#### ECEN326: Electronic Circuits Spring 2022

#### Lab 1 Graphical Design Approach



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#### Common Emitter Amp w/ Emitter Resistor



### **Typical Design Specifications**

- Loaded voltage gain, A<sub>v</sub>
- Max output swing, v<sub>omax</sub>
  - This must be satisfied at a given linearity (total harmonic distortion)
- Input resistance, R<sub>in</sub>
- Power Supply,  $V_{CC}$
- Min Emitter Voltage for  $\beta$  robustness,  $V_{\text{E}}$

### How to set DC Biasing Conditions?

- In order to meet all design specifications, the DC biasing conditions (I<sub>C</sub>, R<sub>C</sub>) must be set appropriately
- Can transform design specifications into functions of  $I_C \& R_C$  and graph them to find acceptable solution space

## R<sub>in</sub>, V<sub>CC</sub>, & Neg. v<sub>omax</sub> Specifications



- $R_{in} = kR_B \left\| (1-k)R_B \right\| \left\| (\beta+1)(r_e + R_E \| R_G) \right\| \approx \beta \left( R_E \| R_G \right)$  $R_E \left\| R_G \approx \frac{R_{in}}{\beta} \right\|$
- Input resistance is primarily set by R<sub>E</sub>||R<sub>G</sub>

# $R_{in}$ , $V_{CC}$ , & Neg. $v_{omax}$ Specifications

 Need a minimum V<sub>CE</sub> to keep transistor in active mode with maximum negative swing

Set  $V_{CE \min} = 300 mV$ \* Note if the specs are relaxed enough, it is often good to set  $V_{CE \min} = 500 mV$ for margin.



V<sub>CC</sub> Spec (w/ max negative swing)

$$V_{CC} = V_E + V_{CE\min} + v_{o\max} + I_C R_C$$
$$V_{CE\min} = V_{CC} - I_C R_C - v_{o\max} - V_E \ge 300 mV$$

## $R_{in}$ , $V_{CC}$ , & Neg. $v_{omax}$ Specifications

• Can solve for I<sub>C</sub>



$$I_C \leq \frac{V_{CC} - v_{o\max} - 0.3V - V_E}{R_C}$$

• Minimum negative AC Swing constraint sets an upper bound on  $\rm I_{\rm C}$ 

## Pos. v<sub>omax</sub> Specification

 Need to insure with a positive swing that the output signal doesn't clip the power supply

$$V_{CC} - I_C R_C + v_{o\max} \le V_{CC}$$

$$I_C \ge \frac{v_{o\max}}{R_C}$$



- Positive AC Swing constraint sets a lower bound on  $\rm I_{\rm C}$
- Additional linearity constraint (harmonic distortion) generally sets a tighter bound

#### Gain Specification



$$I_C \geq \frac{|A_v|V_{th}}{R_C \left\| R_L - \frac{|A_v| \left( R_E \| R_G \right)}{\alpha} \right\|} = \frac{|A_v|V_{th}}{R_C \left\| R_L - \frac{|A_v|R_{in}}{\alpha\beta} \right\|}$$

Gain constraint sets a lower bound on I<sub>C</sub>

#### Harmonic Distortion Specification

 Need a minimum amount of bias current to insure that the AC swing doesn't distort



Model a as a system which distorts

$$i_c = av_{be} = a_1v_{be} + a_2v_{be}^2 + a_3v_{be}^3 + \dots$$
  
where  $a_1 = g_m$ ,  $a_2 = \frac{1}{2}\frac{I_{CQ}}{V_{th}^2}$ ,  $\dots$   
Here  $v_{be} = v_b - v_e \approx v_b - fi_c$   
where  $f = R_E$ 

\*This analysis is for a general CE Amp, in our specific circuit  $R_C \Rightarrow R_C || R_L$ and  $R_F \Rightarrow R_F || R_G$ 

#### Harmonic Distortion Specification



We want to express  $i_c$  as a function of  $v_b$  because that is our input

$$i_c = bv_b = b_1v_b + b_2v_b^2 + b_3v_b^3 + \dots$$

Can show that \*

$$b_1 = \frac{g_m}{1 + g_m R_E}, \quad b_2 = \frac{1}{2} \frac{I_{CQ}}{V_{th}^2 (1 + g_m R_E)^3}, \quad \dots$$

 For single-ended amplifiers with low-distortion, HD2 will dominate the distortion terms
 \*This analysis i

The second - order harmonic distortion is

$$HD2 = \frac{1}{2} \frac{b_2}{b_1^2} i_{c \max} = \frac{1}{4} \left( \frac{1}{1 + g_m R_E} \right) \left( \frac{i_{c \max}}{I_{CQ}} \right)$$

\*This analysis is for a general CE Amp, in our specific circuit  $R_C \Rightarrow R_C || R_L$ and  $R_E \Rightarrow R_E || R_G$ 

#### Harmonic Distortion Specification



 HD2 will dominate, but is not the only distortion term, so you need to use a slightly larger current or put some margin in the HD2 value relative to the THD spec

#### Key CE Amp Design Equation Summary

Neg. Swing, Rin, 
$$V_{CC}$$
:  $I_C \leq \frac{V_{CC} - v_{o \max} - 0.3V - V_E}{R_C}$   
Pos. Swing:  $I_C \geq \frac{v_{o \max}}{R_C}$   
Gain:  $I_C \geq \frac{|A_v|V_{th}}{R_C \|R_L - \frac{|A_v|R_{in}}{\alpha\beta}}$   
Harmonic Distortion:  $I_C \geq \frac{1}{2} \sqrt{\frac{V_{th}v_{o \max}\beta}{(R_C \|R_L)R_{in}HD2}}$ 

### **Design Example - Specifications**

- $|A_v| \ge |-20|$
- $R_{in} \ge 10 k\Omega$
- $R_L = 20k\Omega$
- $V_{\text{omax}} = 1V_{\text{pk}} \text{ w/ THD} \le 5\% \text{ (-26.0dB)}$
- $V_{CC} = 5V$
- V<sub>E</sub> ≥ 0.5V
- Isupply  $\leq 1.5$ mA
- Nominal operation at 5kHz

#### **Design Equation Plots**



• Chosen design point is  $I_c=1mA$ ,  $R_c=3k\Omega$ 

### **DC Operating Points**



- $R_E$  is set with  $V_E = I_E R_E$
- $R_G$  is set as  $R_{in}/\beta$
- DC bias points must be reasonable for the circuit to work as designed!

#### • $|A_v| = 29.4 dB = 29.5 V/V$

AC Gain



 $\mathsf{R}_{\mathsf{in}}$ 



•  $R_{in} = 80.7 dB\Omega = 10.8 k\Omega$ 

#### **Transient Response**



- Response with 35.5mV<sub>pk</sub> input signal
- Signal is beginning to compress

#### **Total Harmonic Distortion**



• THD = 3.16% = -30dB

# $\mathsf{R}_{\mathsf{out}}$



•  $R_{out} = 69.4 dB\Omega = 2.95 k\Omega \approx R_C$ 

### Lab1 Design Specs

- $|A_v| \ge |-15|$
- $R_{in} \ge 5k\Omega$
- $R_L = 10 k\Omega$
- $V_{\text{omax}} = 1V_{\text{pk}} \text{ w/ THD} \le 5\%$  (-26.0dB)
- $V_{CC} = 5V$
- V<sub>E</sub> ≥ 0.5V
- Isupply  $\leq 4mA$
- Nominal operation at 5kHz