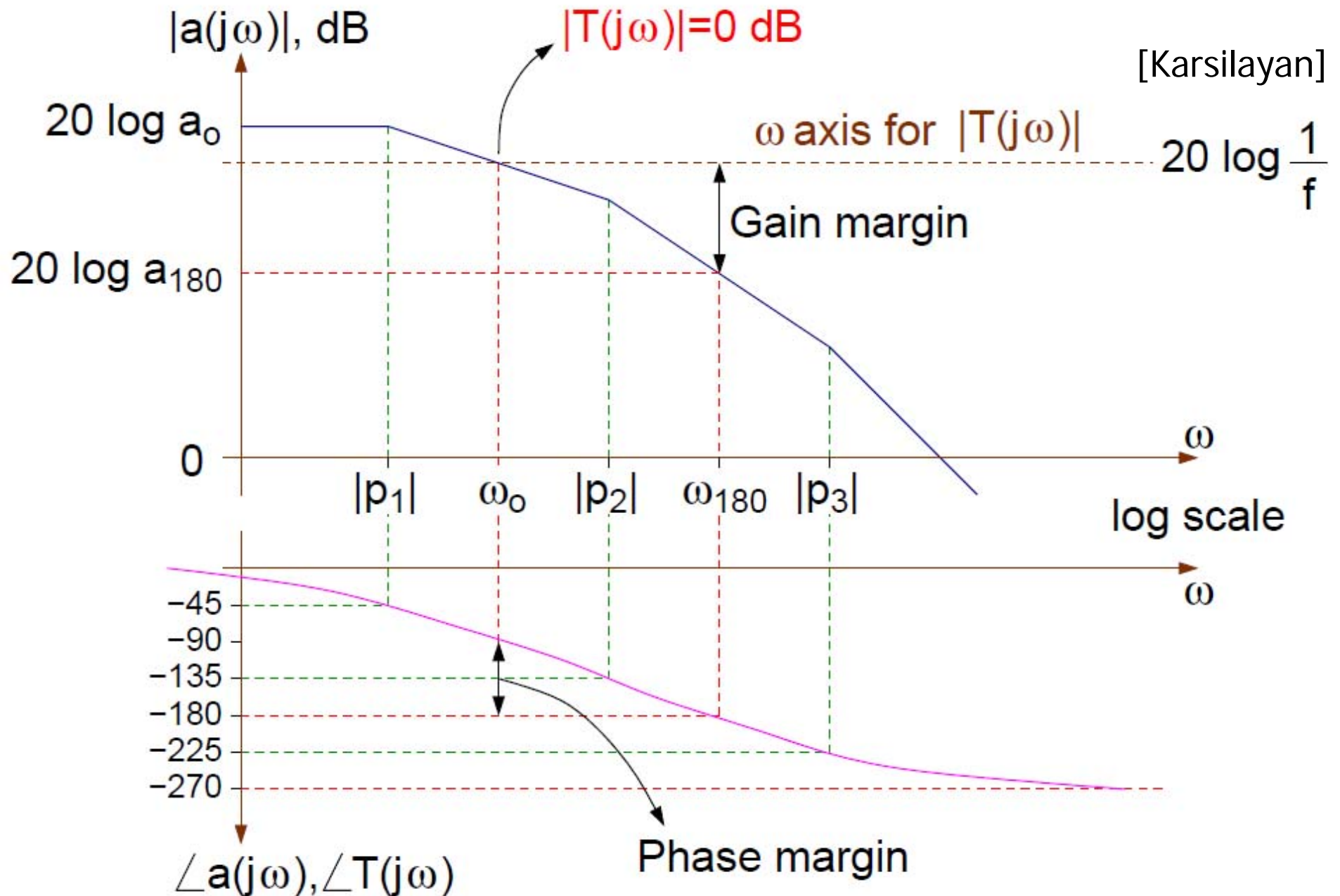
# Nyquist Plot

$$T(s) = a(s)f_2$$

[Karsilayan]



# Gain & Phase Margin



# Stability Criteria

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Nyquist:

$$|T(j\omega_{180})| = a_{180}f < 1 \Rightarrow \text{Stable}$$

[Karsilayan]

Gain Margin (**GM**):

$$\text{GM} = 20 \log \frac{1}{|T(j\omega_{180})|} = -20 \log |T(j\omega_{180})|$$

$$\text{GM} > 0 \Rightarrow \text{Stable}$$

Phase Margin (**PM**):

$$\text{PM} = 180^\circ + \angle T(j\omega_o)$$

$$\text{PM} > 0 \Rightarrow \text{Stable}$$

# Phase Margin

[Karsilayan]

$$|T(j\omega_o)| = 1 \Rightarrow |a(j\omega_o)|f = 1 \Rightarrow |a(j\omega_o)| = \frac{1}{f}$$

$$PM = 45^\circ \Rightarrow \angle T(j\omega_o) = -135^\circ, \mathbf{A}_{CL}(j\omega_o) = \frac{a(j\omega_o)}{1 + T(j\omega_o)}$$

$$\mathbf{A}_{CL}(j\omega_o) = \frac{a(j\omega_o)}{1 + e^{-j135^\circ}} = \frac{a(j\omega_o)}{1 - 0.7 - 0.7j}$$

$$|\mathbf{A}_{CL}(j\omega_o)| = \frac{|a(j\omega_o)|}{|0.3 - 0.7j|} = \frac{1}{0.76f} = \frac{1.3}{f}$$

$$PM = 30^\circ \Rightarrow \angle T(j\omega_o) = -150^\circ, |\mathbf{A}_{CL}(j\omega_o)| = 1.92/f$$

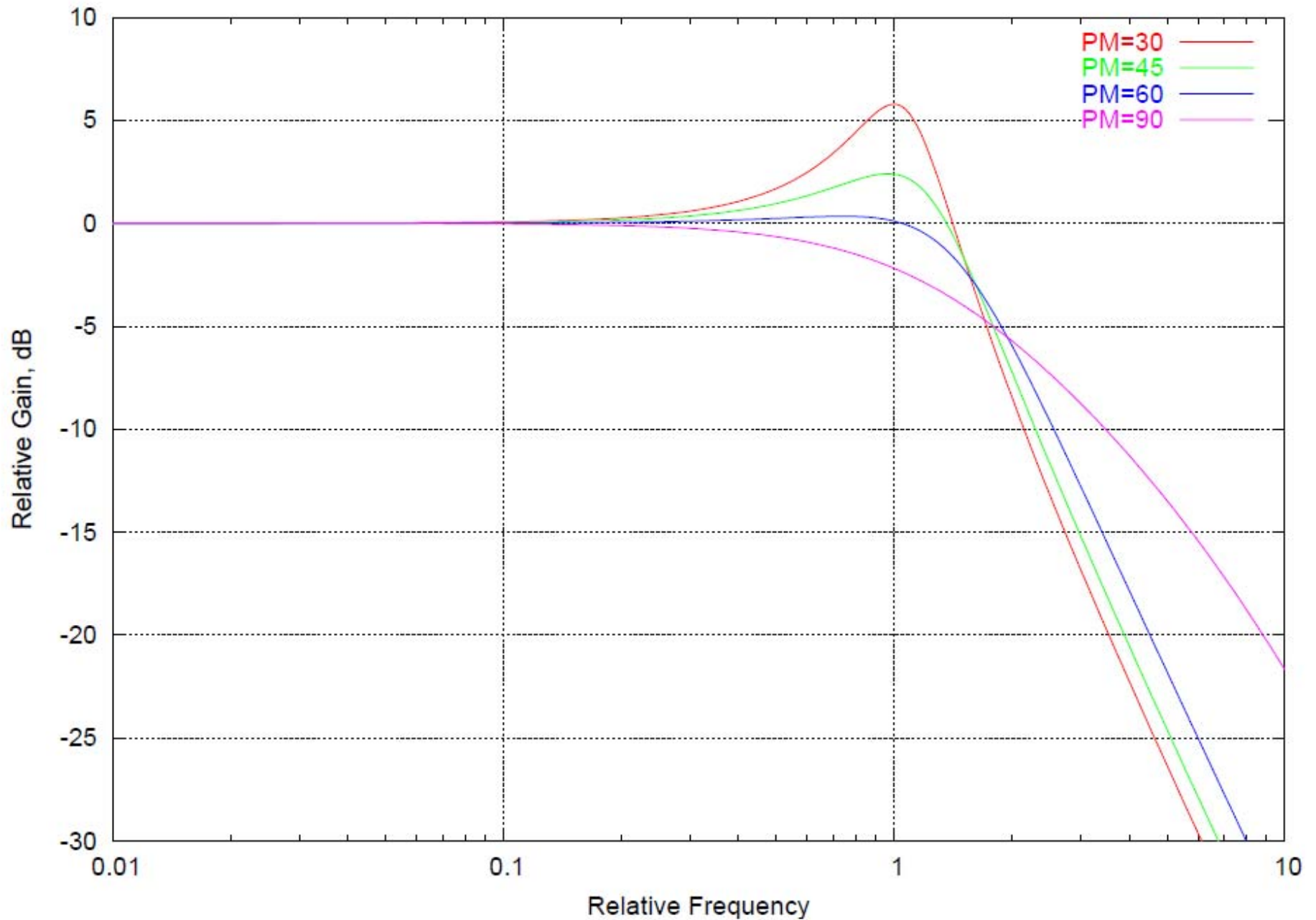
$$PM = 60^\circ \Rightarrow \angle T(j\omega_o) = -120^\circ, |\mathbf{A}_{CL}(j\omega_o)| = 1/f$$

$$PM = 90^\circ \Rightarrow \angle T(j\omega_o) = -90^\circ, |\mathbf{A}_{CL}(j\omega_o)| = 0.7/f$$



# Closed-Loop Frequency Response

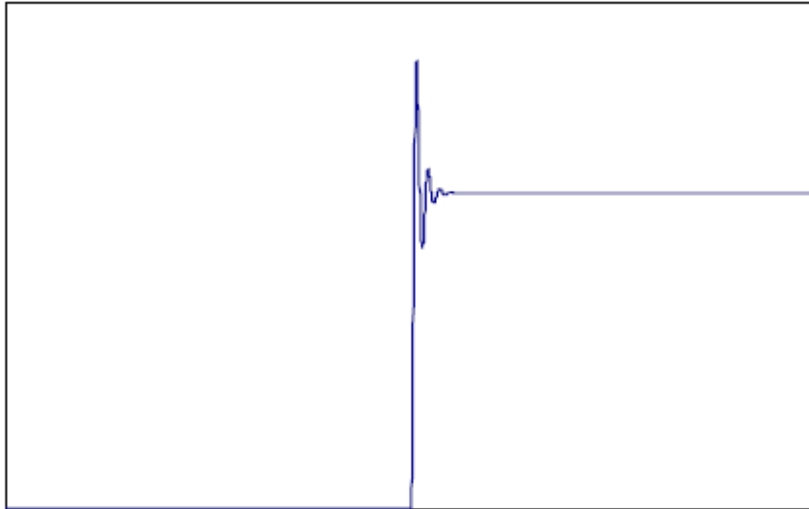
[Karsilayan]



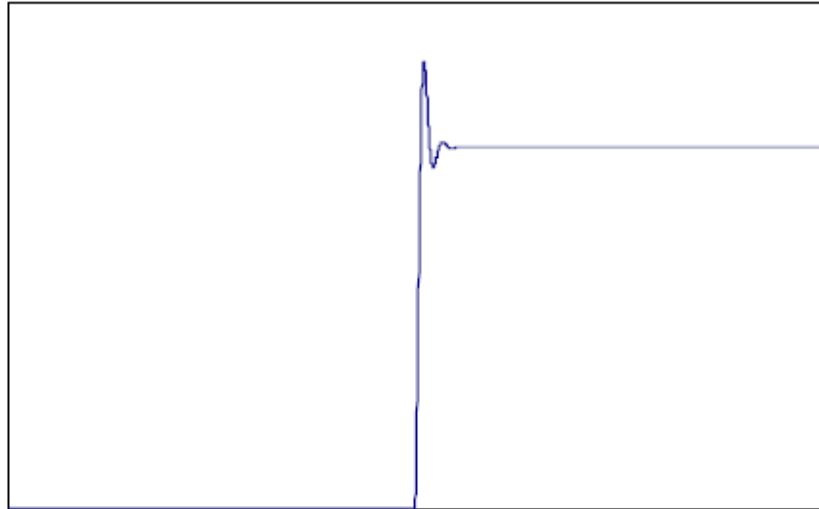
# Closed-Loop Step Response

[Karsilayan]

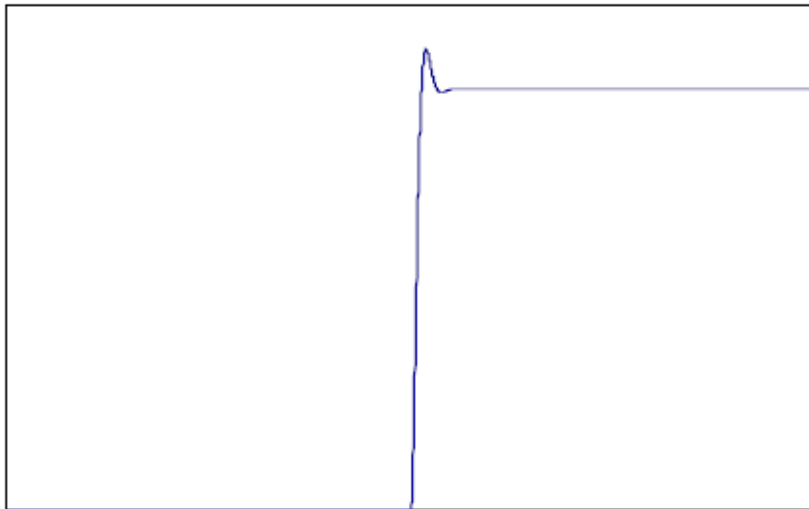
PM = 30°



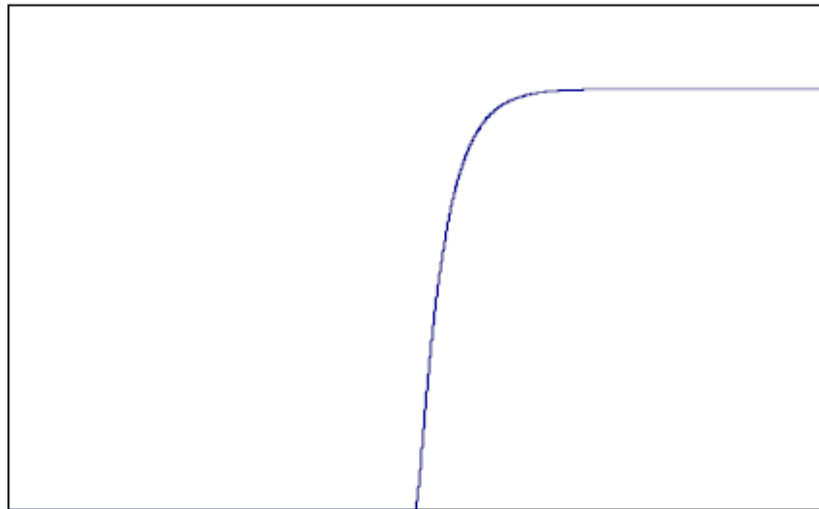
PM = 45°



PM = 60°



PM = 90°



# Next Time

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- Common-Mode Feedback Techniques