

Cardinality-Constrained Texture Filtering

Josiah Manson and Scott Schaefer

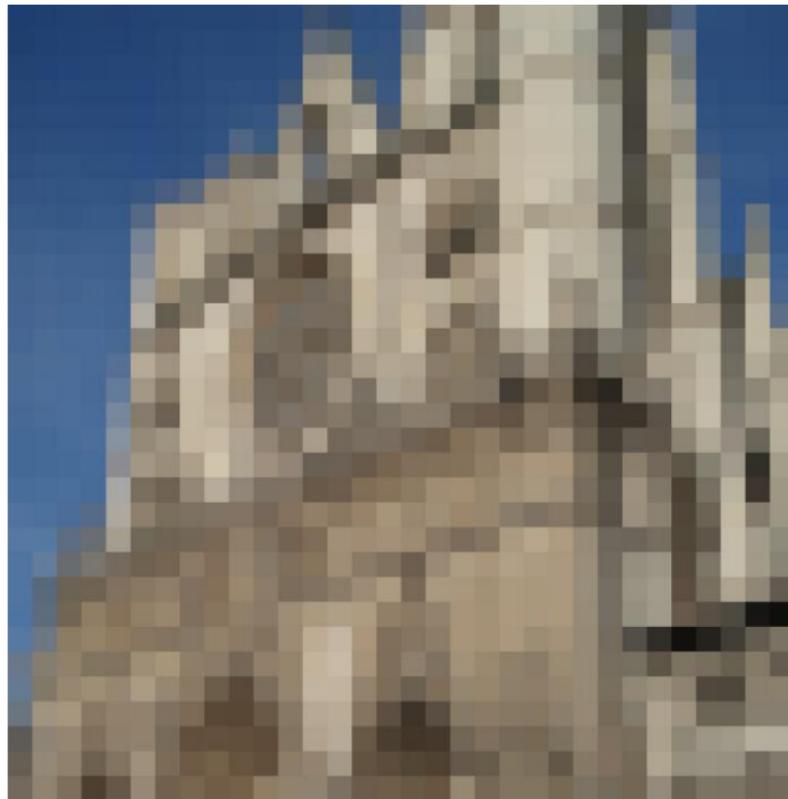
Texas A&M University



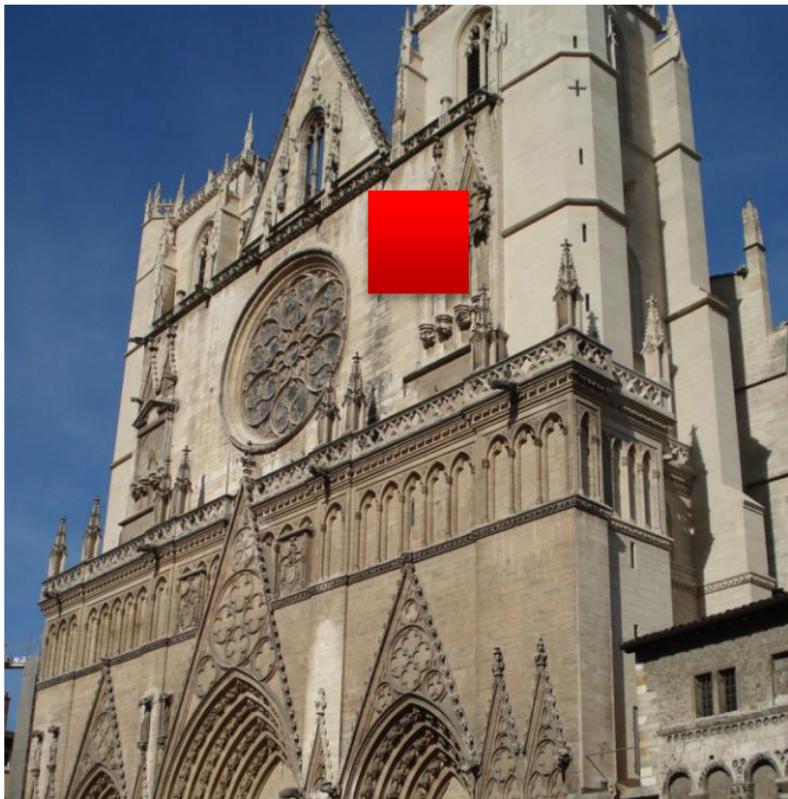
SIGGRAPH2013



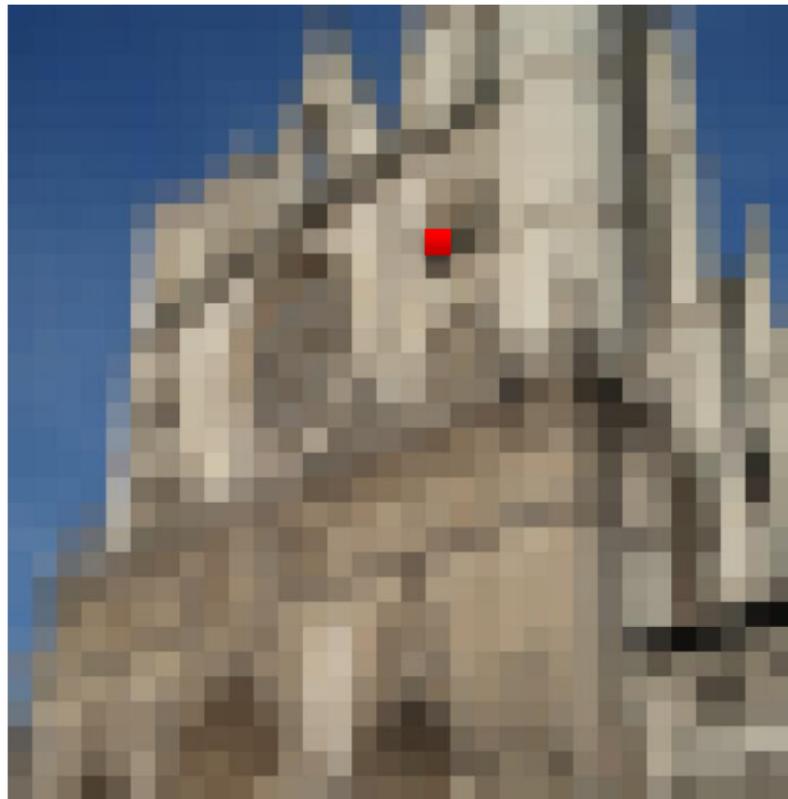
Input



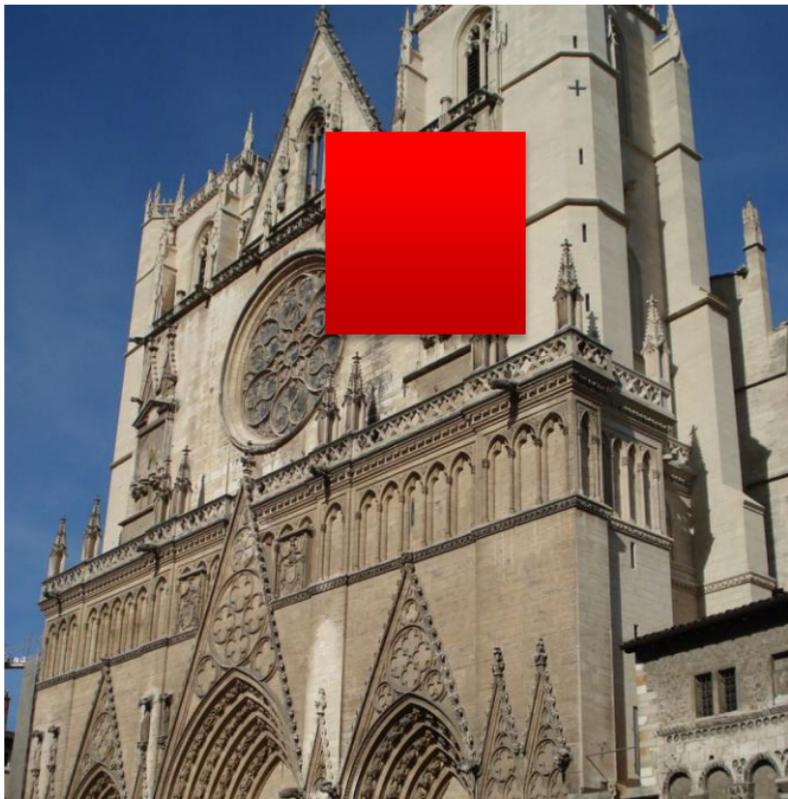
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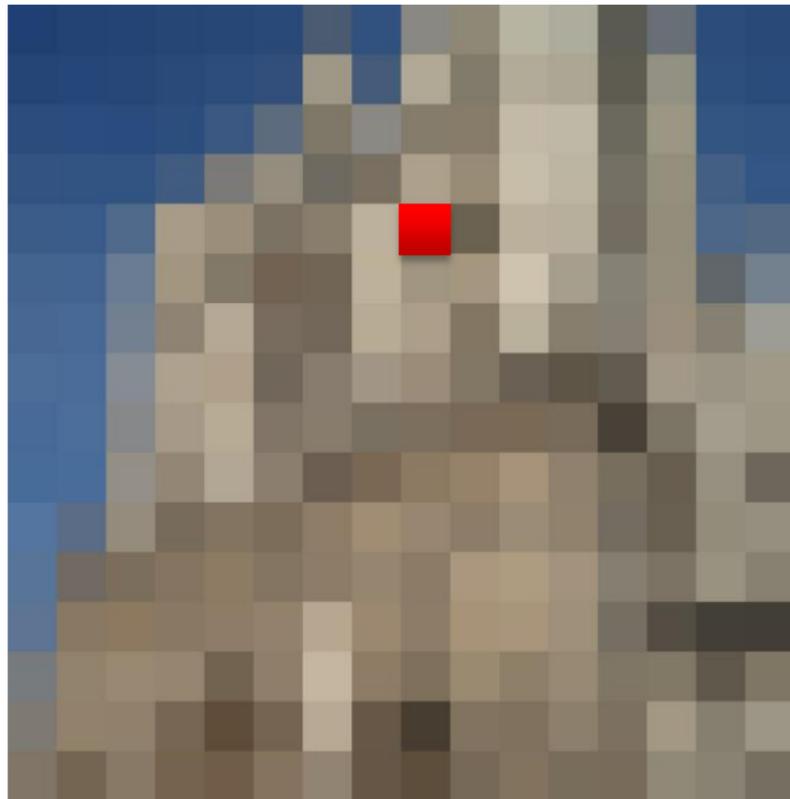
Input



Downsampled

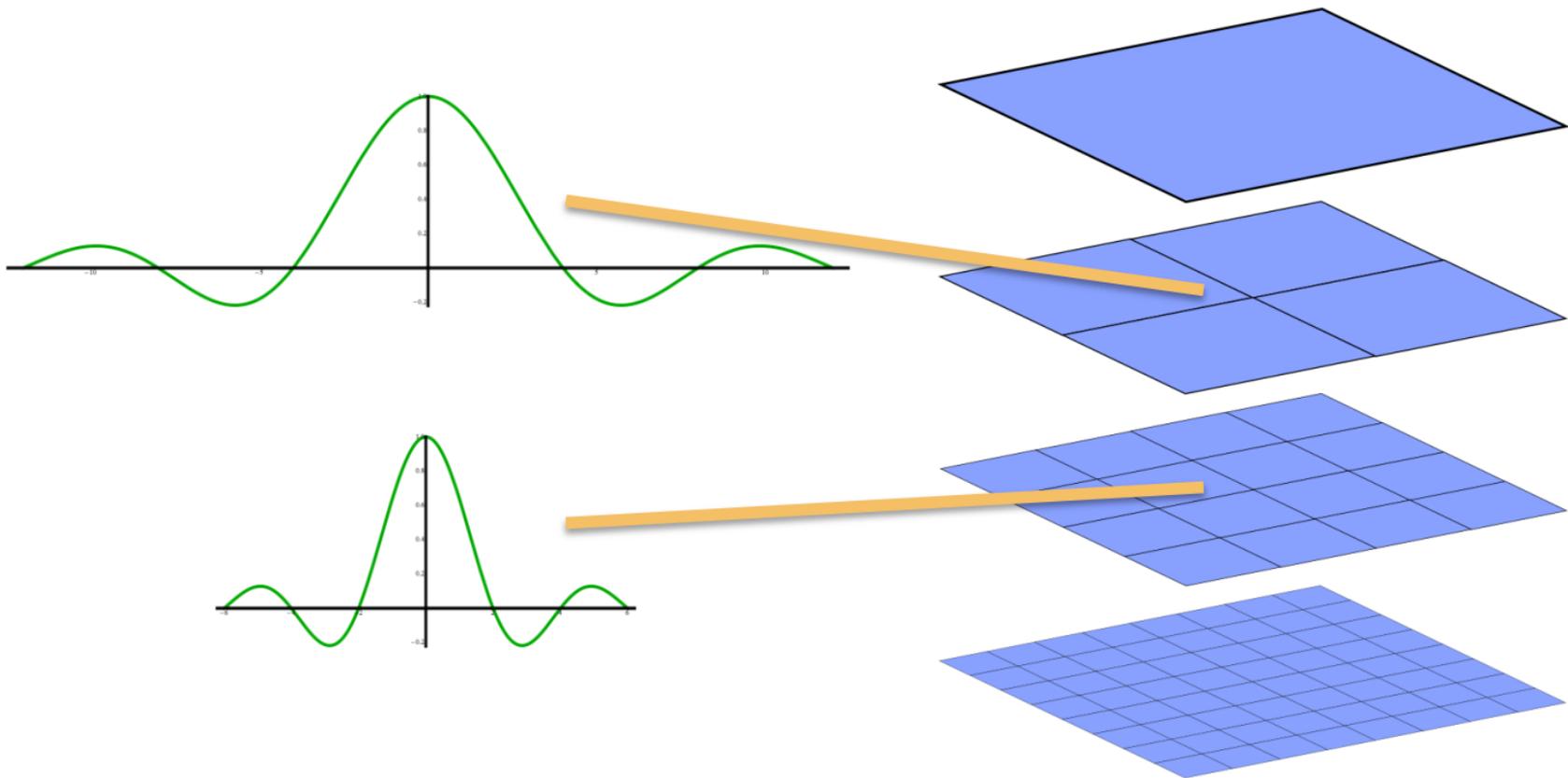


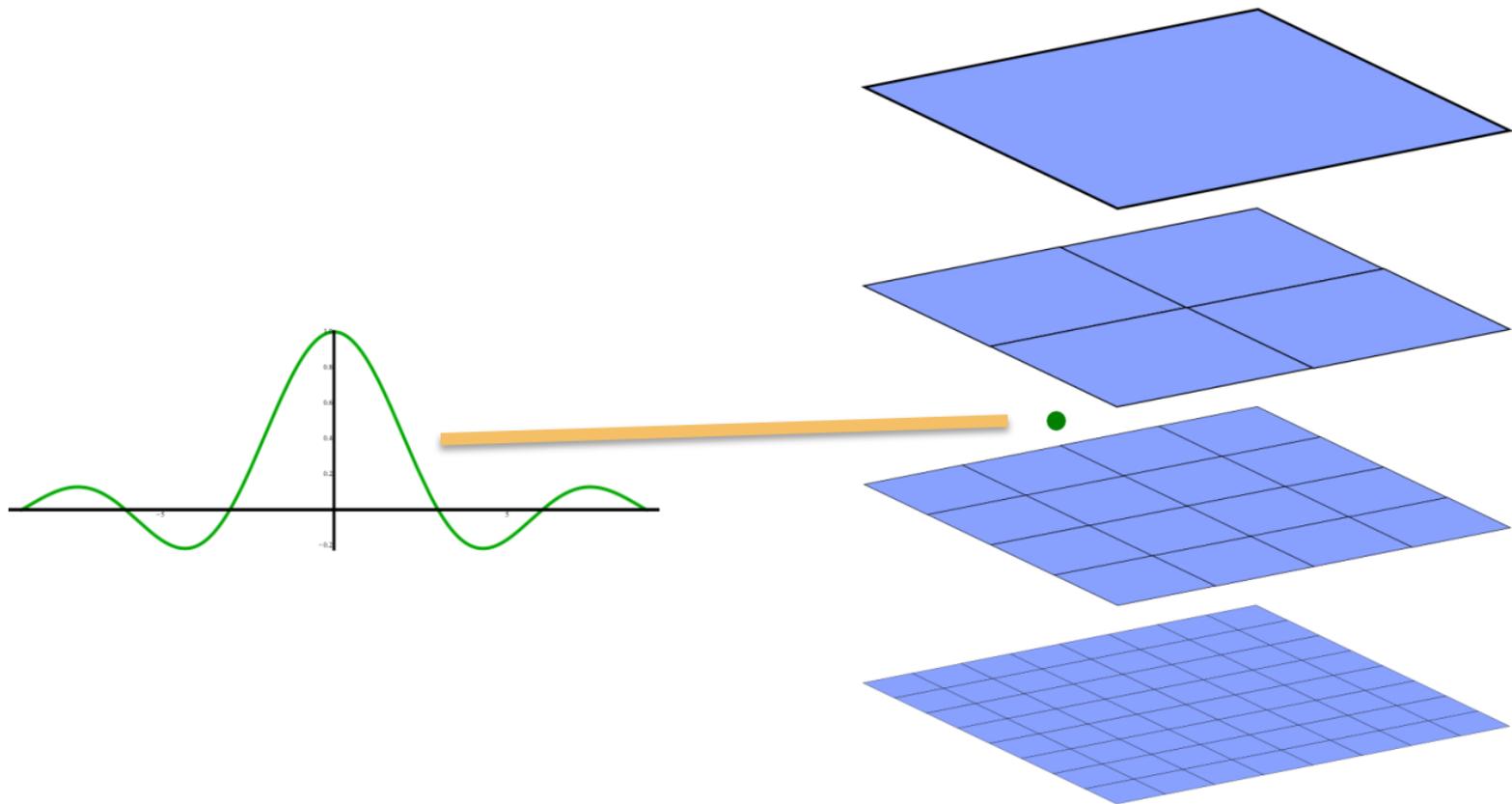
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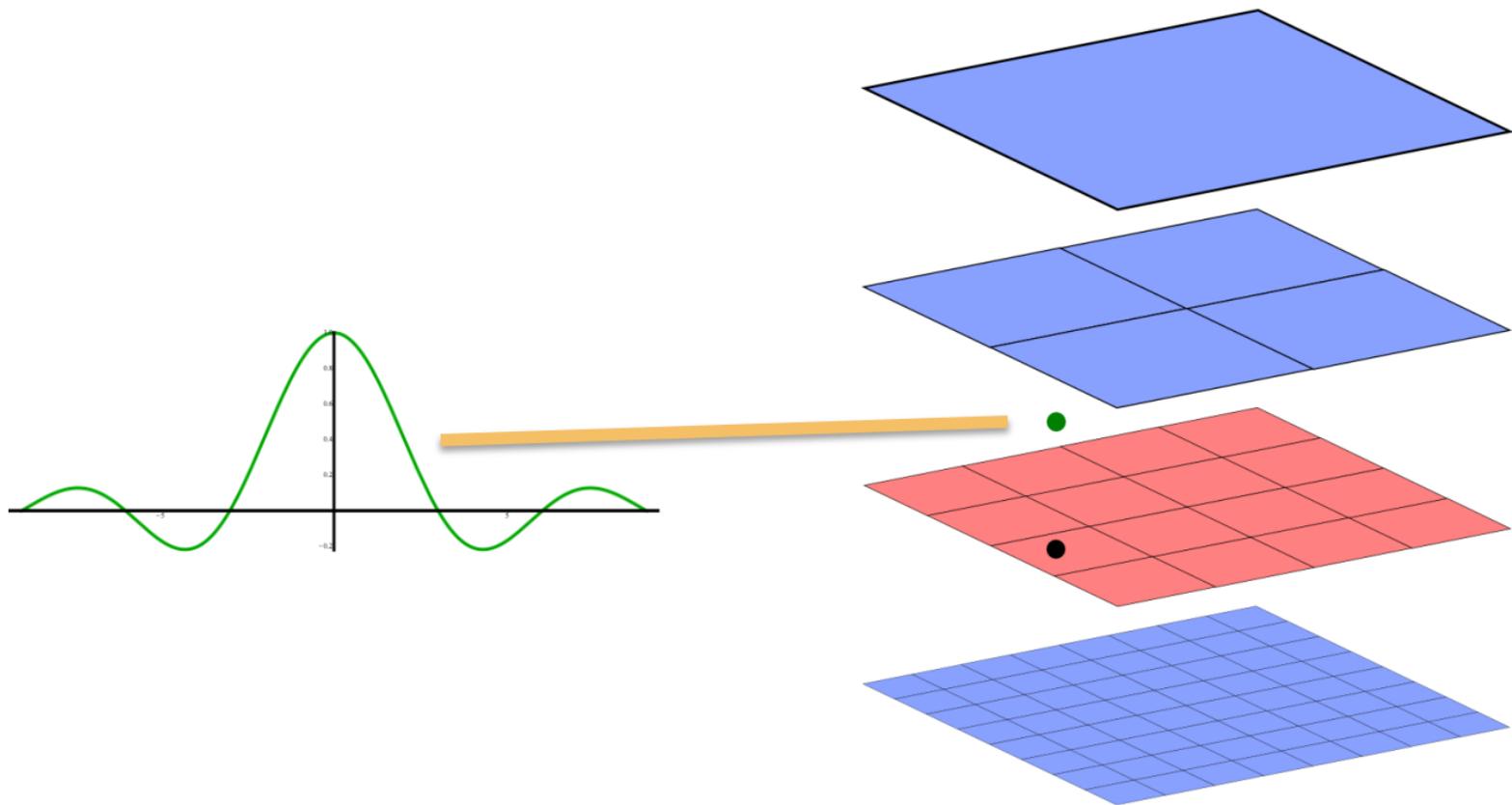


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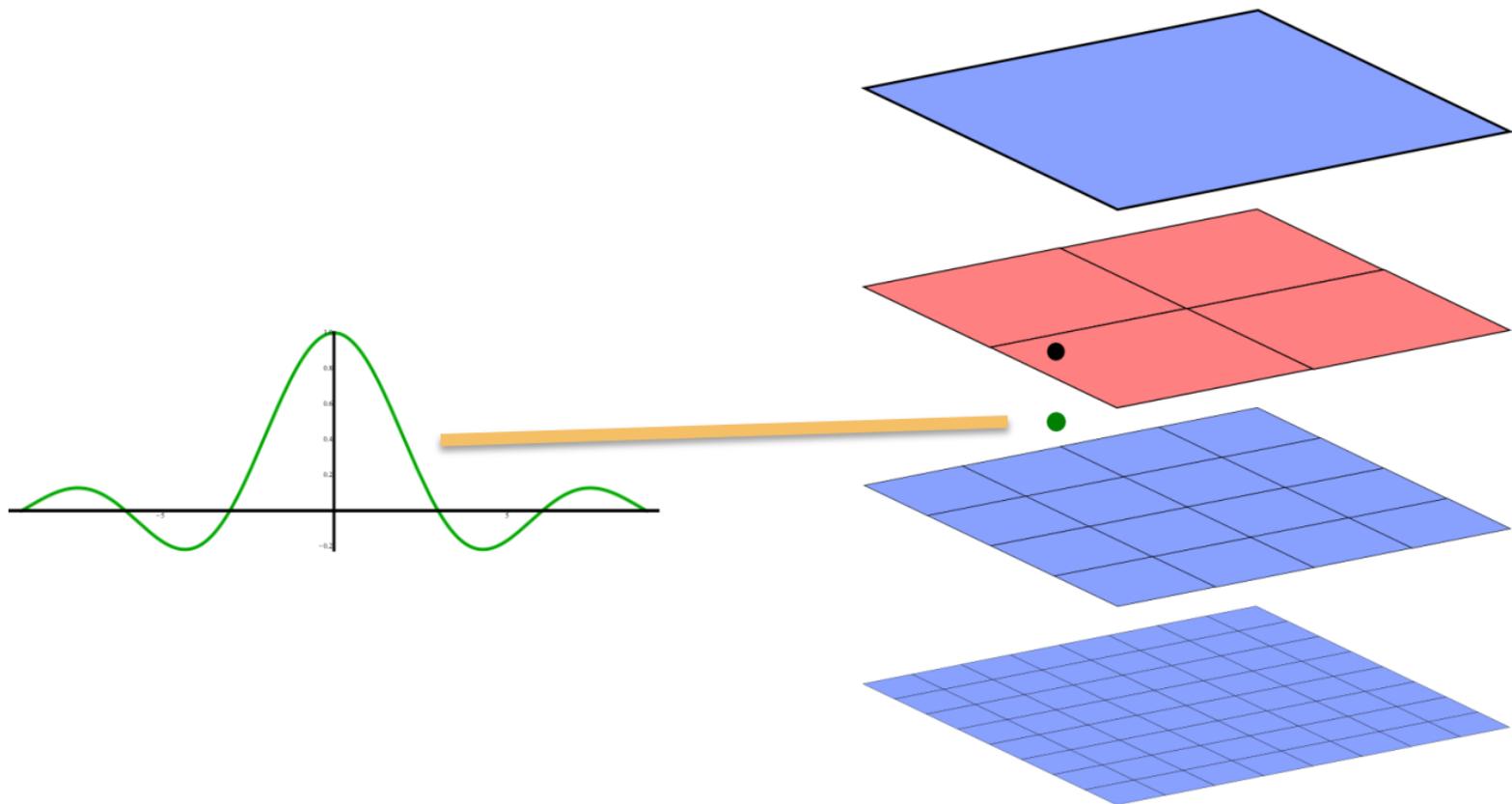
Mipmapping

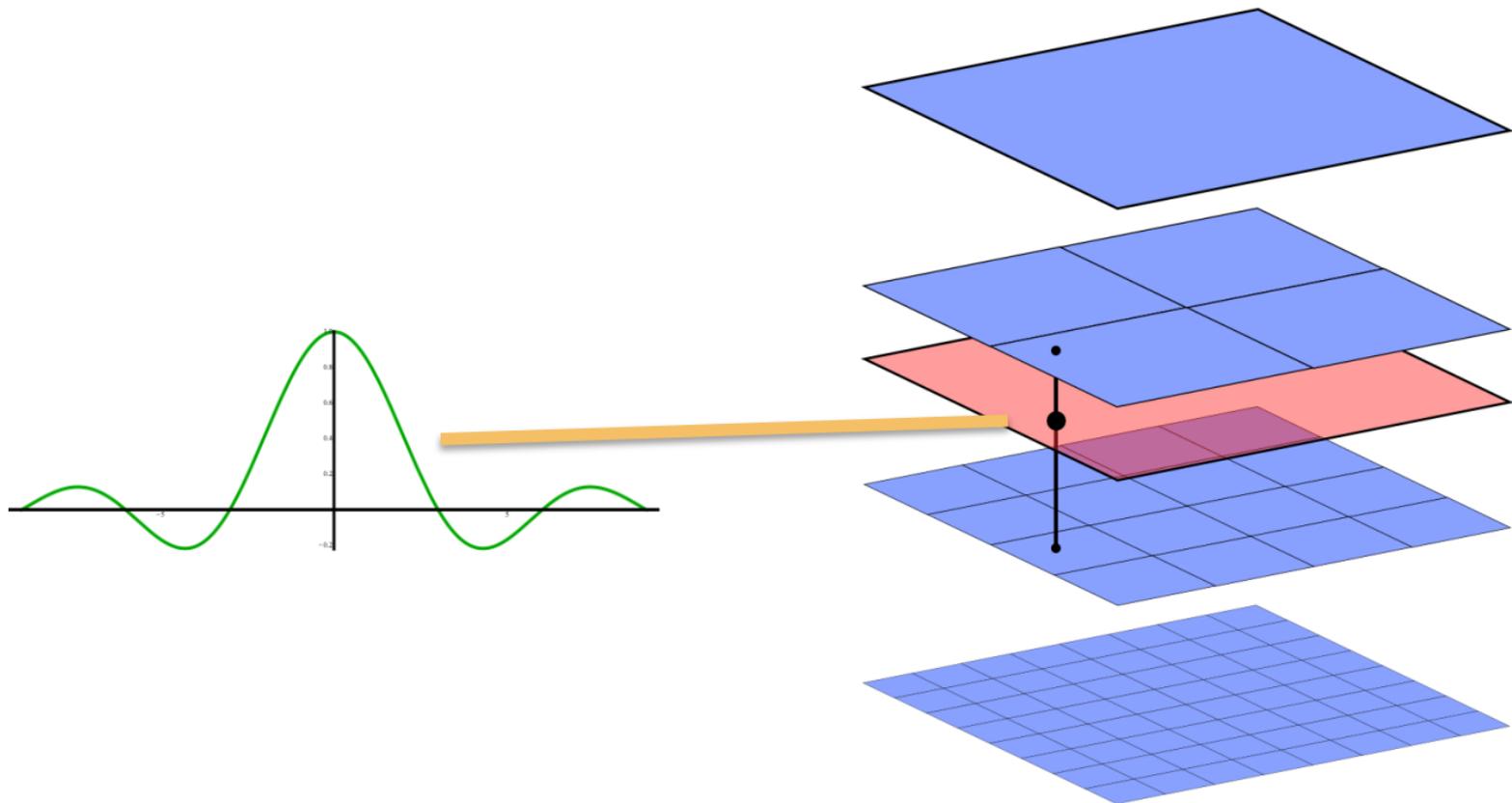






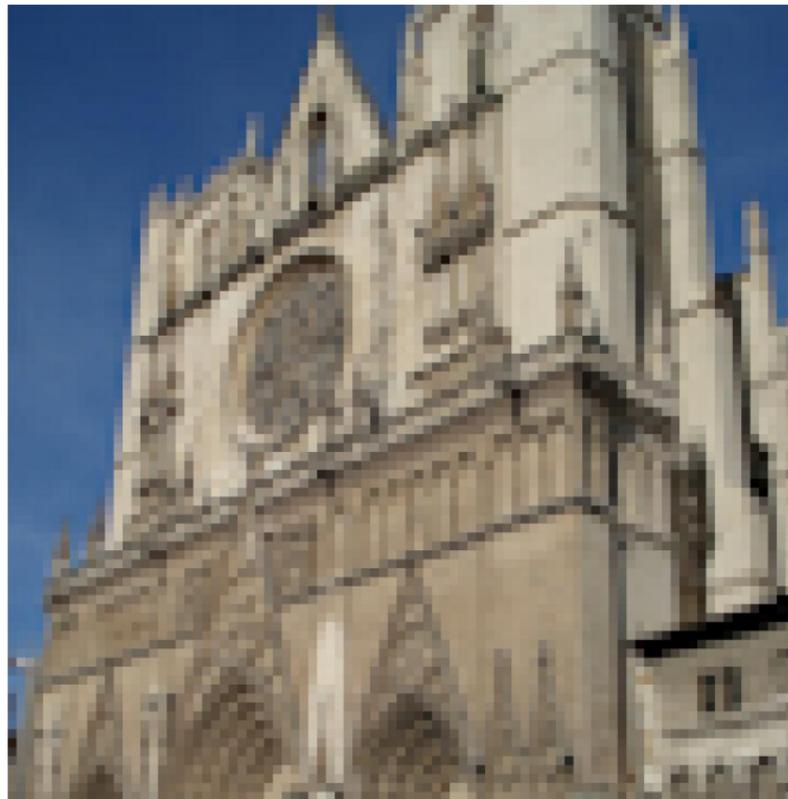
Mipmapping







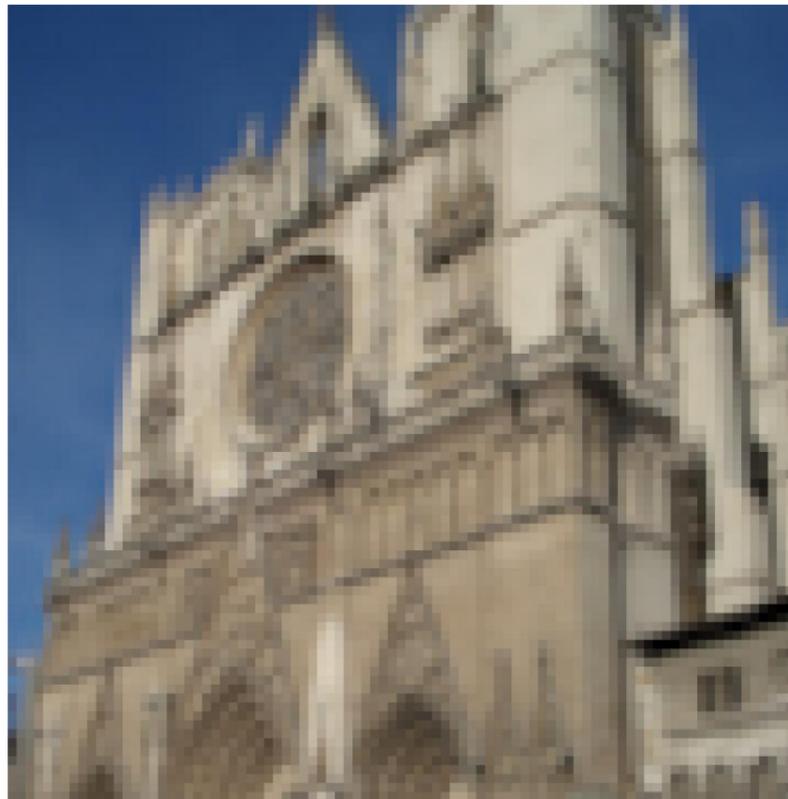
Input



Exact



Input



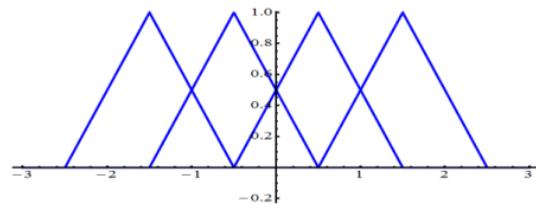
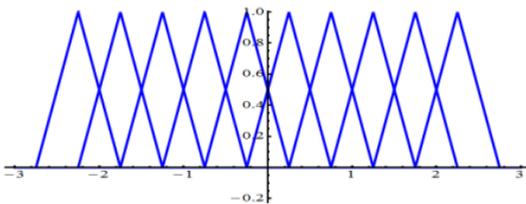
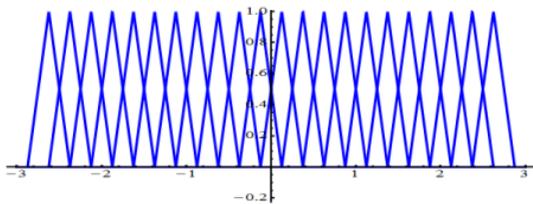
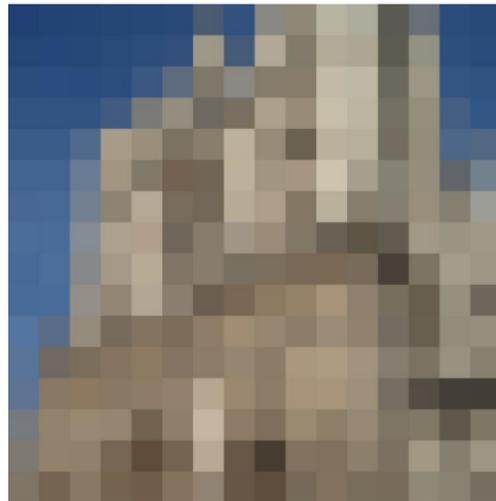
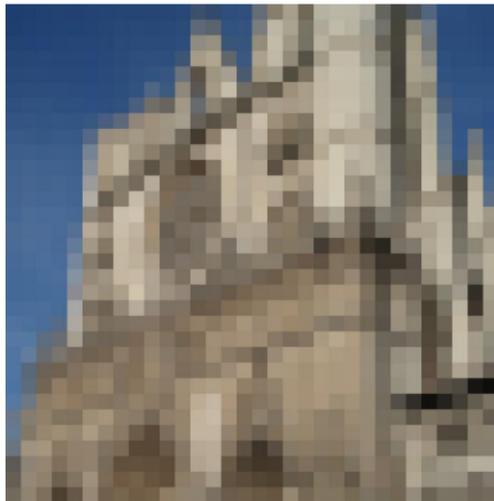
Trilinear



Input



Our Method



$$v_i = \iint_{\mathbb{R}^2} I(x)h_i(x) dx$$

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$$c_1 v_1 + c_2 v_2$$

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$$\iint_{\mathbb{R}^2} I(x)(c_1 h_1(x) + c_2 h_2(x)) dx$$

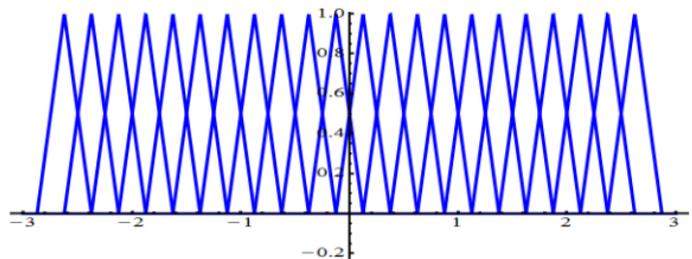
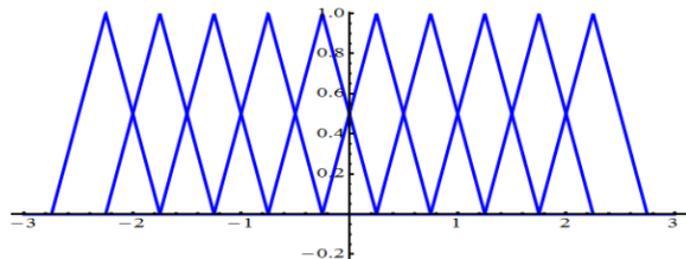
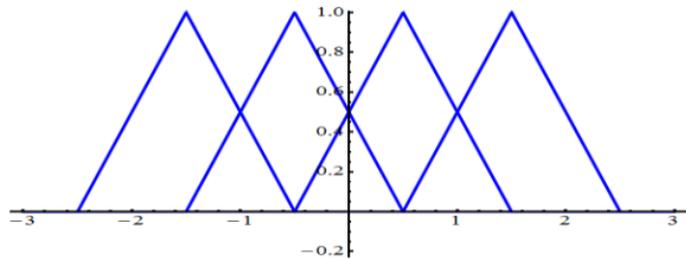
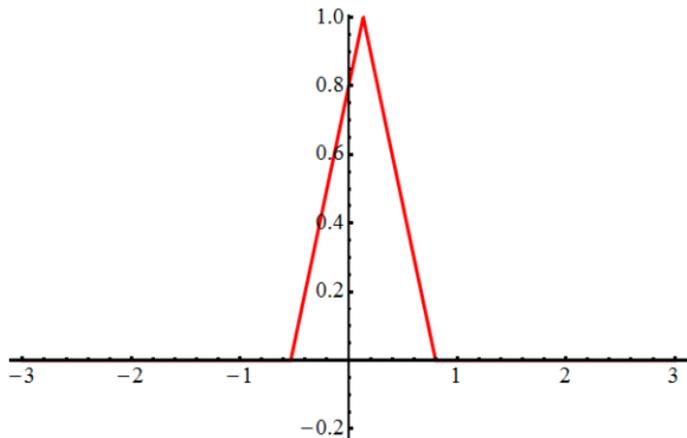
$$v_i = \iint_{\mathbb{R}^2} I(x) h_i(x) dx$$

$$c_1 v_1 + c_2 v_2$$

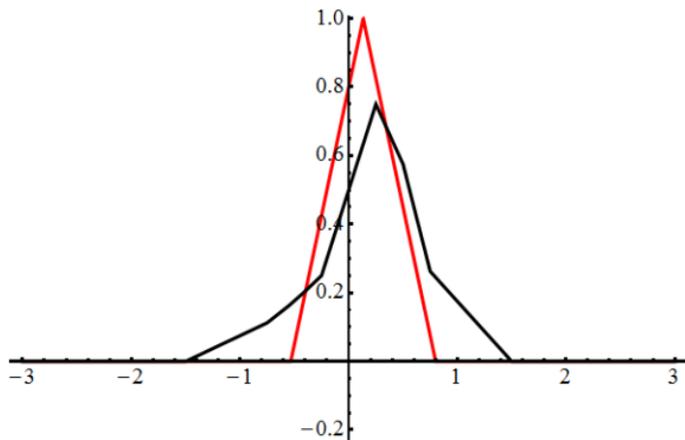
$$c_1 \iint_{\mathbb{R}^2} I(x) h_1(x) dx + c_2 \iint_{\mathbb{R}^2} I(x) h_2(x) dx$$

$$\iint_{\mathbb{R}^2} I(x) (c_1 h_1(x) + c_2 h_2(x)) dx$$

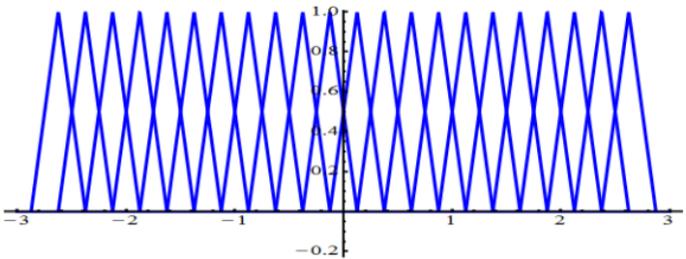
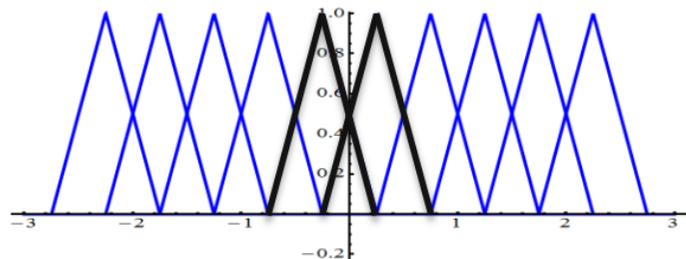
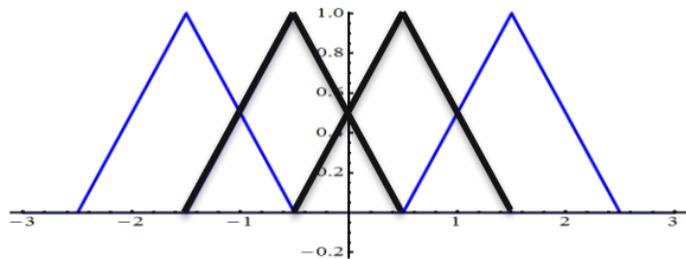
Filter Approximation



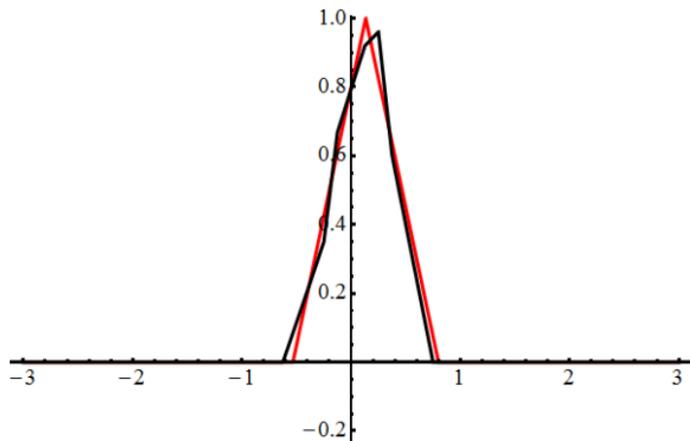
Filter Approximation



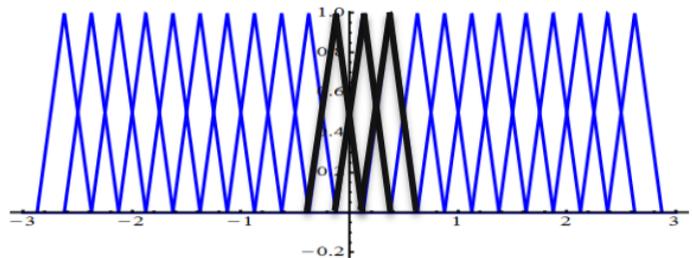
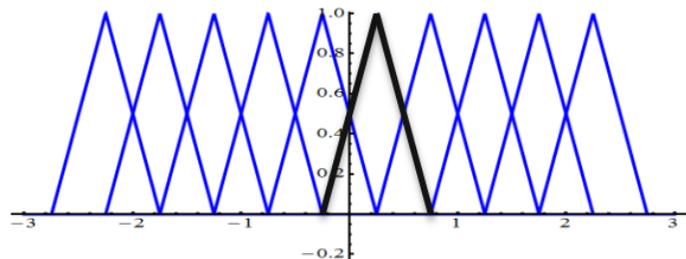
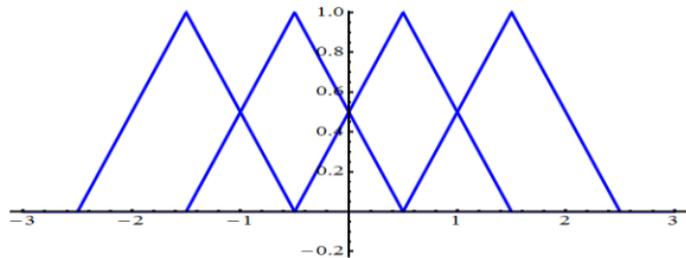
Interpolation of 4 samples



Filter Approximation

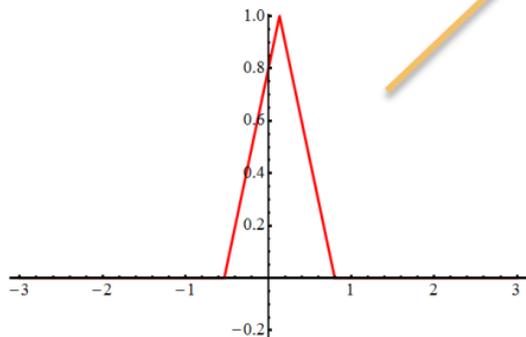


Best fit using 4 samples

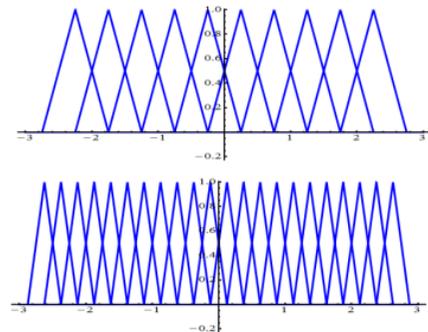
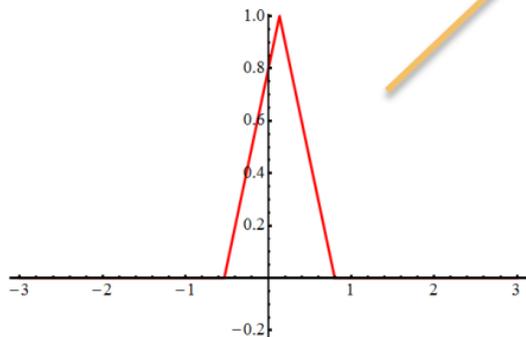


$$\operatorname{argmin}_{c, e \in E} \iint_{\mathbb{R}^2} \left(h_{\hat{s}, \hat{t}}(x) - \sum_{i=1}^n h_{e_i}(x) c_i \right)^2 dx$$

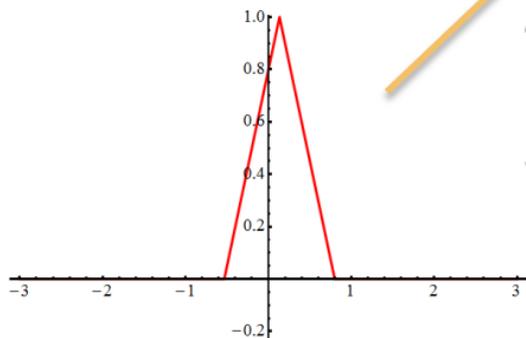
$$\operatorname{argmin}_{c, e \in E} \iint_{\mathbb{R}^2} (h_{\hat{s}, \hat{t}}(x) - \sum_{i=1}^n h_{e_i}(x) c_i)^2 dx$$



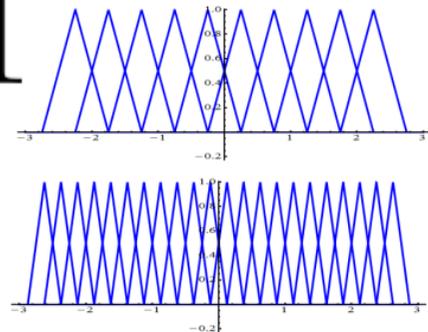
$$\operatorname{argmin}_{c, e \in E} \iint_{\mathbb{R}^2} \left(h_{\hat{s}, \hat{t}}(x) - \sum_{i=1}^n h_{e_i}(x) c_i \right)^2 dx$$



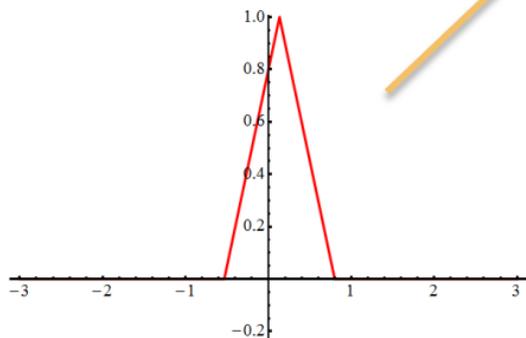
$$\operatorname{argmin}_{c, e \in E} \iint_{\mathbb{R}^2} \left(h_{\hat{s}, \hat{t}}(x) - \sum_{i=1}^n h_{e_i}(x) c_i \right)^2 dx$$



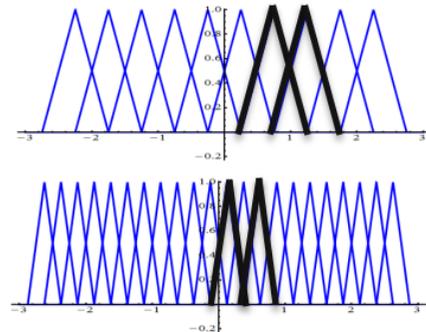
$$\sum c_i = 1$$



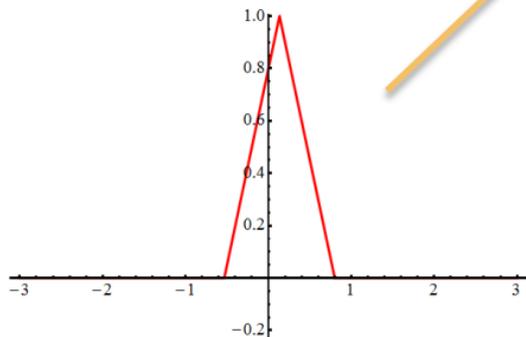
$$\operatorname{argmin}_{c, e \subset E} \iint_{\mathbb{R}^2} \left(h_{\hat{s}, \hat{t}}(x) - \sum_{i=1}^n h_{e_i}(x) c_i \right)^2 dx$$



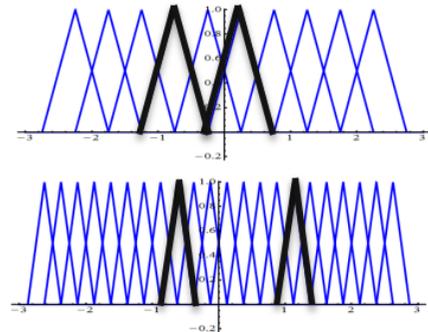
$$|e| = n$$



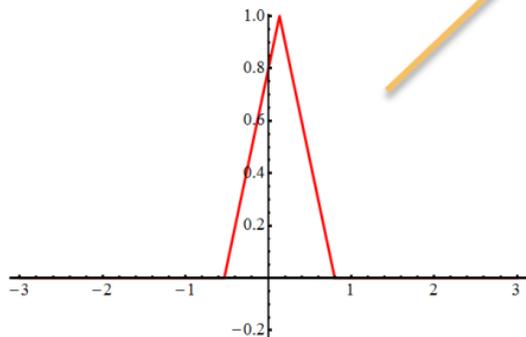
$$\operatorname{argmin}_{c, e \subset E} \iint_{\mathbb{R}^2} \left(h_{\hat{s}, \hat{t}}(x) - \sum_{i=1}^n h_{e_i}(x) c_i \right)^2 dx$$



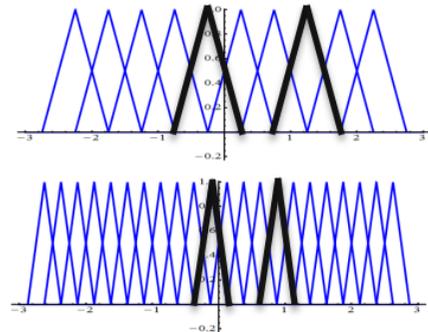
$$|e| = n$$

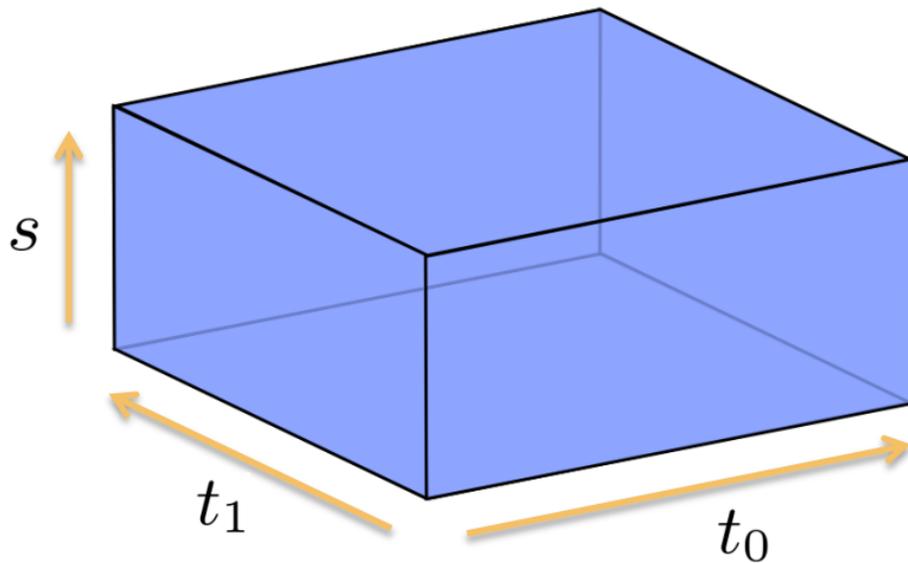


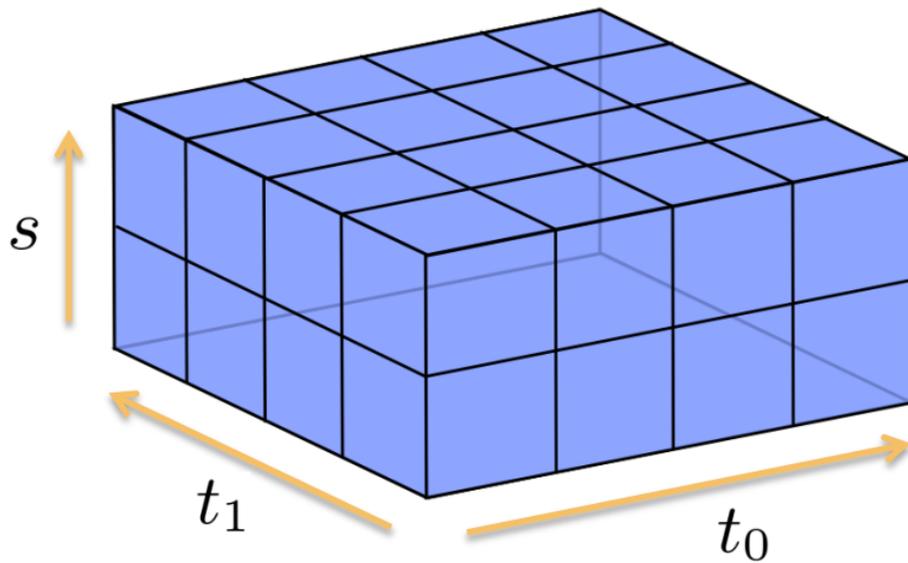
$$\operatorname{argmin}_{c, e \subset E} \iint_{\mathbb{R}^2} \left(h_{\hat{s}, \hat{t}}(x) - \sum_{i=1}^n h_{e_i}(x) c_i \right)^2 dx$$

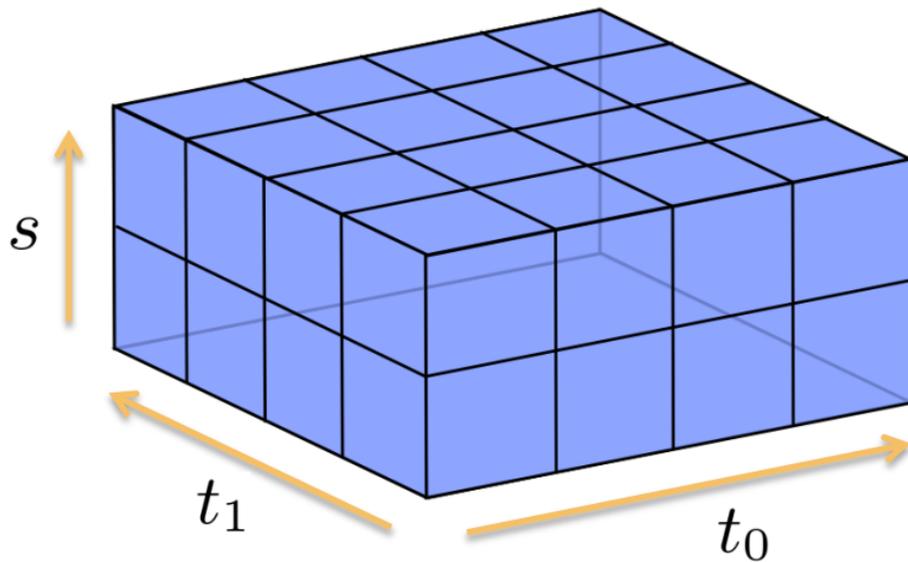


$$|e| = n$$

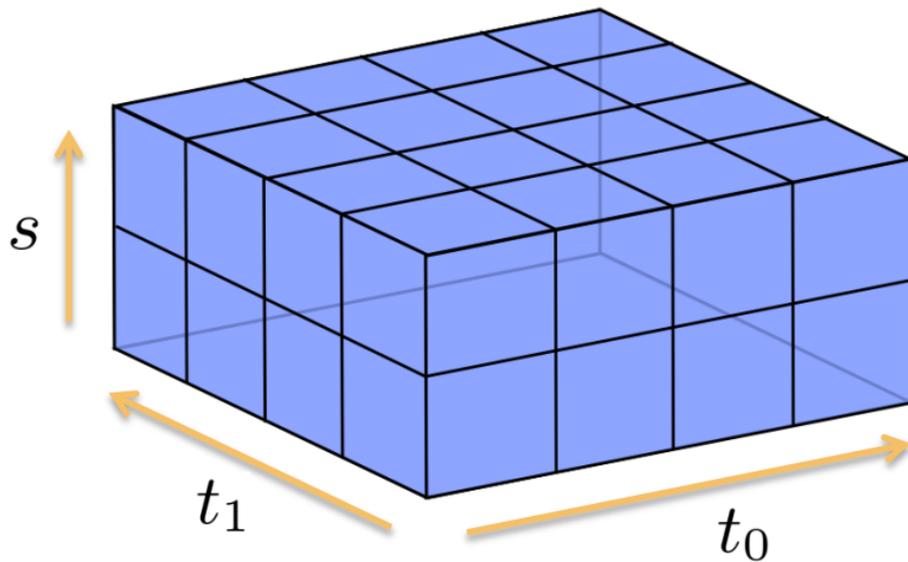






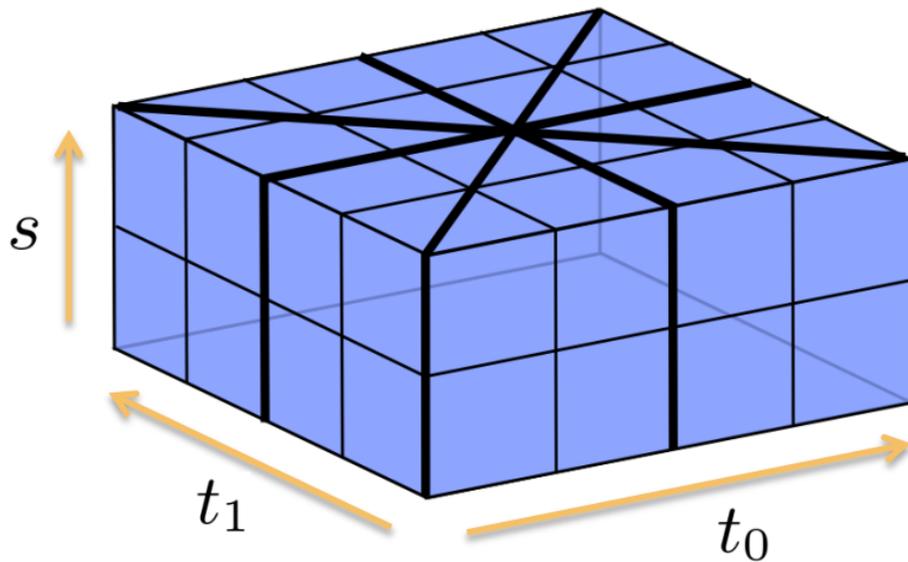


$$c_i(s, t) = \sum_j p_j(s, t) c_{ij}$$



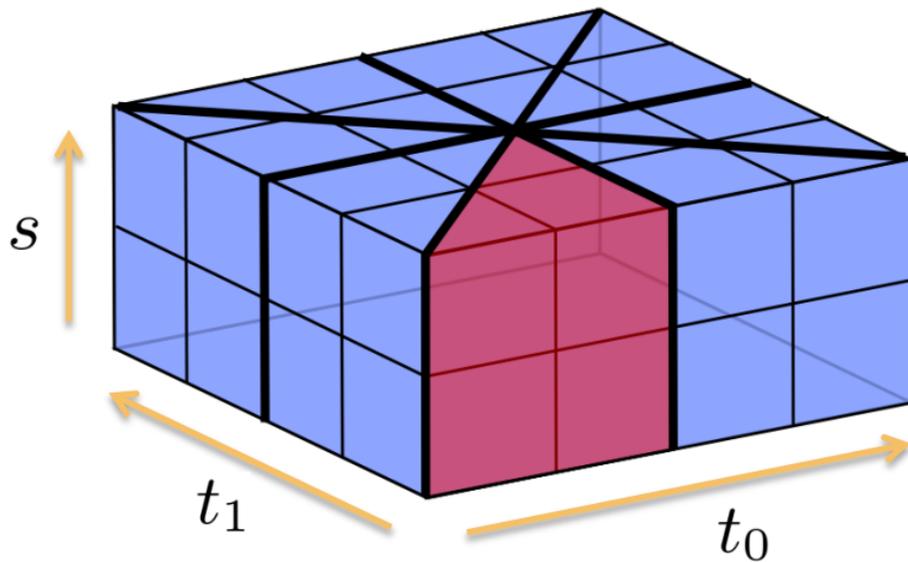
$$c_i(s, t) = \sum_j p_j(s, t) c_{ij}$$

$$p(s, t) = (1, t_0, t_1, s)$$



$$c_i(s, t) = \sum_j p_j(s, t) c_{ij}$$

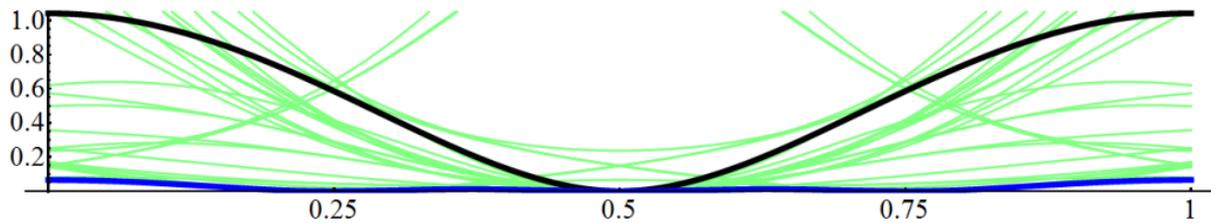
$$p(s, t) = (1, t_0, t_1, s)$$



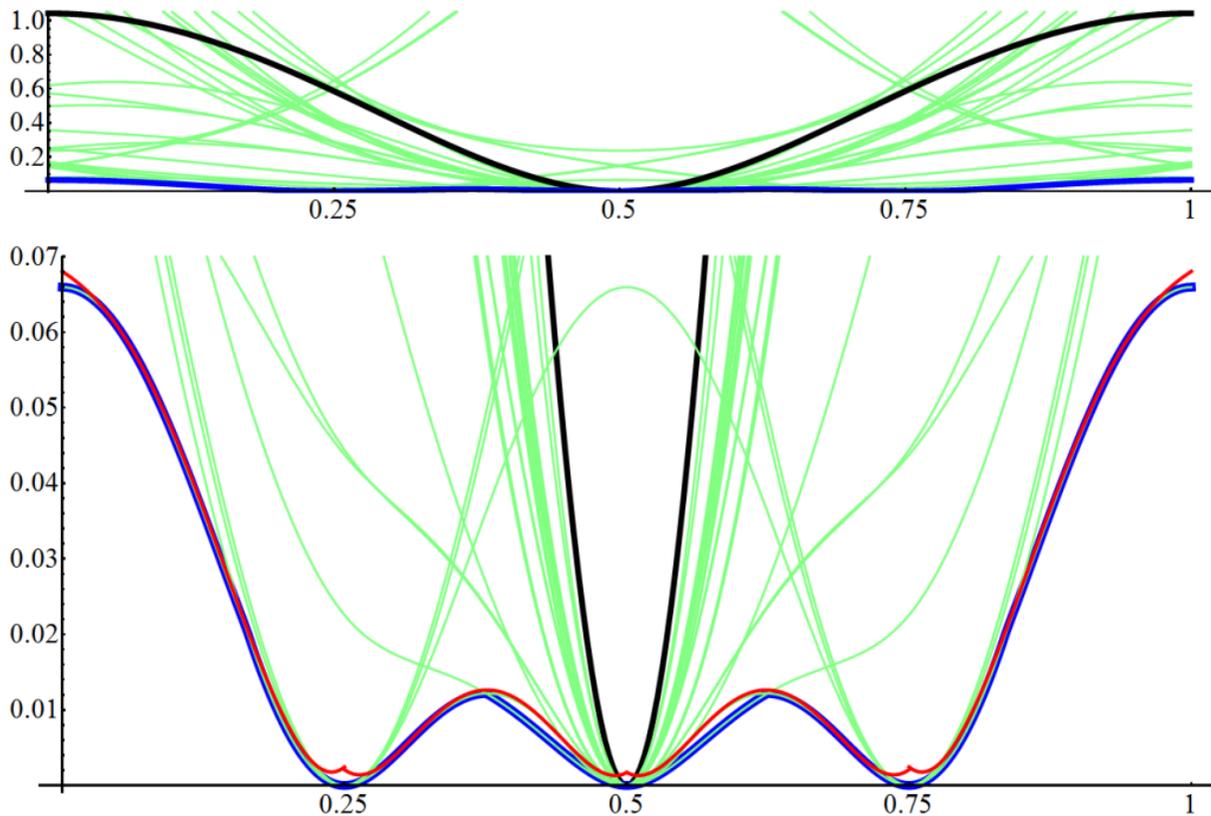
$$c_i(s, t) = \sum_j p_j(s, t) c_{ij}$$

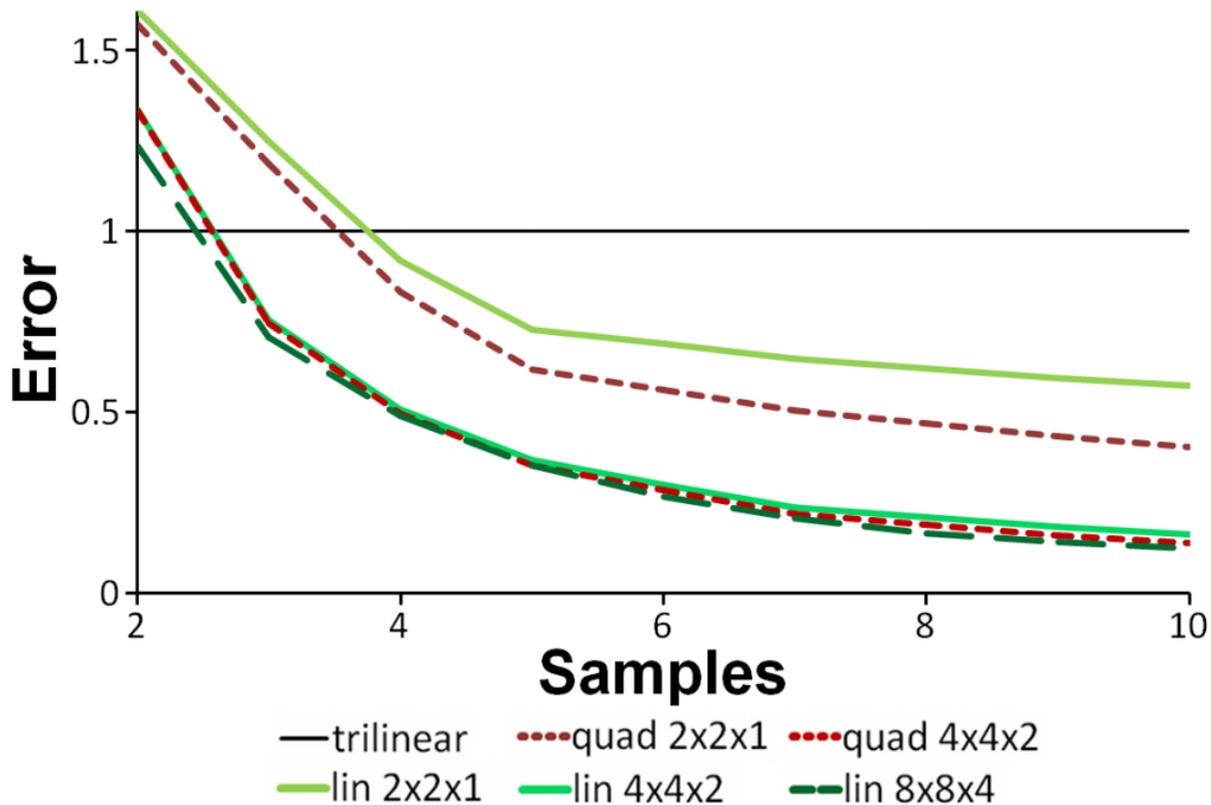
$$p(s, t) = (1, t_0, t_1, s)$$

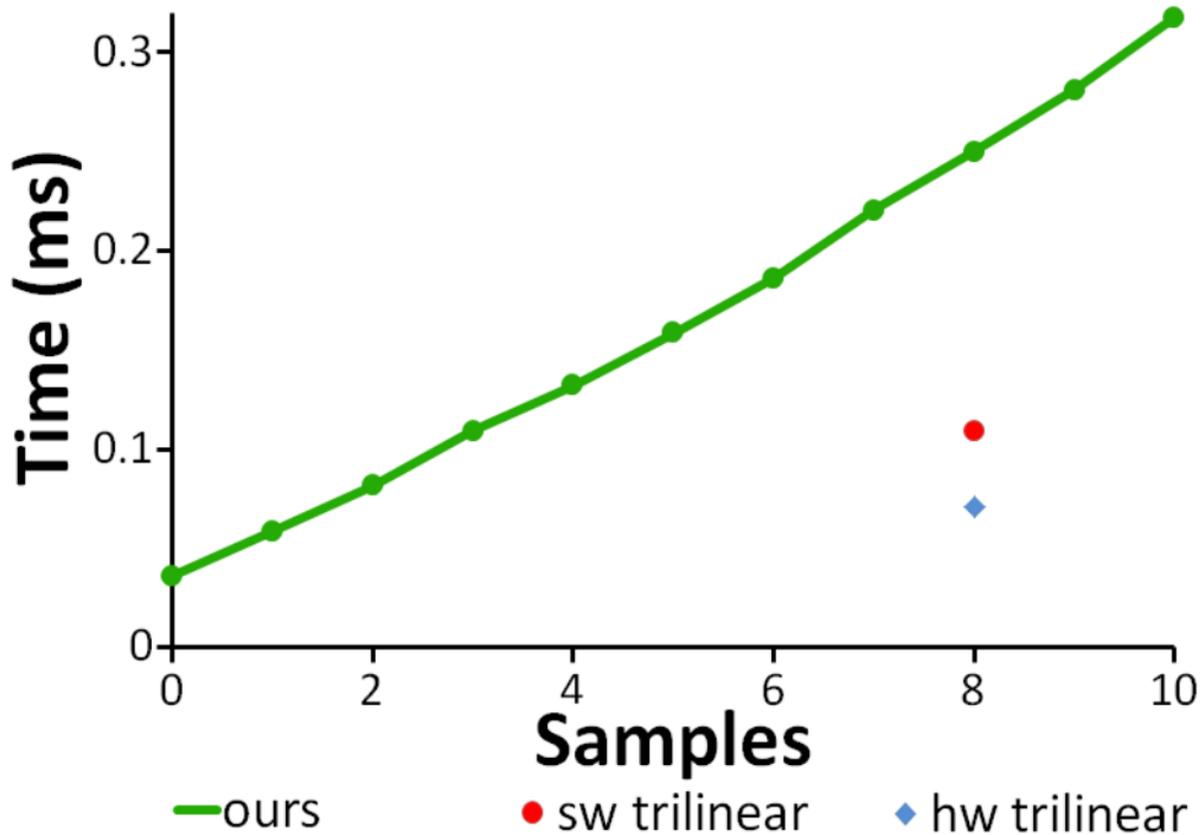
Fitting Error

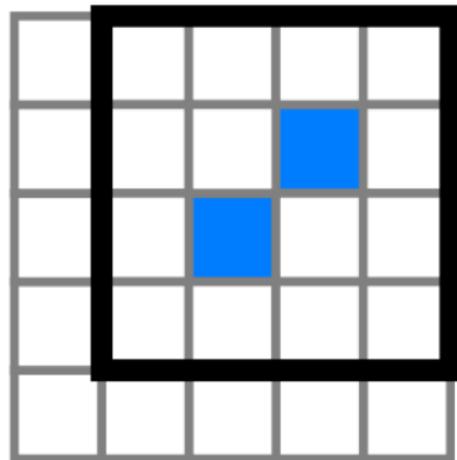
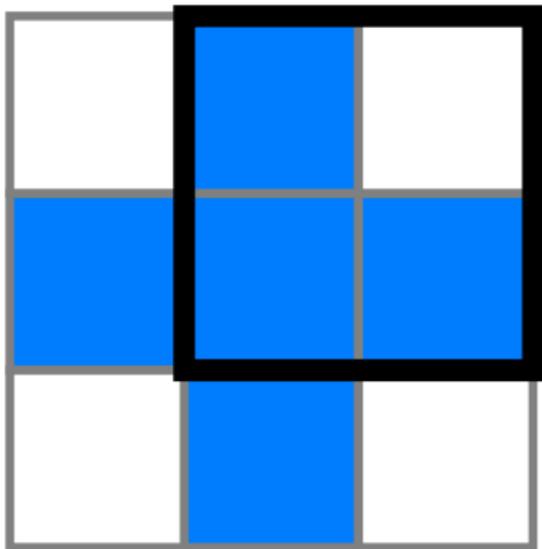


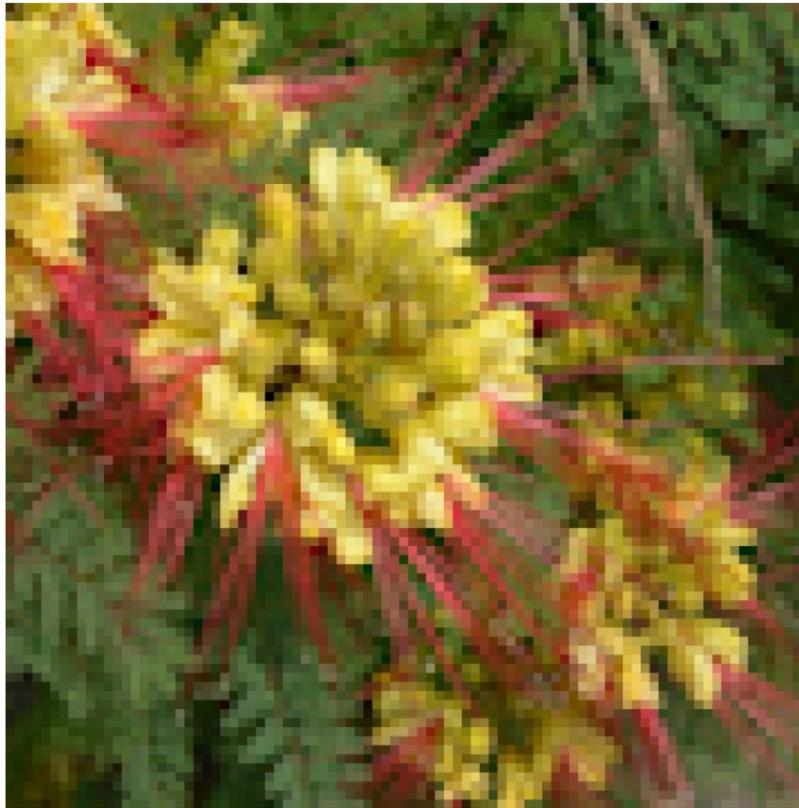
Fitting Error







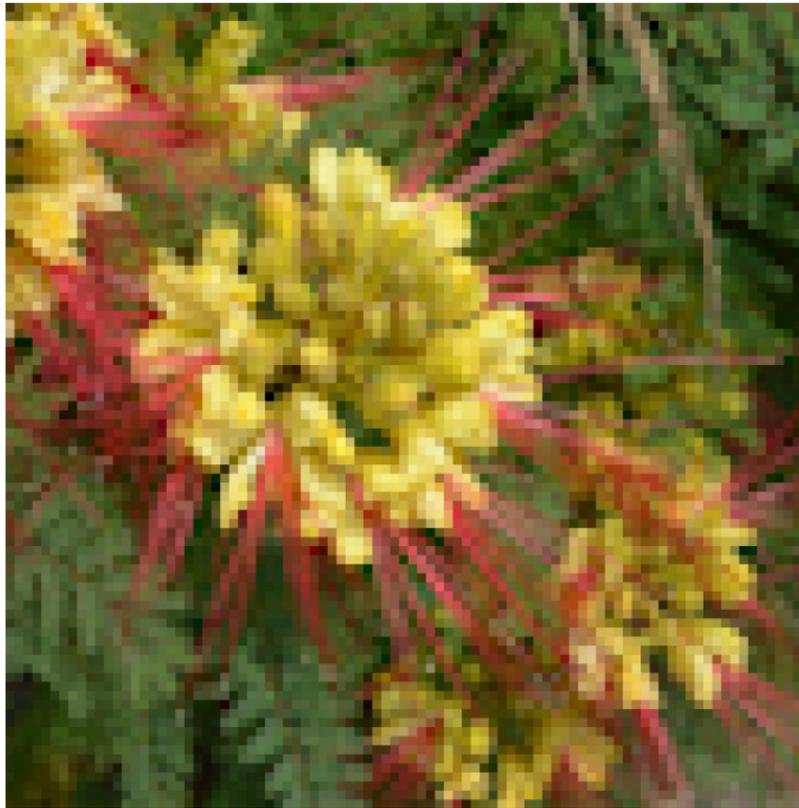




Exact



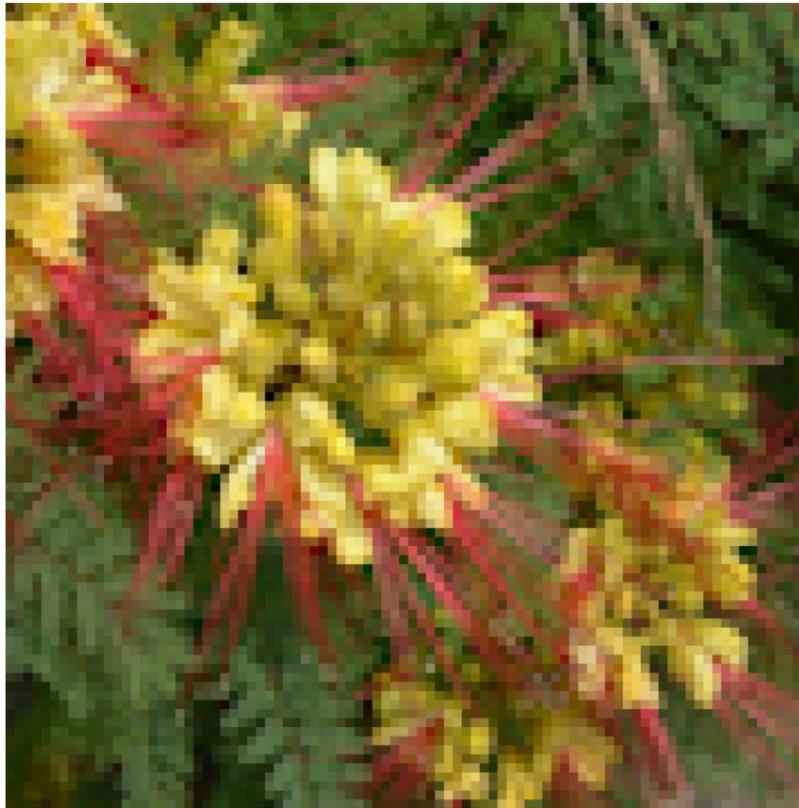
Trilinear



Exact



8 Samples



Exact



4 Samples



Exact



Trilinear



8 Samples



7 Samples



6 Samples



5 Samples

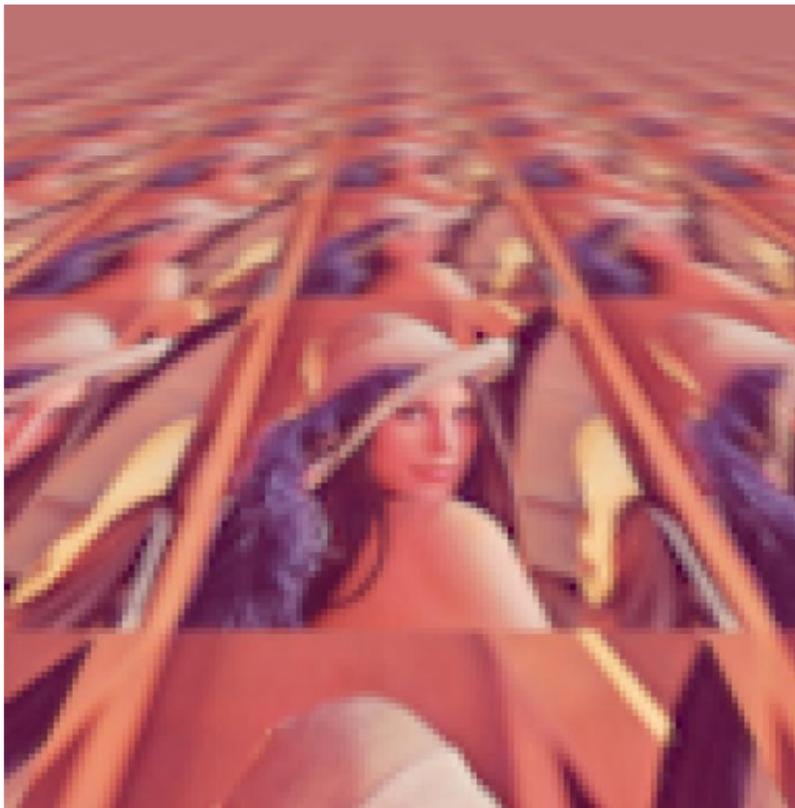


4 Samples



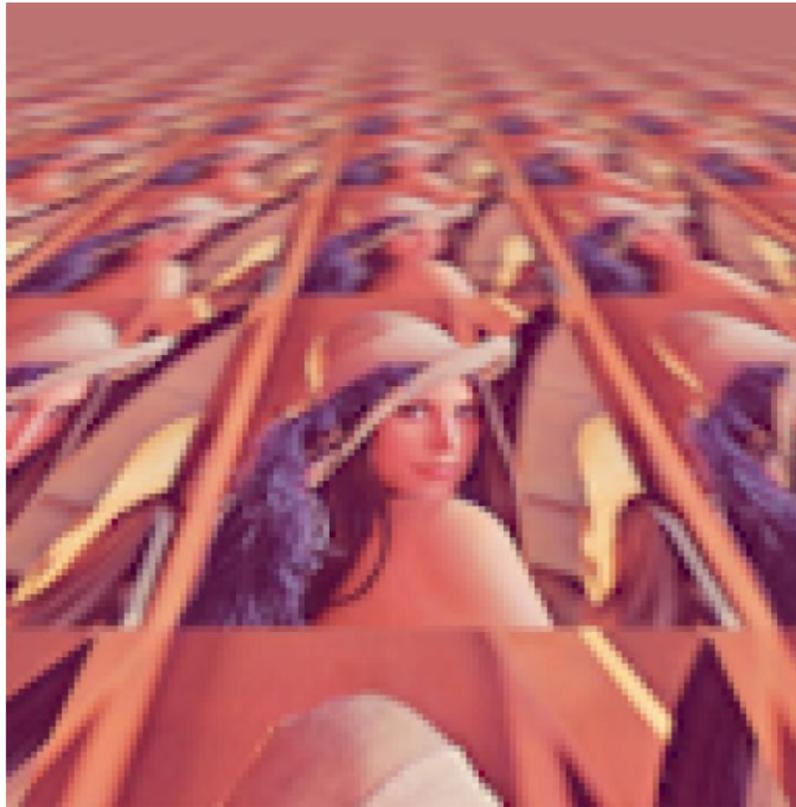
3 Samples

Isotropic Lánczos 2 Approximation

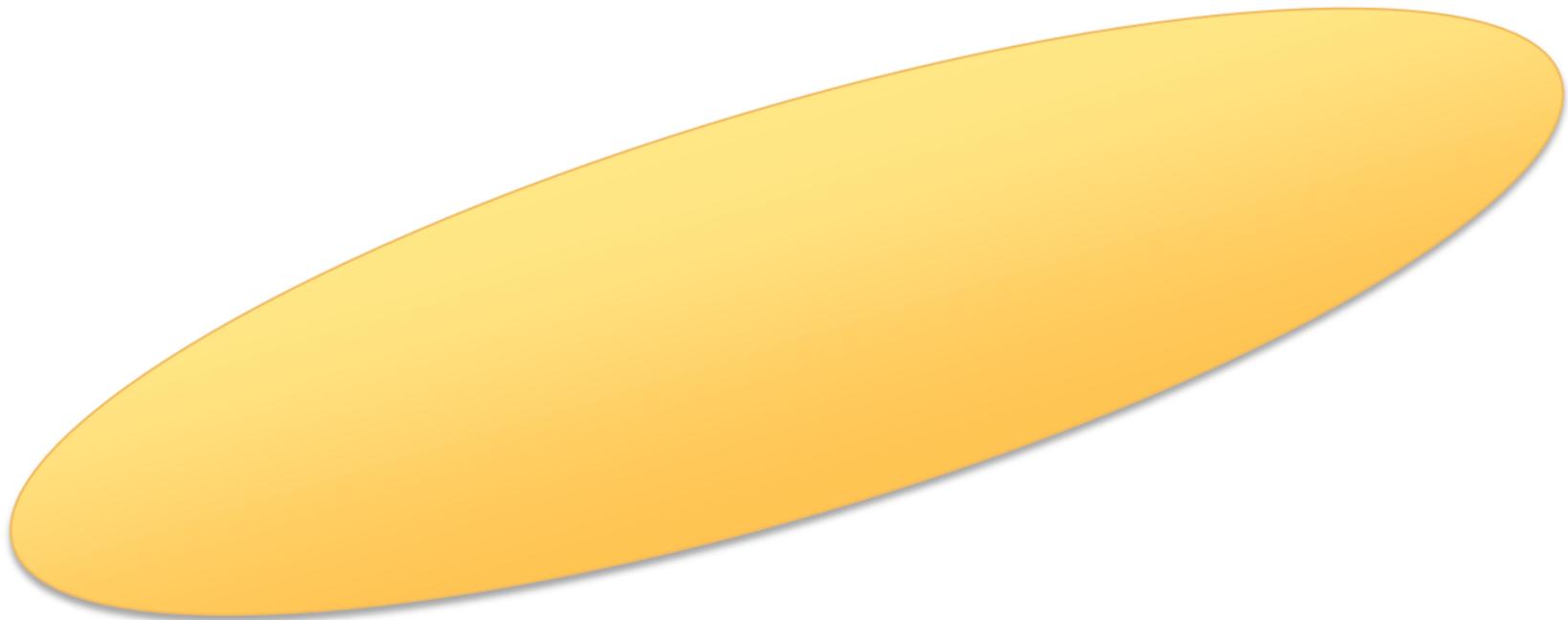


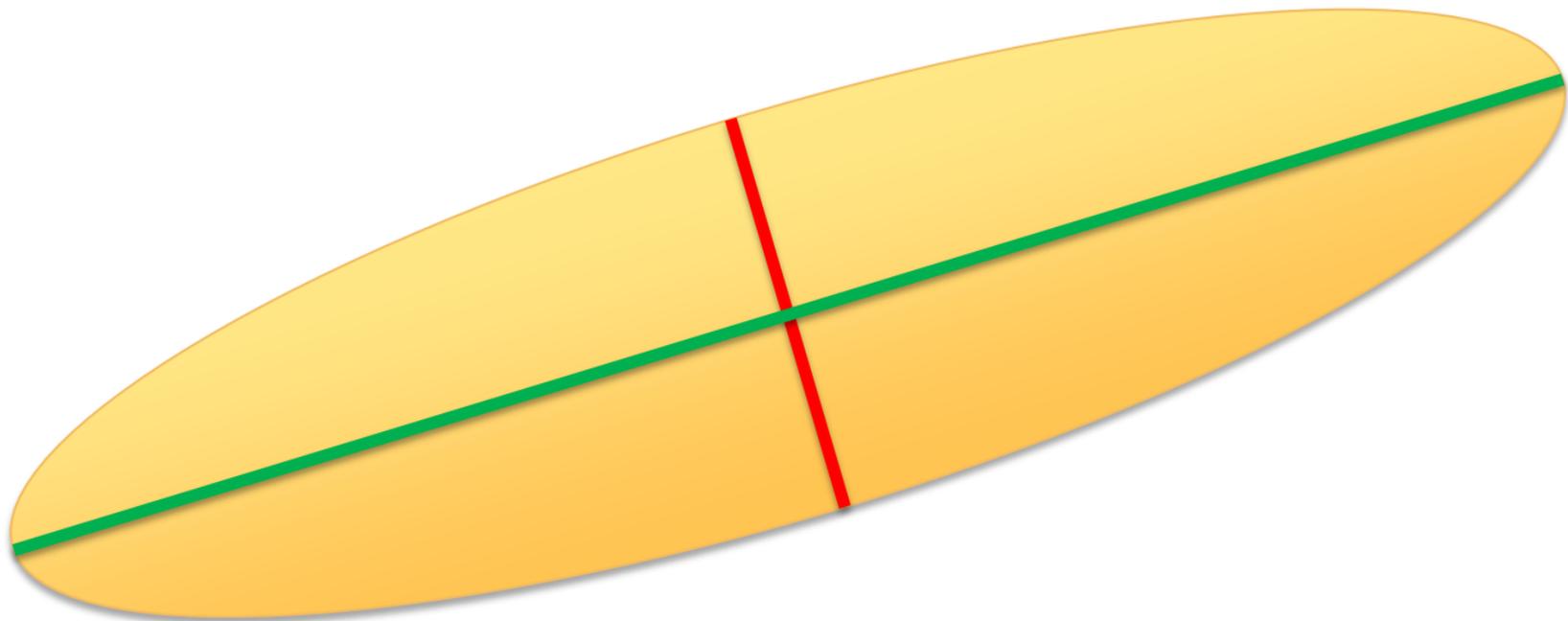
Trilinear

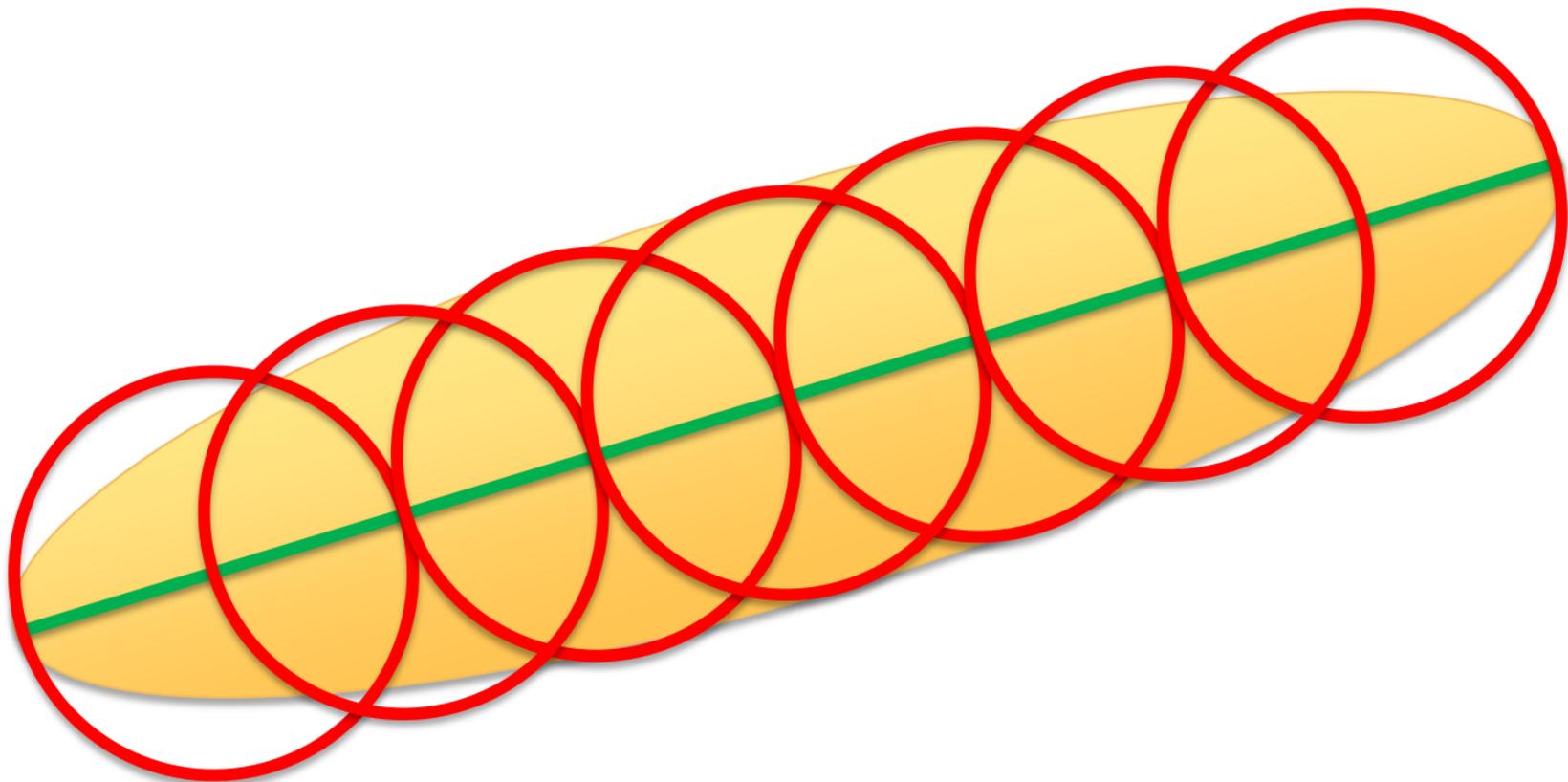
Isotropic Lánczos 2 Approximation

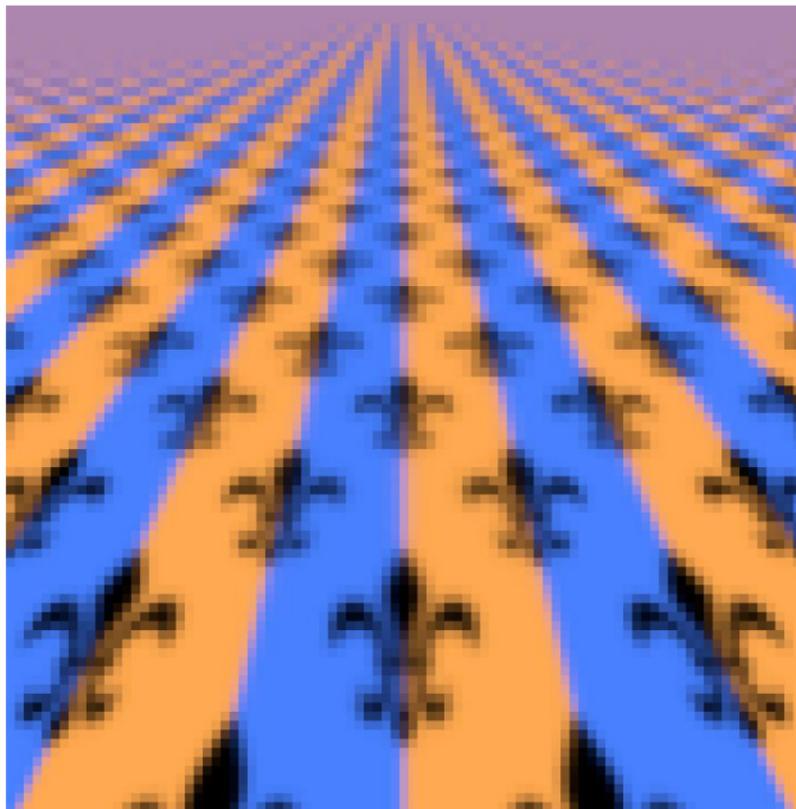


8 Samples

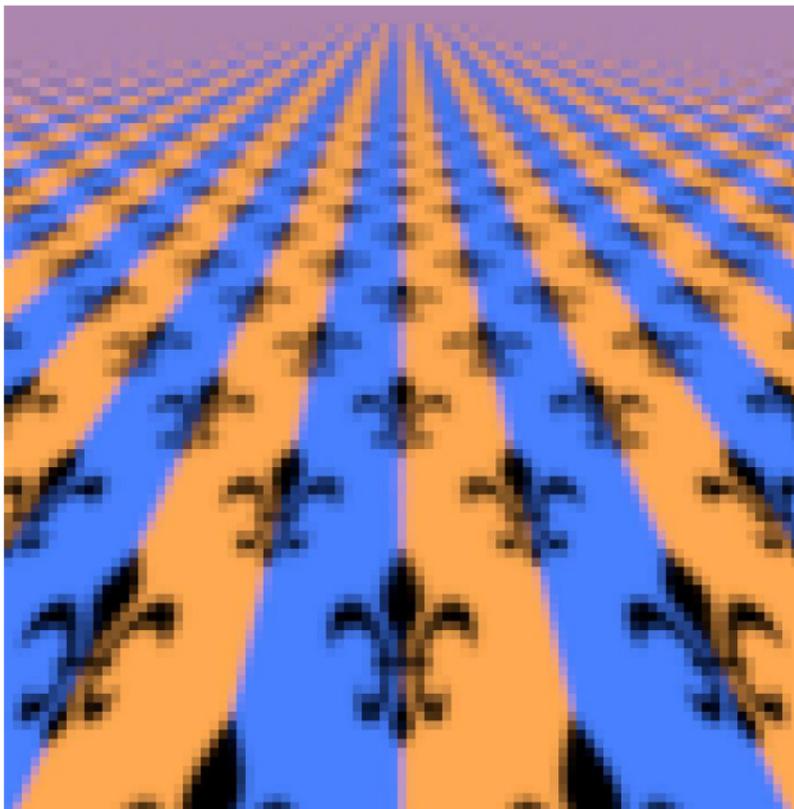




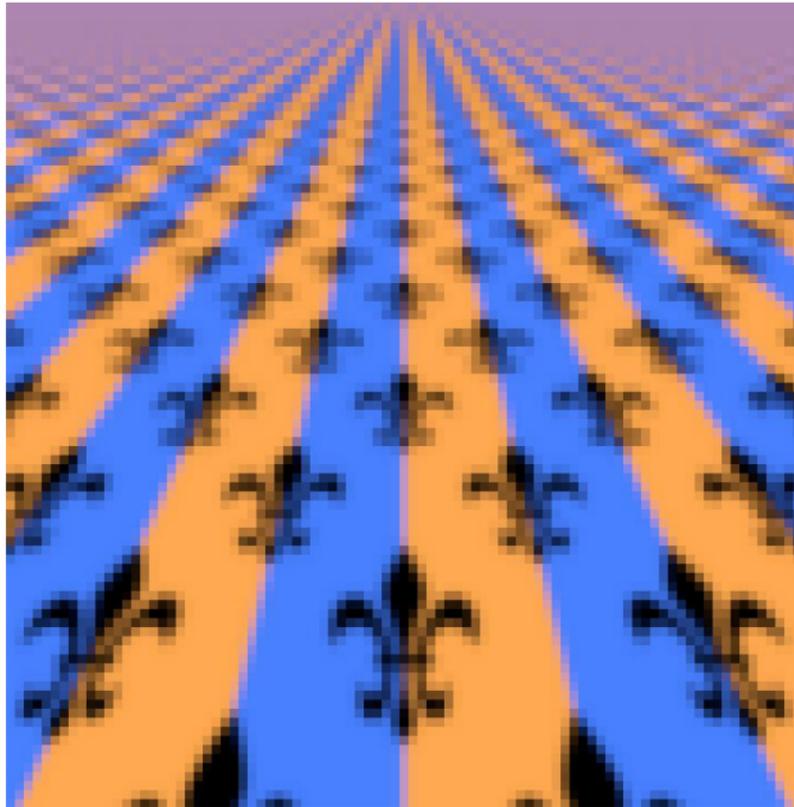




Feline



8 Samples with Feline



Exact

- Higher quality using less bandwidth
 - Scattered reads cost performance
- Approximate filters with few samples
 - Cost is only in preprocessing
- Small lookup tables
 - Easily fits in local memory
- GPU implementation
 - http://josiahmanson.com/research/cardinality_constrained/