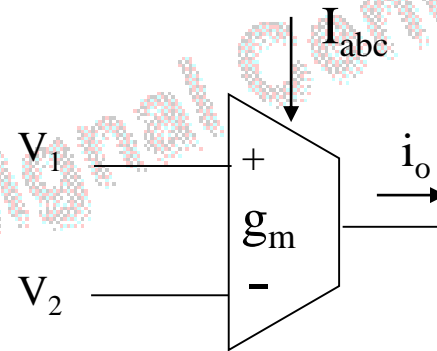


Nested G_m -C Compensation Amplifier.



Voltage Multistage Transconductance Amplifier Topologies for LV Power Supply.



- Good voltage gain can be obtained using cascode stages. But these stages are not amenable for LV power supply.

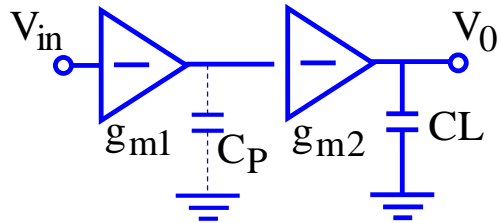


- Under LV conditions, high voltage can be obtained using cascade amplifiers. That is growing horizontally, rather than vertically.

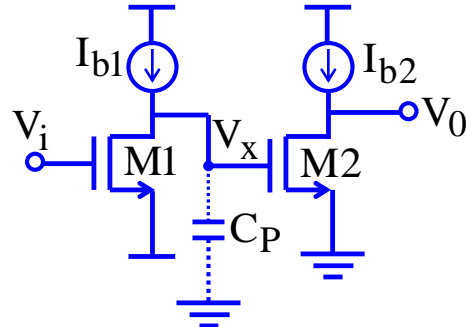


- Direct Cascade of simple (inverting) stages gives the required voltage gain without control of poles and zeroes.
- Dynamic behavior for optimal performance requires feedback (and feedforward) circuits.

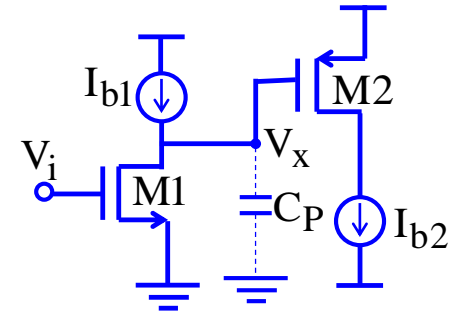
First Approach: Direct Cascade



Symbolic Representation



(a)



(b)

Two Possible Implementations

$$H(s) = \frac{V_0(s)}{V_{in}(s)} \cong \frac{+g_{m1}g_{m2} / C_p C_L}{1 + s \left(\frac{C_L}{g_{o2}} + \frac{C_p}{g_{o1}} \right) + \frac{C_p C_L}{g_{o1}g_{o2}} s^2}$$

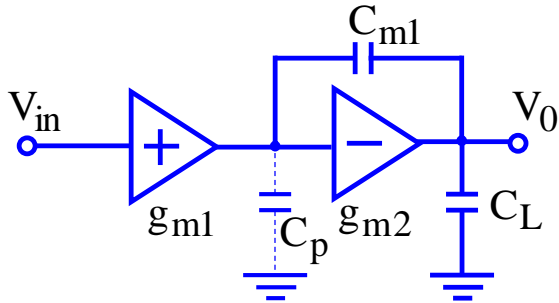
The poles are located at

$$\omega_{p1} = \frac{g_{o1}}{C_p}, \quad \omega_{p2} = \frac{g_{o2}}{C_L} \quad \text{☹️} \quad \text{i.e., 1 MHz and 10 MHz}$$

$$H(0) = \frac{g_{m1}g_{m2}}{g_{o1}g_{o2}} \quad \text{☺️}$$

How do you bring one pole close to the origin?

-Use feedback, i.e. **Miller effect**



Neglect C_p (i.e., $C_p \ll C_{m1}$)

$$H(s) = \frac{V_0(s)}{V_{in}(s)} = \frac{g_{m1}(g_{m2} - sC_{m1})/C_L C_{m1}}{s^2 + s(g_{01}(C_L + C_{m1})/C_L C_p + g_{m2}/C_L + g_{02}/C_L) + g_{01}g_{02}/C_L C_{m1}}$$

The poles locations are approximately at:

$$\omega_{p2} \cong (g_{m2} + g_{02})/C_L \quad \text{and} \quad \omega_{p1} \cong \left(\frac{g_{01}}{C_{m1}}\right) \frac{g_{02}}{g_{m2}} = \left(\frac{g_{01}}{C_{m1}}\right) \frac{1}{A_{V02}}$$

The good news is that: :

$$\omega_{p1} \ll \omega_{p2}$$

Good for stability

$$H(0) = g_{m1}g_{m2}/g_{01}g_{02} \quad \text{Large DC voltage gain}$$



The bad news is that a zero is at the RHP.

$$\omega_{z1} = \frac{g_{m2}}{C_{m1}}$$

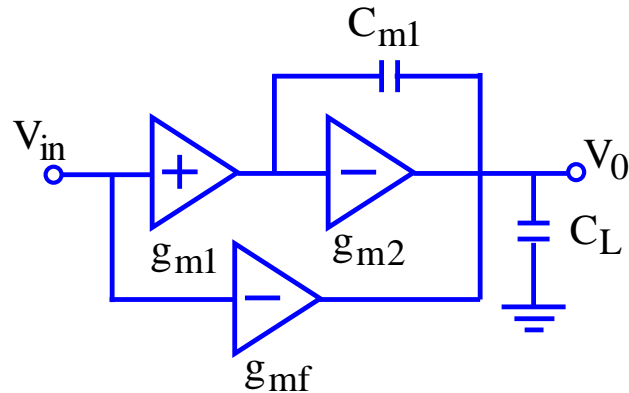


Now we will use a feedforward circuit to cancel the zero at the RHP.

This will impact the complexity and performance of the design. 😊

Recall that before applying the feedforward we had:

$$H(s) = \frac{V_0(s)}{V_{in}(s)} = \frac{g_{m1}(g_{m2} - sC_{m1})/C_L C_{m1}}{s^2 + s(g_{o1}(C_L + C_{m1})/C_L C_p + g_{m2}/C_L + g_{o2}/C_L) + g_{o1}g_{o2}/C_L C_{m1}}$$



No zero 😊

Now the corresponding H(s) becomes:

For $g_{mf} = g_{m1}$

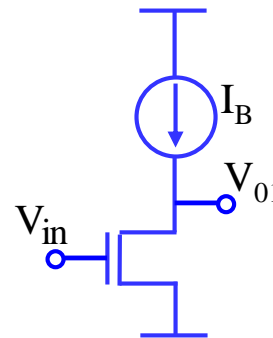
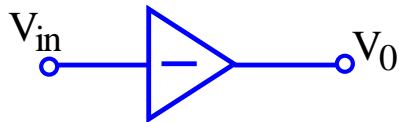
$$H(s) = \frac{V_o(s)}{V_{in}(s)} = \frac{-g_{m1}g_{m2}}{s^2 C_L C_{m1} + s(C_{m1}g_{m2} + C_L g_{o1}) + g_{o1}(g_{of} + g_{o2})}$$

Assume a dominant pole, then

$$\omega_{p1} \cong \frac{g_{o1}(g_{o2} + g_{of})}{g_{m2}C_{m1}} \quad ; \quad \omega_{p2} = \frac{g_{m2}}{C_L}$$

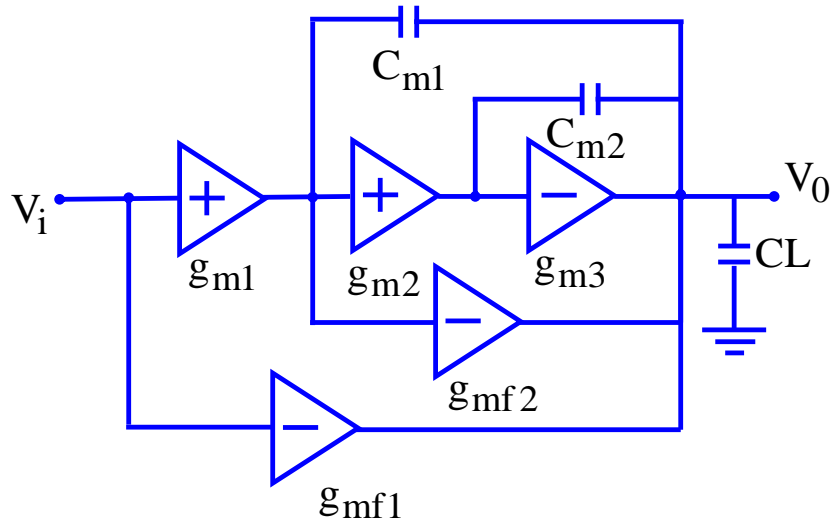
$$H(o) = A_{vo} = \frac{-g_{m1}g_{m2}}{g_{o1}(g_{o2} + g_{of})} \quad ; \quad GB \cong A_{vo}\omega_{p1} = \frac{g_{m1}}{C_{m1}}$$

$$\frac{\omega_{p2}}{\omega_{p1}} = \frac{g_{m2}g_{m2}C_{m1}}{C_L(g_{o2} + g_{of})g_{o1}} \quad ; \quad C_{m1} \geq C_L$$



Let us consider a higher-order system, i.e. 3rd order.

Nested G_m -C Compensation Amplifier.



Three-stage amplifier topology with NGCC

$$H(s) = \frac{V_0(s)}{V_i(s)} = \frac{g_{m1}g_{m2}g_{m3} + s g_{m1}(g_{mf2} - g_{m2})C_{m2} + (g_{mf1} - g_{m1})C_{m1}C_{m2}s^2}{g_{01}g_{02}g_{03} + s g_{m2}g_{m3}C_{m1} + s^2(g_{m3} + g_{mf2} - g_{m2})C_{m1}C_{m2} + s^3 C_L C_{m1}C_{m2}}$$

By making $g_{mf1} = g_{m1}$ and $g_{mf2} = g_{m2}$,

$$H(s) = \frac{V_0(s)}{V_i(s)} = \frac{-g_{m1}g_{m2}g_{m3}}{g_{01}g_{02}g_{03} + s g_{m2}g_{m3}C_{m1} + s^2 g_{m3}C_{m1}C_{m2} + s^3 C_L C_{m1}C_{m2}}$$

Observe the regularity and simplicity of the reduced expression

This 3rd order H(s) assuming a dominant pole can be written as

$$H(s) = \frac{-A_0}{\left(1 + s \frac{A_0}{f_1}\right) \left(1 + \frac{s}{f_2} + \frac{s^2}{f_2 f_3}\right)}$$

$$A_0 = \frac{g_{m1} g_{m3} g_{m2}}{g_{o1} g_{o3} g_{o2}} \quad \text{and} \quad f_1 = GB = \frac{g_{m1}}{C_{m1}}$$

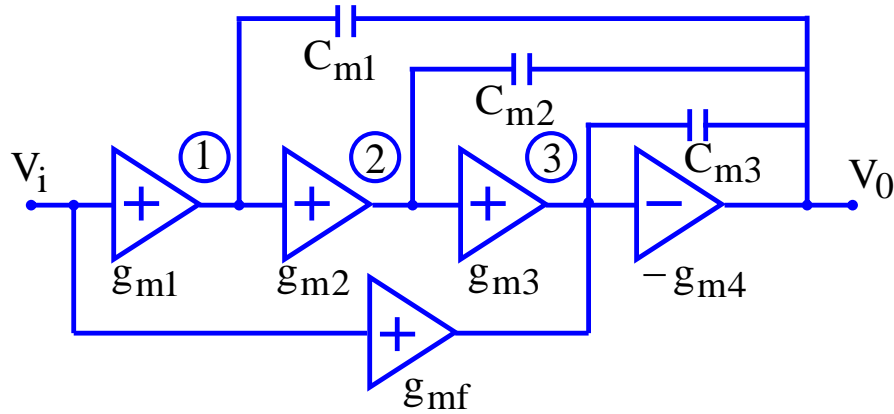
$$f_2 = \frac{g_{m2}}{C_{m2}}, \quad f_2 f_3 = \frac{g_{m2} g_{m3}}{C_{m2} C_L}; \quad f_i = \frac{g_{mi}}{C_{mi}}$$

Note that the dominant pole is located at

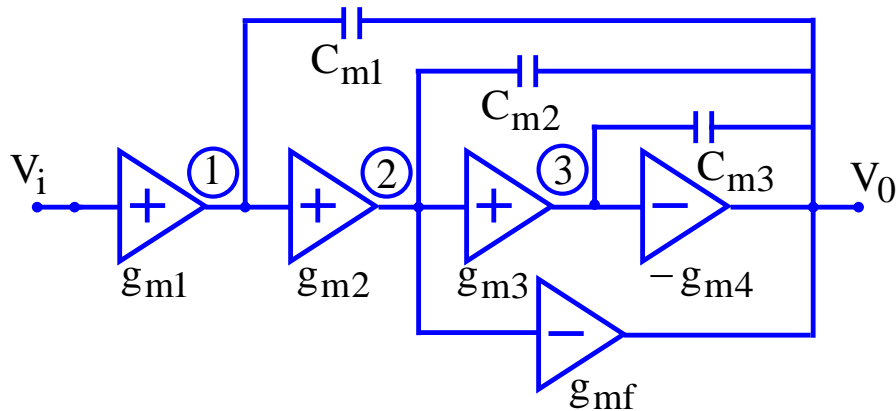
$$P_1 = \frac{f_1}{A_0} = \frac{\frac{g_{m1}}{C_{m1}}}{\frac{g_{m1} g_{m2} g_{m3}}{g_{o1} g_{o2} g_{o3}}} = \frac{g_{o1} g_{o2} g_{o3}}{g_{m2} g_{m3} C_{m1}} = \left(\frac{g_{o1}}{C_{m1}}\right) \frac{1}{A_{v0_2} A_{v0_3}}$$

Multipath Nested Miller Compensation Technology

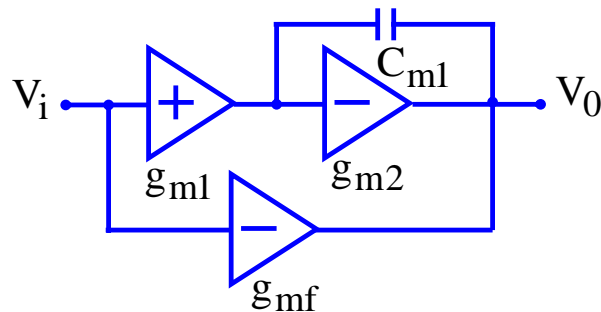
Potential Feedforward Schemes: An Amplifier Topologies Re-Visit.



(a) Multipath nested miller compensation topology.
FF : NMC

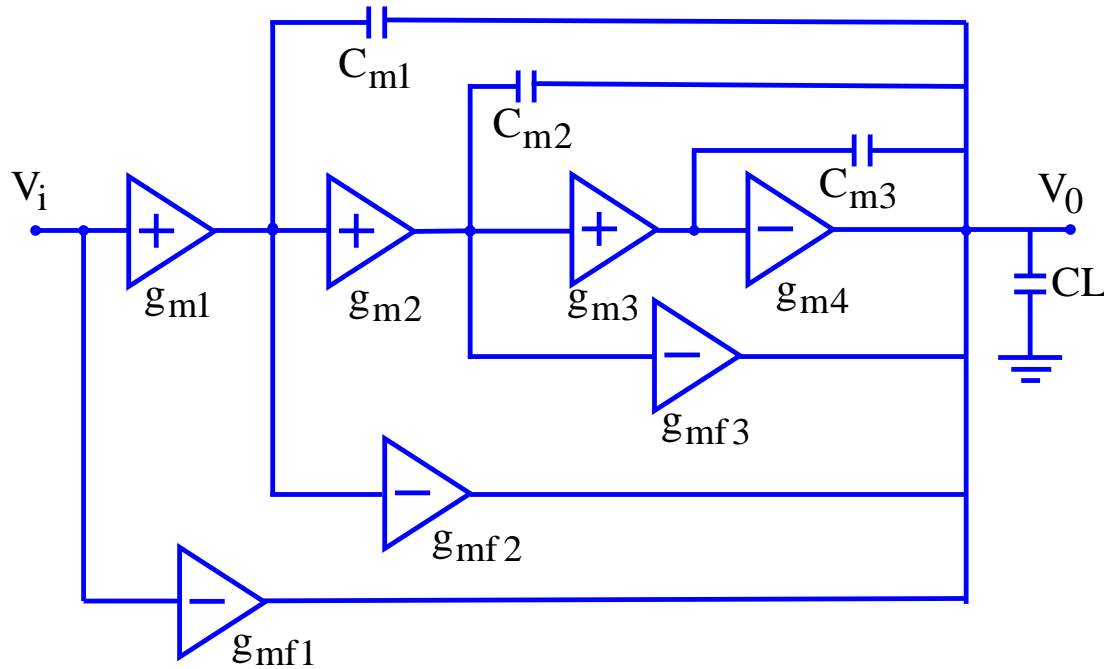


(b) An abstract model for the amplifier proposed by Castello, et.al.



(c) The amplifier with multipath miller zero cancellation.

Let Us Now Compare Several Four-Order Topologies



Four stage amplifier topology with NGCC (Fan You et al)

$$f_1 < f_2 < f_3 \leq f_4, \quad f_1 = GB$$

$$f_4 > \frac{f_2}{1 - f_2/f_3}$$

- Power Consumption: $P = (V_{dd} - V_{ss}) \sum_1^n I_i$

$$P = (V_{DD} - V_{ss}) I_n \left[1 + \sum_{i=1}^{n-1} \frac{\alpha_i f_i}{f_n} \right], \quad \alpha_i = \frac{C_{mi}}{C_L}, \quad \alpha_i f_i = \frac{g_{mi}}{C_L}$$

I_n and f_n are current and frequency normalization factors, respectively.

$$H(s) = \frac{-A_0}{\left(1 + \frac{s}{P_1}\right) (1 + a_1 s + a_2 s^2 + a_3 s^3)}$$

$$P_1 = \frac{GB}{A_0}$$

$$a_1 = \frac{1}{f_2}, \quad a_2 = \frac{1}{f_2 f_3}, \quad a_3 = \frac{1}{f_2 f_3 f_4}$$

$$\frac{1}{f_2 f_3} = \frac{C_{m2} C_{m3}}{g_{m2} g_{m3}}, \quad \frac{1}{f_i} = \frac{C_{mi}}{g_{mi}}$$

Comparison of Several Topologies.

$$\frac{V_0(s)}{V_i(s)} = -A_0 \frac{1 - b_1s - b_2s^2 - b_3s^3}{(1 + s/P_1)(1 + a_1s + a_2s^2 + a_3s^3)}, \quad k_i = \frac{g_{mi}}{g_{oi}}, i = 1,3 \quad \text{and} \quad f_i = \frac{g_{mi}}{C_{mi}}$$

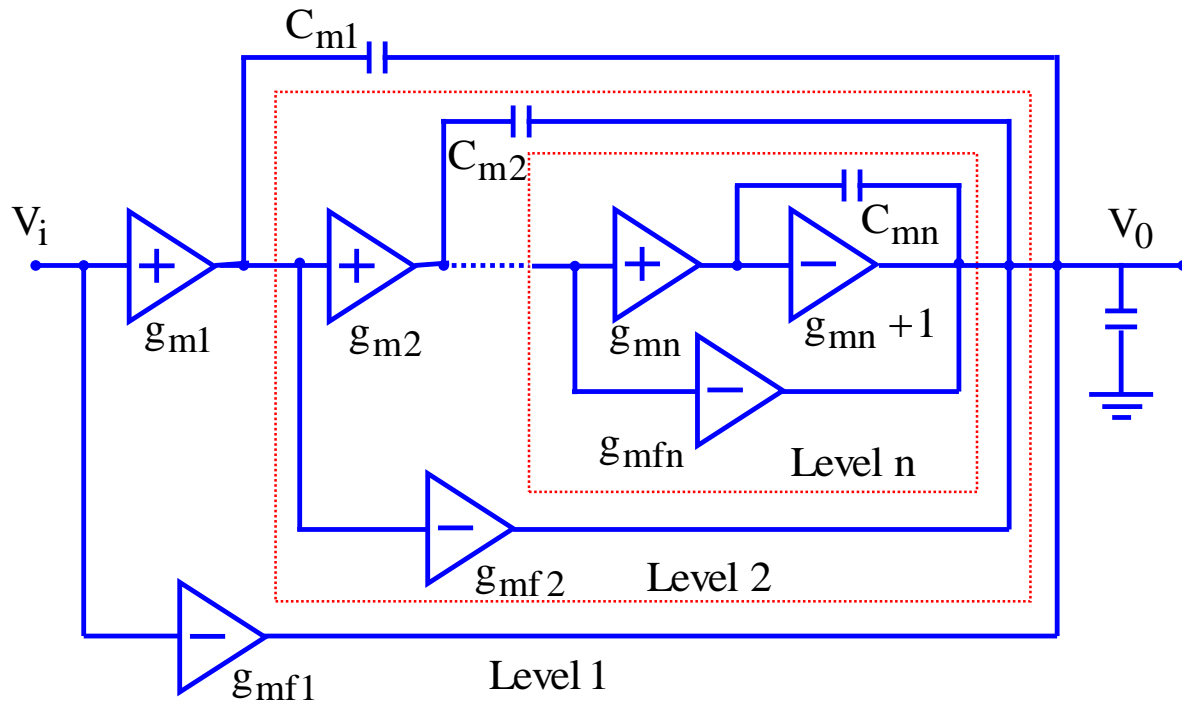
Where

$$A_0 = k_1k_2k_3k_4, \quad P_1 = \frac{f_1}{A_0} = \frac{GB}{A_0}$$

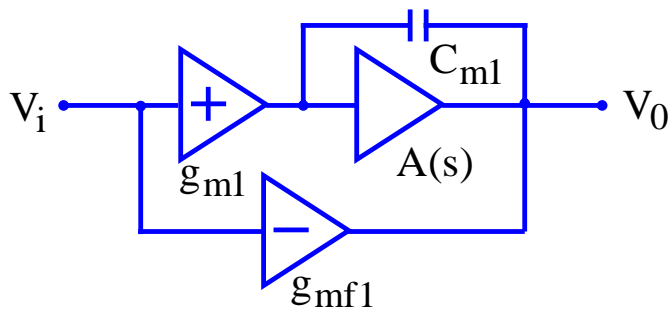
Comparison of Polynomial Coefficients for Four Stage NMC and NGCC Amplifier.

				Design
P_h(s)	a₁	a₂	a₃	
NMC	$\frac{(g_{m4}C_{m2} - g_{m2}C_{m3})}{g_{m2}g_{m4}}$	$\frac{(g_{m4} - g_{m2} - g_{m3})C_{m2}C_{m3}}{g_{m2}g_{m3}g_{m4}}$	$\frac{C_{m2}C_{m3}C_L}{g_{m2}g_{m3}g_{m4}}$	← Complex
NGCC	$\frac{C_{m2}}{g_{m2}}$	$\frac{C_{m2}C_{m3}}{g_{m2}g_{m3}}$	$\frac{C_{m2}C_{m3}C_L}{g_{m2}g_{m3}g_{m4}}$	← Simple
Z(s)	b₁	b₂	b₃	
NMC	$\frac{C_{m3}}{g_{m4}}$	$\frac{C_{m2}C_{m3}}{g_{m3}g_{m4}}$	$\frac{C_{m1}C_{m2}C_{m3}}{g_{m2}g_{m3}g_{m4}}$	
NGCC	0	0	0	

Nested G_m -C Compensation (NGCC) N^{th} -Order

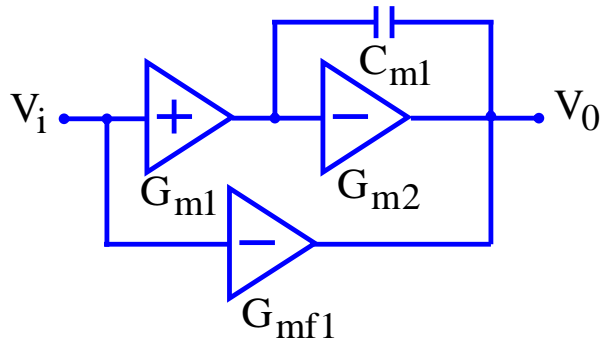


Conceptual multistage amplifier topology with NGCC.

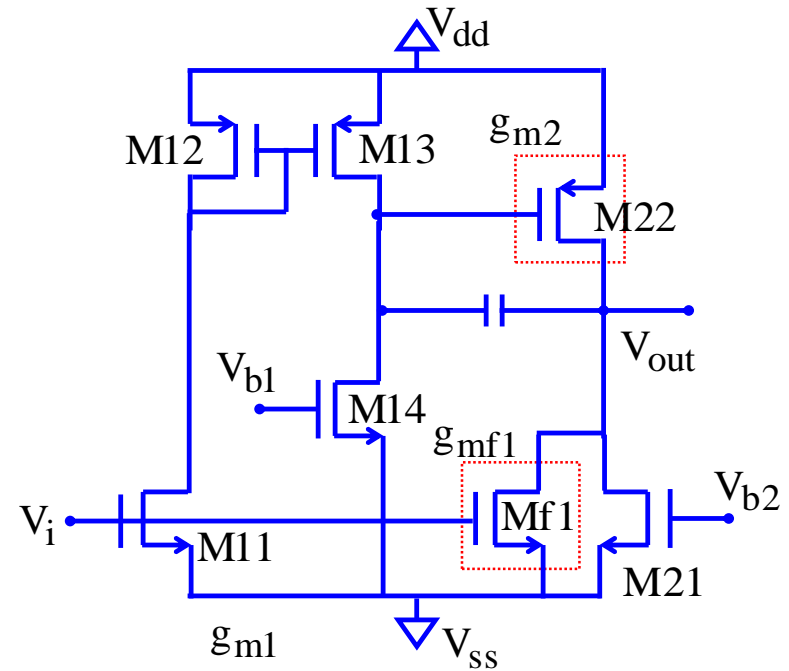


Abstract model.

How to Implement a Positive G_m ?



(a) Representation



(b) Transistor Level

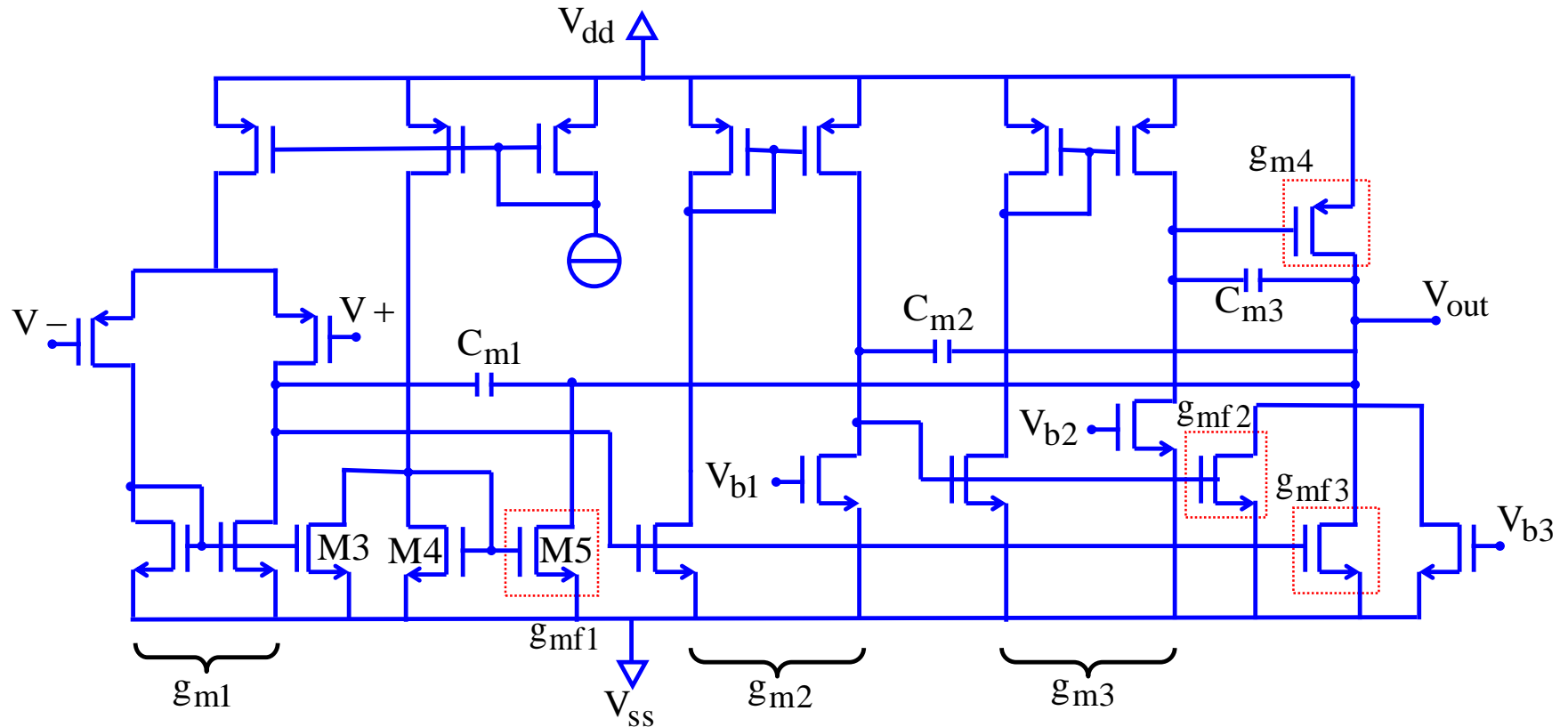
$$G_{m1} \Rightarrow M11 - M14, \quad g_{mM11} = g_{m1}$$

$$G_{m2} \Rightarrow M21 - M22, \quad g_{mM22} = g_{m2}$$

$$G_{mf1} \Rightarrow Mf1$$

- If $G_{m2} > G_{mf1}$, $M22$ current $>$ $Mf1$ current, then add $M21$ to provide additional current.
- If $G_{m2} < G_{mf1}$, Remove $M21$ and add a PMOS transistor in parallel to $M22$.

Design Example of a Four-Stage Amplifier



Four stage operational amplifier with NGCC topology

- The dominant pole f_1 is determined by GB
- Phase margin (ϕ_m) is mainly determined by the high frequency poles

- The location of higher-order poles not only influence on the ϕ_m , but also in settling time and power consumption.
- For specification requiring $A_o > 80$ dB, a four-stage ($n = 4$) is usually required
- Stability considerations for $n = 4$ impose

$$f_4 > \frac{f_2}{1 - f_1 / f_3} \quad ; \quad f_1 = GB$$

$$f_1 < f_2 < f_3 \leq f_4$$

$$H(s) = \frac{V_o(s)}{V_{in}(s)} = \frac{-A_o}{\left(1 + \frac{A_o}{GB} s\right) \left(1 + \frac{s}{f_2} + \frac{s^2}{f_2 f_3} + \frac{s^3}{f_2 f_3 f_4}\right)}$$

$$\frac{1}{f_i} = \frac{C_{mi}}{g_{mi}} \quad , \quad i = 1, \dots, 4$$

Design Approach

Step 1. Determine f_1 based on **GB**

$$f_1 = \text{GB}$$

Step 2. Determine f_2 based on **Phase Margin**

$$\phi_m = 90^\circ - \tan^{-1} \left(\frac{\text{GB}}{f_2} \left(\frac{1 - \text{GB}^2 / f_3 f_4}{1 - \text{GB}^2 / f_2 f_3} \right) \right) \approx 90^\circ - \tan^{-1} \left(\frac{\text{GB}}{f_2} \right)$$

Example:

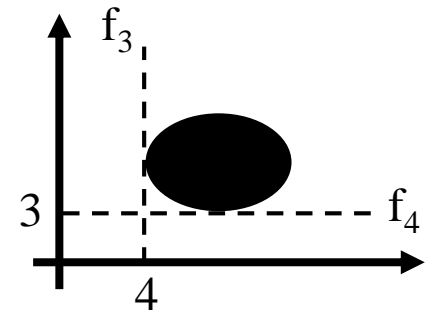
$$f_2 = 2 \text{ GB}, f_3 > f_2, f_4 > f_2 \rightarrow \phi_m \cong 60^\circ$$

However, this does not guarantee small settling time

Design Approach

Step 3. Determine f_3, f_4 based on **settling time** and **power**

$$H(s) = \frac{A_o}{\left(1 + \frac{A_o s}{f_1}\right) \left(1 + \frac{s}{f_2} + \frac{s^2}{f_2 f_3} + \frac{s^3}{f_2 f_3 f_4}\right)}$$



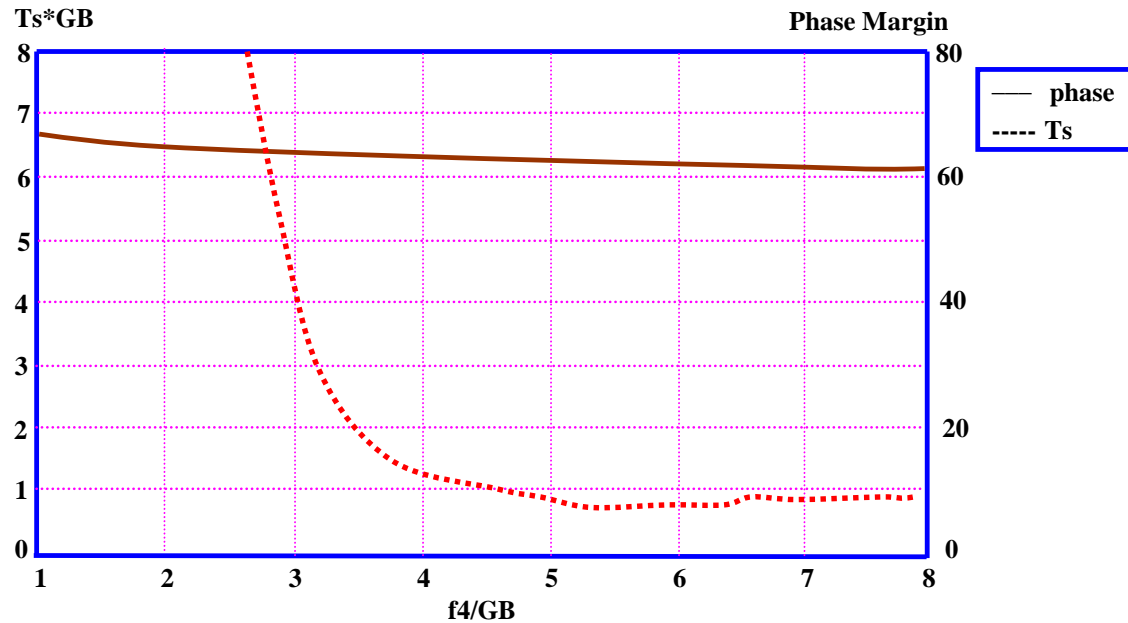
a. Sweep f_3 and f_4 **Ts?** (settling time)

Numerical Analysis (e.g. **MATLAB**)

b. Select a set of (f_3, f_4) with desired power and settling time

What is the effect of f_4/GB ?

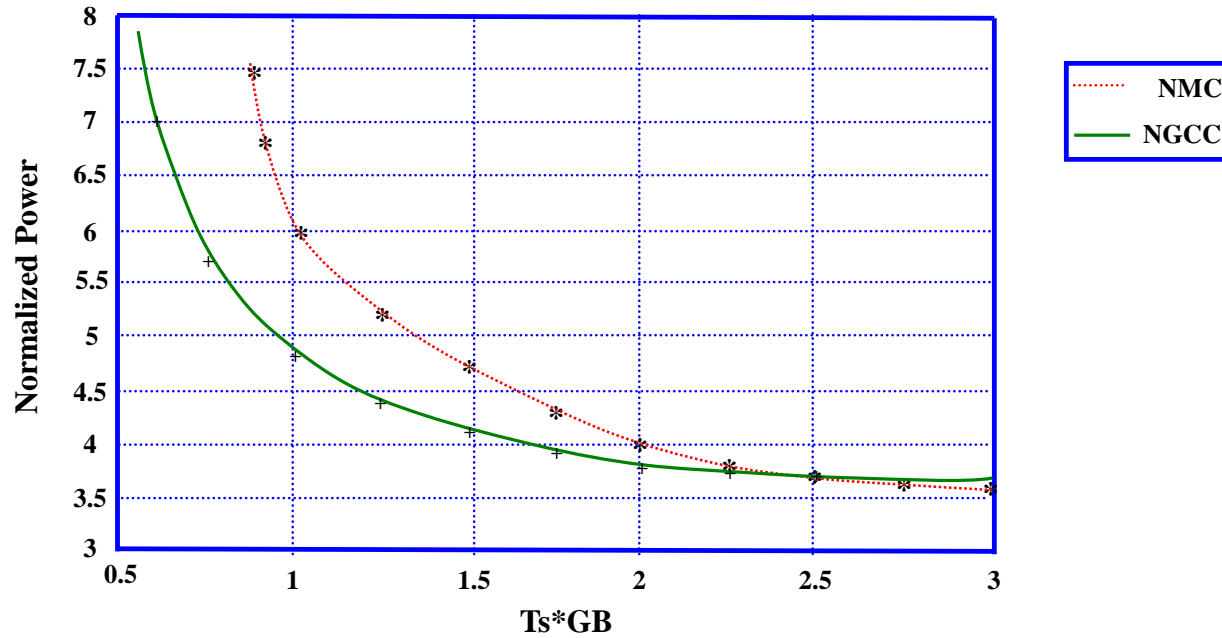
How far should one push f_4 ?



The phase margin and normalized settling time ($TsGB$) of an NGCC amplifier vs. f_4/GB .

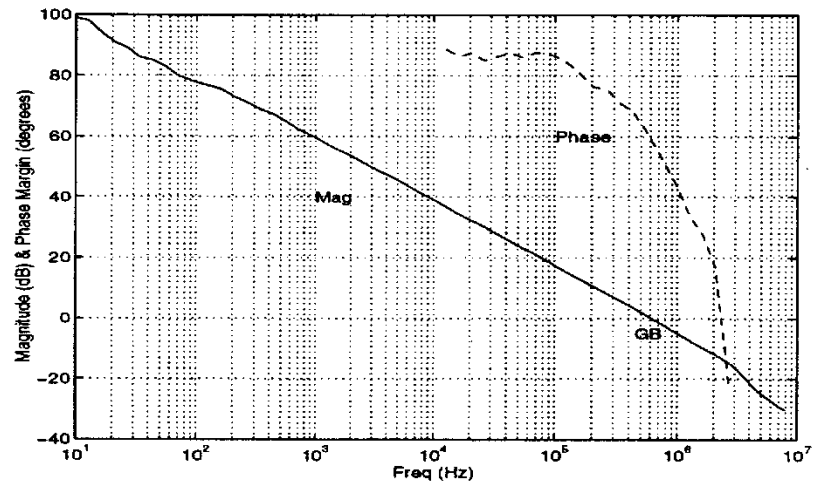
- Trade-off between phase margin versus setting time.

How do the Two Topologies Compare for Power Consumption?

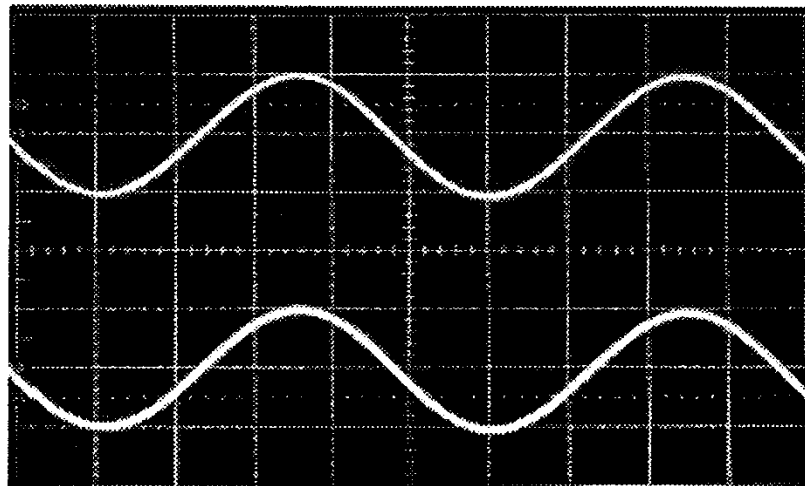


The normalized power consumption of the NGCC and the NMC amplifiers as a function of the normalized settling time.

More Experimental Results.



Measured frequency response of 4-stage NGCC amplifier

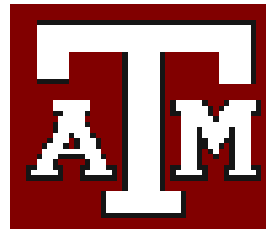


Measured 1.0V_{p-p} 100 KHz sin-wave at input and output nodes of a unity follower.

Measured Performance of the 4-Stage NGCC Op Amp.

Power Consumption	0.68mW	1.40mW
DC Gain	$\approx 100\text{dB}$	$\approx 100\text{dB}$
Gain Bandwidth	610kHz	1.0MHz
Phase Margin	60°	58°
Input Offset	5.2mV	5.2mV
Slew Rate	$2.5\text{V}/\mu\text{S}$	5.0V
Power Supply	$\pm 1.0\text{V}$	$\pm 1.0\text{V}$
Load Condition	$10\text{k}\Omega // 20\text{pF}$	$10\text{k}\Omega // 20\text{pF}$
Area	0.22mm^2	0.22mm^2

OPTIMAL DESIGN OF LOW POWER NESTED GM-C COMPENSATION AMPLIFIERS USING A CURRENT-BASED MOS TRANSISTOR MODEL



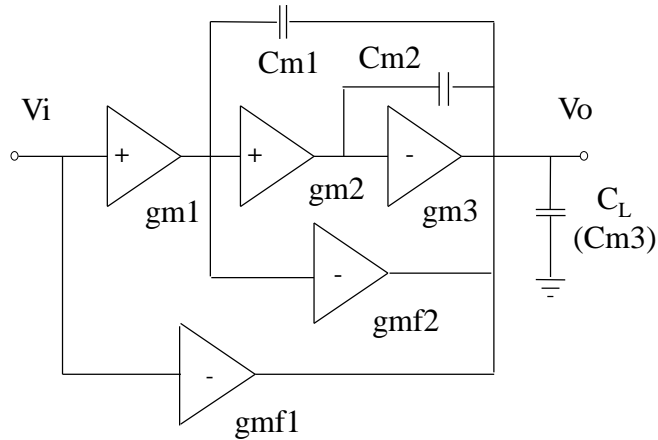
X. Xie, M. C. Schneider, S. H. K. Embabi, E. Sánchez-Sinencio

Department of Electrical Engineering
Texas A&M University
College Station, Texas 77843-3128, USA

Low Power Operational Amplifiers

- Applications: mobile communication & portable devices
- Major concerns: power, stability, area and speed.
- Design approach:
 - Low voltage — multistage cascading.
Techniques for solving stability problem:
 - Nested Miller Compensation (NMC)
 - Nested Gm-C Compensation (NGCC)
 - Low operating current — weak or moderate inversion.
 - Optimal design in moderate inversion
 - Continuous MOSFET model

Topology of Three-stage NGCC Amplifier



We define:

$$k_i = \frac{g_{mi}}{g_{oi}} \quad f_i = \frac{g_{mi}}{C_{mi}}$$

$$f_1 = \frac{g_{m1}}{C_{m1}} \quad \text{— unity gain frequency}$$

$$A_o = k_1 k_2 k_3 \quad \text{— dc gain}$$

- feedforward path g_{mf1} and g_{mf2} to cancel RHP zeros.

- Transfer function:

$$\frac{V_o(s)}{V_i(s)} = - \frac{g_{m1}g_{m2}g_{m3} + s g_{m1}(g_{mf2} - g_{m2})C_{m2} + s^2(g_{mf1} - g_{m1})C_{m1}C_{m2}}{g_{o1}g_{o2}g_{o3} + s g_{m2}g_{m3}C_{m1} + s^2(g_{m3} + g_{mf2} - g_{m2})C_{m1}C_{m2} + s^3 C_L C_{m1}C_{m2}}$$

Making $g_{mf1} = g_{m1}$ and $g_{mf2} = g_{m2}$ gives:

$$\frac{V_o(s)}{V_i(s)} = \frac{-g_{m1}g_{m2}g_{m3}}{g_{o1}g_{o2}g_{o3} + s g_{m2}g_{m3}C_{m1} + s^2 g_{m3}C_{m1}C_{m2} + s^3 C_L C_{m1}C_{m2}}$$

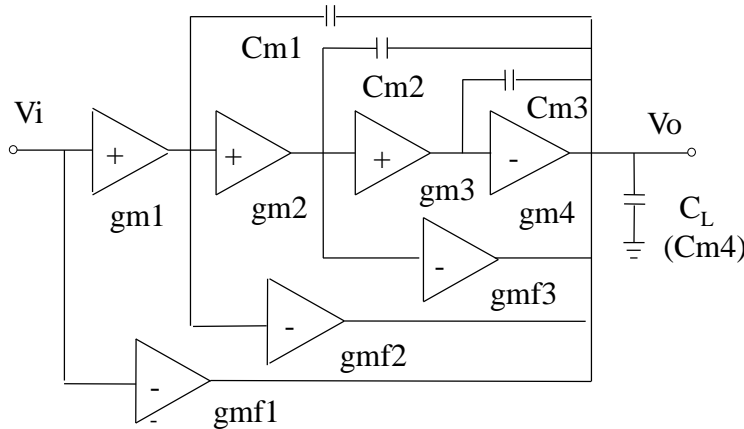
Rewritten as:

$$H(s) = \frac{V_o(s)}{V_i(s)} = \frac{-k_1 k_2 k_3}{\left(1 + s \frac{k_1 k_2 k_3}{f_1}\right) \left(1 + \frac{s}{f_2} + \frac{s^2}{f_2 f_3}\right)}$$

Phase margin:

$$PM \cong 90^\circ - \tan^{-1} \frac{1}{\left(\frac{f_2}{GB} - \frac{GB}{f_3}\right)}$$

Topology of Four-stage NGCC Amplifier



Compared to three-stage NGCC:

- easier to obtain high dc gain,
- more complicated design,
- potentially more power consumption.

- Transfer function:

$$\frac{V_o(s)}{V_i(s)} = \frac{-A_0}{\left(1 + \frac{A_0 s}{f_1}\right) \left(1 + \frac{s}{f_2} + \frac{s^2}{f_2 f_3} + \frac{s^3}{f_2 f_3 f_4}\right)}$$

- Phase margin:

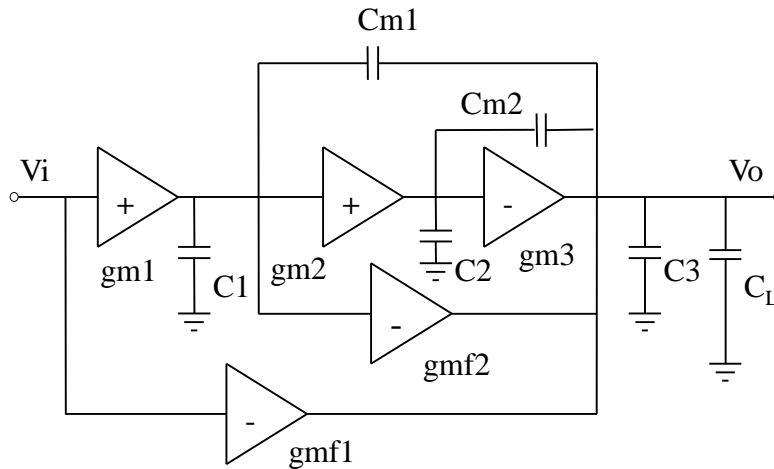
$$PM = 90^\circ - \tan^{-1} \left(\frac{GB}{f_2} \times \frac{1 - GB^2 / f_3 f_4}{1 - GB^2 / f_2 f_4} \right)$$

$$\approx 90^\circ - \tan^{-1} \left(\frac{GB}{f_2} \right)$$

- Transfer function of an n-stage NGCC amplifier:

$$\frac{V_o(s)}{V_i(s)} = \frac{-A_0}{\left(1 + \frac{A_0 s}{f_1}\right) \left(1 + \frac{s}{f_2} + \frac{s^2}{f_2 f_3} + \dots + \frac{s^{n-1}}{\prod_{i=2}^n f_i}\right)}$$

Modification on Low Power Three-stage NGCC



Significant parasitic effect:

- very large transistors for weak inversion design,
- long channel transistors used for high dc gain.

- Modified transfer function:

$$H'(s) = -\frac{A_0 + a_1 s + a_2 s^2}{\left(1 + s \frac{A_0}{f_1'}\right) \left(1 + \frac{s}{f_2'} + \frac{s^2}{f_2' f_3'}\right)}$$

where

$$a_1 = k_1 k_2 \left(\frac{C_2}{g_{o3}} - k_3 \tau \right)$$

$$a_2 = k_1 \left(\frac{C_1 (C_2 + C_{m2})}{g_{o2} g_{o3}} + k_2 \tau \frac{C_{m2}}{g_{o3}} \right)$$

- C_i — parasitic capacitance at each output node,
- τ — phase delay due to the current mirror at second stage.

Modification on Low Power Three-stage NGCC (cont.)

$$f'_1 = f_1$$

$$f'_2 = f_2 \frac{1}{1 + \varepsilon_1 + \varepsilon_2 \frac{g_{m2}}{g_{m3}} - f_2 \tau + \frac{g_{o3}}{g_{m3}} (1 + \varepsilon_1)(1 + \varepsilon_2)}$$

$$f'_3 = f_3 \frac{\frac{1}{1 + \varepsilon_2} - f_2 \tau \frac{1}{1 + \varepsilon_1} \frac{1}{1 + \varepsilon_2} + \frac{g_{o3}}{g_{m3}} + \frac{g_{m2}}{g_{m3}} \frac{1}{1 + \varepsilon_1} \frac{\varepsilon_2}{1 + \varepsilon_2}}{1 + \frac{C_3}{C_L} + \frac{C_2}{C_L} \frac{1}{1 + \varepsilon_2} + \frac{C_1}{C_L} \frac{1}{1 + \varepsilon_1} + \frac{g_{m2} \tau}{C_L} \frac{1}{1 + \varepsilon_1} \frac{1}{1 + \varepsilon_2}}$$

Moderate inversion:

- good stability,
- optimization of power, speed & area.

with $\varepsilon_1 = C_1/C_{m1}$ and $\varepsilon_2 = C_2/C_{m2}$

Ex: $f_1 = \text{GB}$, $f_2 = 2\text{GB}$, $f_3 = 4\text{GB}$, $C_{m1} = C_{m2} = 8 \text{ pF}$, $C_L = 20 \text{ pF}$,

then $g_{m1} = 50 \text{ } \mu\text{S}$, $g_{m2} = 100 \text{ } \mu\text{S}$, $g_{m3} = 500 \text{ } \mu\text{S}$,

For $g_{o3} = 100 \text{ } \mu\text{S}$ (R_L), $C_1 = 1 \text{ pF}$, $C_2 = 3 \text{ pF}$, $C_3 = 6 \text{ pF}$

Assume $\tau = 0$,

Then $f'_2 = 0.66f_2$ and $f'_3 = 0.67f_3$

Current-Based Transistor Model

- Features of ACM model:
 - physics-based model,
 - universal and continuous expression for any inversion,
 - independent of technology, temperature, geometry and gate voltage,
 - same model for analysis, characterization and design.
- Main design equations: (design parameters: I , g_m , i_f)

$$\frac{I}{\phi_t g_m n} = \frac{1 + \sqrt{1 + i_f}}{2}$$

$$f_T = \frac{\mu \phi_t}{2\pi L^2} 2(\sqrt{1 + i_f} - 1)$$

$$\frac{W}{L} = \frac{g_m}{\mu C_{ox} \phi_t} \frac{1}{\sqrt{1 + i_f} - 1}$$

$$\frac{V_{DSAT}}{\phi_t} \cong (\sqrt{1 + i_f} - 1) + 4$$

$$\frac{W}{L} = \frac{g_m}{2\mu C_{ox} \phi_t \left(\frac{I}{\phi_t g_m n} - 1 \right)}$$

I — drain current in transistor

g_m — transconductance in saturation

n — slope factor

ϕ_t — thermal voltage

i_f — inversion level of the transistor defined as

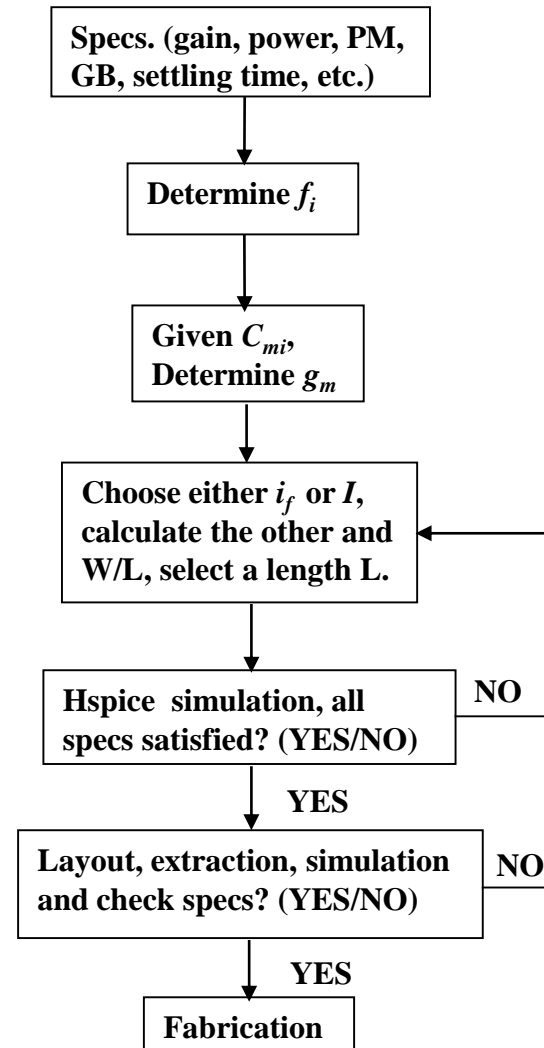
$i_f = I/I_s$, where $I_s = \mu n C_{ox} \frac{\phi_t^2 W}{2 L}$
is the normalization current.

$i_f \ll 1$ — weak inversion,

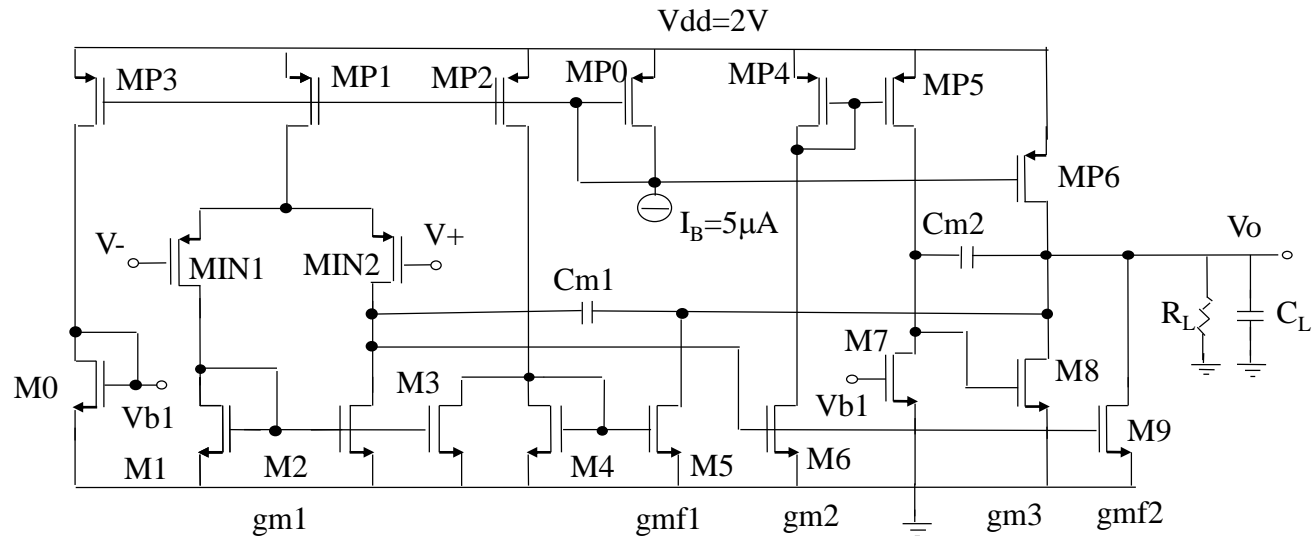
$i_f \gg 1$ — strong inversion.

Specifications and Design Procedure

- Specifications:
 - load $10\text{ k}\Omega/20\text{ pF}$
 - gain bandwidth $\text{GB}=1\text{ MHz}$
 - dc gain $A_0 > 100\text{ dB}$
 - phase margin $\text{PM} > 60^\circ$
 - 0.2% settling time $< 1\mu\text{s}$
 - power consumption: minimum
- Other Specs can be included (if determined by g_m , I , and i_f):
 - noise,
 - slew rate,
 - common mode rejection.



Implementation of Three-Stage NGCC Amplifier

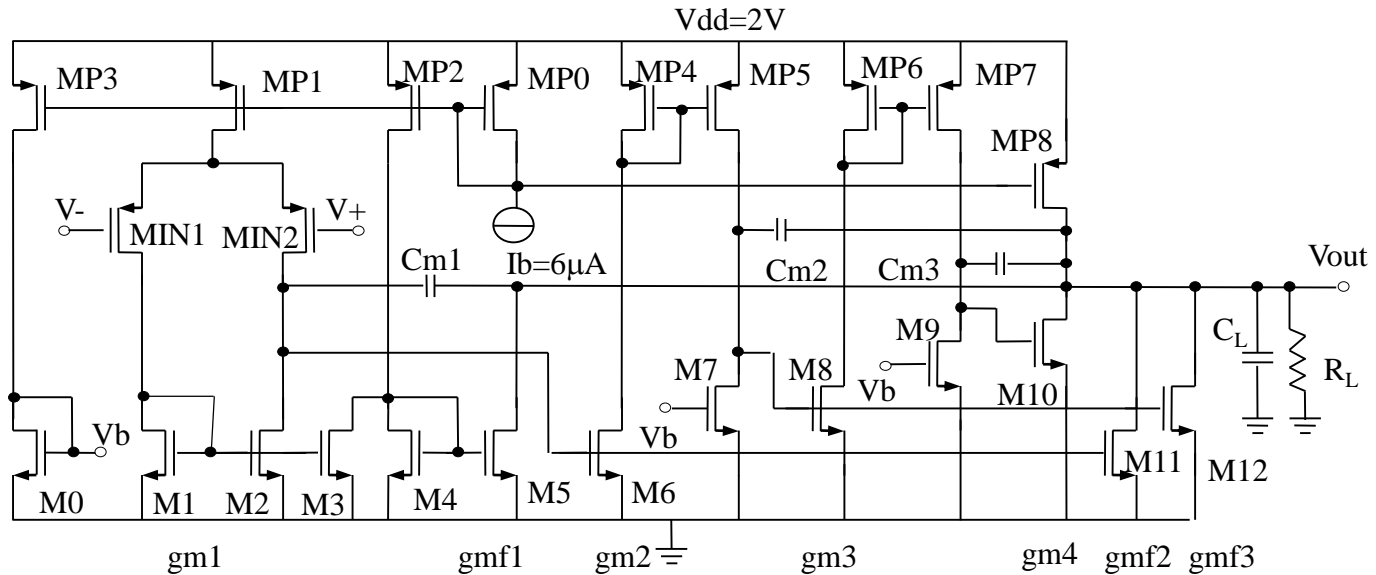


Remarks:

- Ideally, $f_1 = \text{GB}$, $f_2 = 2\text{GB}$, $f_3 = 4\text{GB}$,
Choose $f_2=3\text{GB}$, $f_3=5\text{GB}$ to
compensate large parasitic effect.
- Long channel to obtain adequate gain
— cause large parasitic effect.

Transistor NO.	W(μm)	L(μm)	i_f
M ₁ — M ₄	1×18	4.2	20
M ₀ , M ₅	2×18	4.2	20
M ₆ , M ₇ , M ₉	6×18	4.2	20
M ₈	25×18	4.2	20
M _{IN1} , M _{IN2}	20×18	4.2	4
M _{PO} — M _{P3}	2×18	4.2	80
M _{P4} , M _{P5}	6×18	4.2	80
M _{P6}	33×18	4.2	80

Implementation of Four-Stage NGCC Amplifier



Remarks:

- $f_1=GB, f_2=2GB, f_3=5GB, f_4=6GB$
- shorter length — small parasitic effect
- lower inversion level than 3-stage one.
- Same implementation and same f_i for reference opamp (low-voltage strong inversion 4-stage)

Transistor NO.	W(μm)	L(μm)	i_f
M ₁ — M ₄	4×10.8	1.8	6
M ₀ , M ₅	8×10.8	1.8	6
M ₆ , M ₇ , M ₁₁	8×10.8	1.8	6
M ₈ , M ₉ , M ₁₂	20×10.8	1.8	6
M ₁₀	60×10.8	1.8	6
M _{IN1} , M _{IN2}	8×18	1.8	6
M _{P0} — M _{P3}	2×18	1.8	30
M _{P4} , M _{P5}	2×18	1.8	30
M _{P6} , M _{P7}	5×18	1.8	30
M _{P8}	24×18	1.8	30

Simulation Results of NGCC Amplifiers

($V_{DD} = 2 \text{ V}$, $Z_{LOAD} = 10 \text{ k}\Omega/20 \text{ pF}$)

	Specifications	Three-Stage	Four-Stage	Four-Stage(ref.)
Power Consumption	Minimum	0.28 mW	0.30 mW	0.93 mW
DC Gain	$\geq 100 \text{ dB}$	$\sim 100 \text{ dB}$	$\sim 105 \text{ dB}$	$\sim 110 \text{ dB}$
Gain Bandwidth	1.0 MHz	1.08 MHz	1.03 MHz	1.09 MHz
Phase Margin	$> 60^\circ$	59.5°	62.7°	61.2°
0.2% Settling Time (100 mV)	$< 1 \mu\text{S}$	$0.77 \mu\text{S}$	$0.55 \mu\text{S}$	$0.53 \mu\text{S}$
THD (1kHz $1V_{P,P}$)		- 84.8 dB	- 88 dB	- 55.8 dB
1% THD Input (1kHz)		1.36V	1.38V	1.26V
Active Area (relative area)		0.01mm^2 (1.75)	0.0052 mm^2 (0.91)	0.0057 mm^2 (1)
$\min i_f, \max i_f$		4 , 80	6 , 30	100 , 130

* 1.2 μm AMI n-well CMOS technology

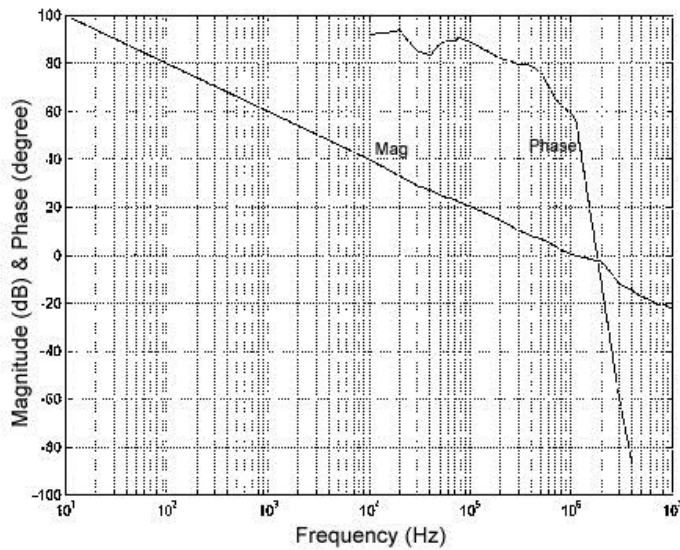
* BSIM (HSPICE level 13) simulation

Experimental Results

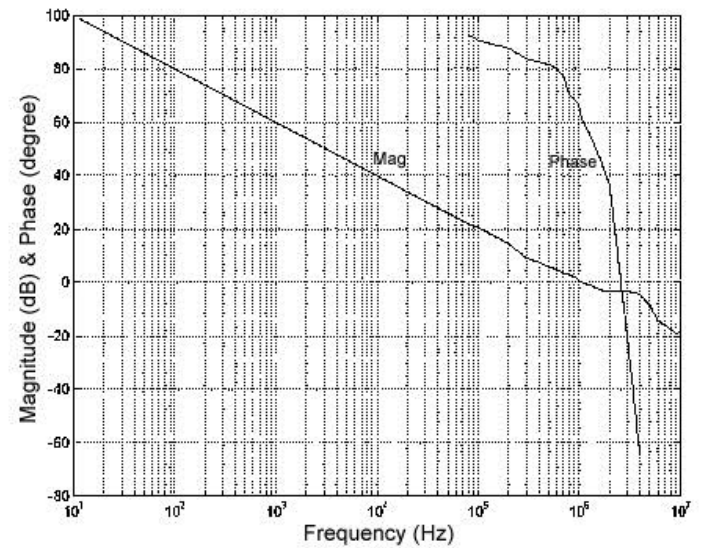
	Specifications	Three-Stage	Four-Stage	Four-Stage(ref.)
Power Consumption	Minimum	0.26 mW	0.28 mW	0.63 mW
DC Gain	≥ 100 dB	~ 96 dB	~ 105 dB	~ 100 dB
Gain Bandwidth	1.0 MHz	1.10 MHz	1.05 MHz	900 kHz
Phase Margin	$> 60^\circ$	56.7°	62.0°	63.6°
THD (1kHz 1V _{P-P})		- 67.7 dB	- 67.5 dB	- 28.5 dB
1% THD Input (1kHz)		1.13 V	1.11 V	0.94 V
Active Area (Relative Area)		0.01mm ² (1.49)	0.0052 mm ² (0.78)	0.0067 mm ² (1)

* The output stage of the reference op amp is realized with a PMOS transistor for reduction of power.

Frequency Response

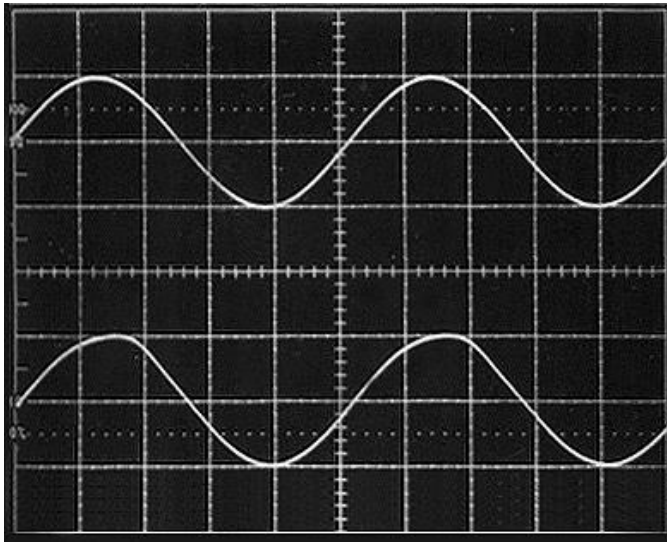


3-stage NGCC amplifier



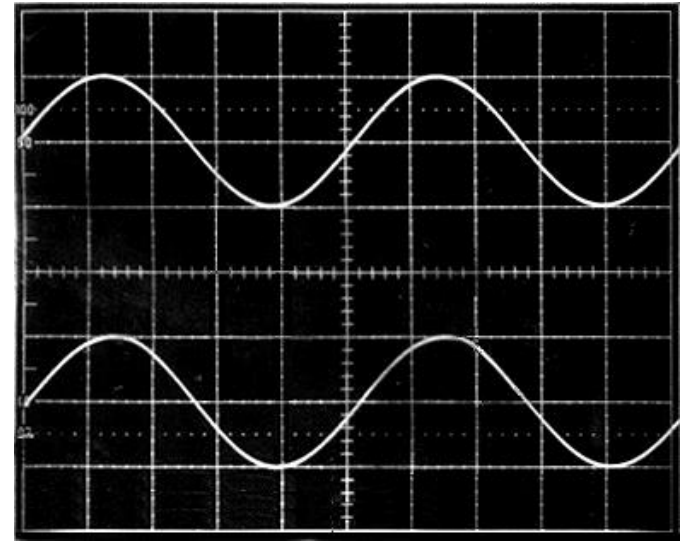
4-stage NGCC amplifier

Response to 100 kHz 1Vp-p sine wave



2 μ S/DIV

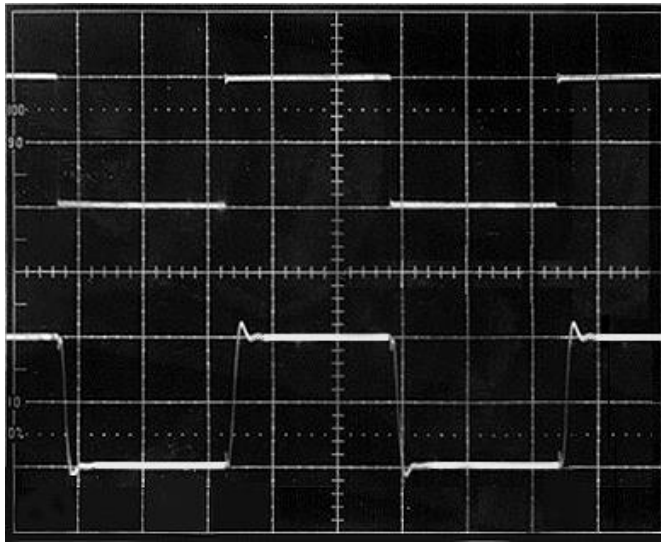
3-stage NGCC amplifier



2 μ S/DIV

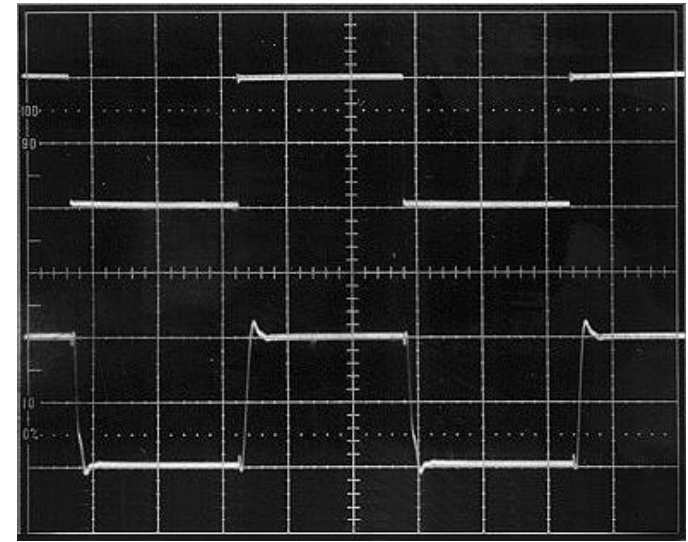
4-stage NGCC amplifier

Step Response with 100 kHz 100 mV Input



2 μ S/DIV

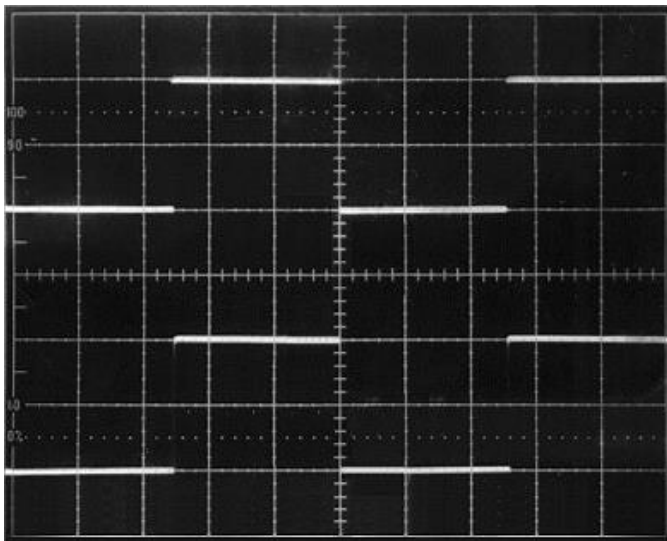
3-stage NGCC amplifier



2 μ S/DIV

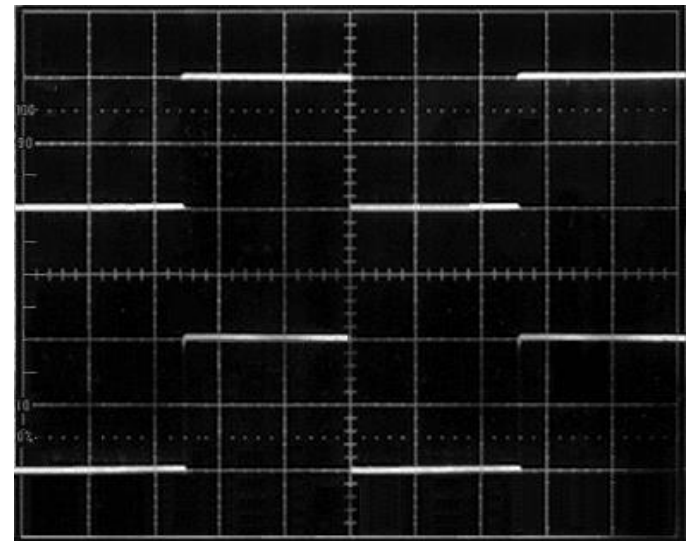
4-stage NGCC amplifier

Step Response with Large Signal (1 kHz 1V)



200 μ S/DIV

3-stage NGCC amplifier

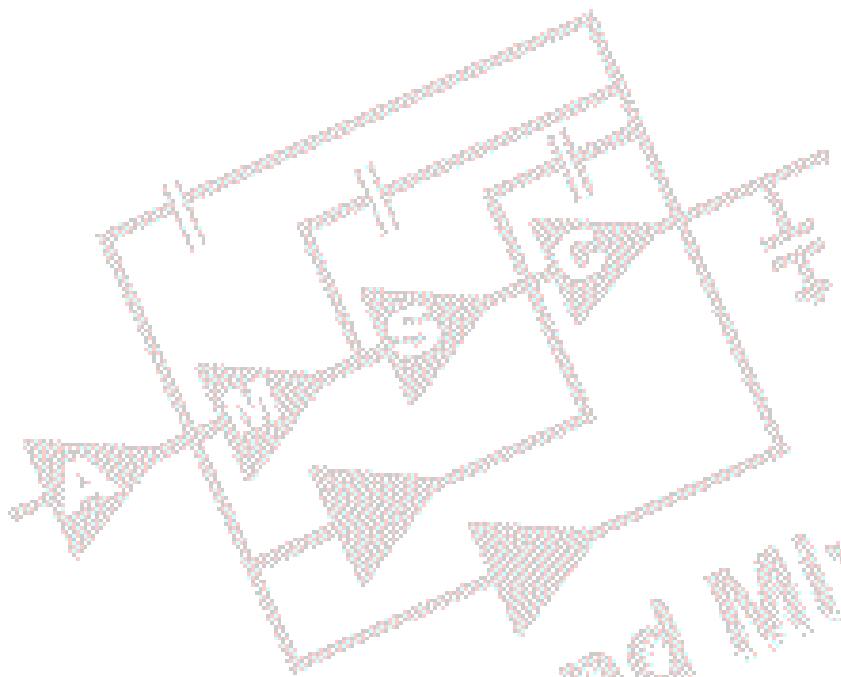
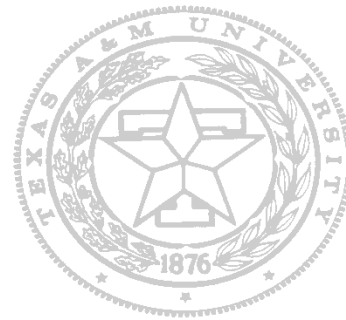


200 μ S/DIV

4-stage NGCC amplifier

Conclusions

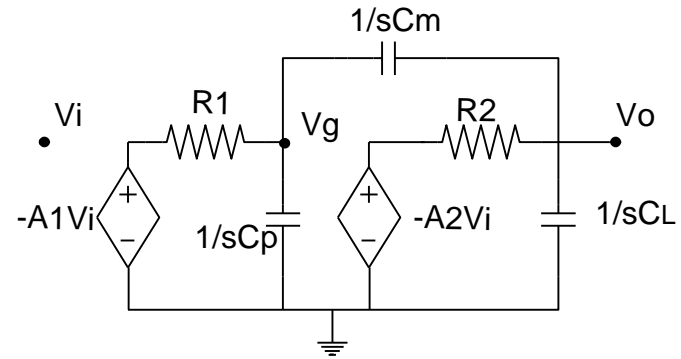
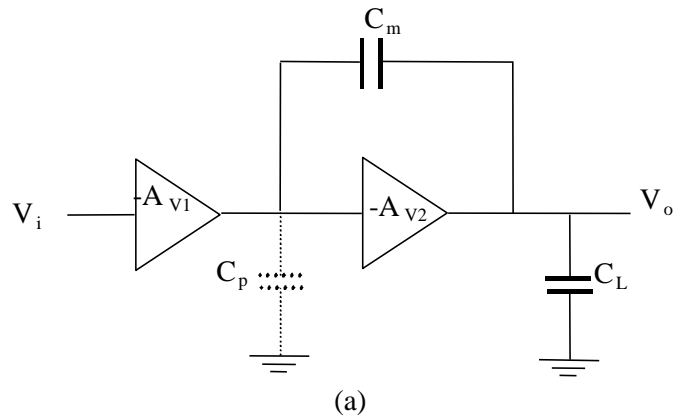
- Using a new MOSFET model, NGCC amplifiers can be designed in moderate inversion yielding optimal trade-off design.
- With same or better performance, low power amplifiers consume 65% less power than low voltage (strong inversion) design.
- Four-stage op amp has better overall performance with much less area and without dissipating evidently more power.
- Three-stage one benefits for the reduction of design complexity.



Analog and Mixed-Signal Center

Alternative structures for the Nested Gm-C Architectures: Advantages and Disadvantages

Review: Cascade with Miller effect



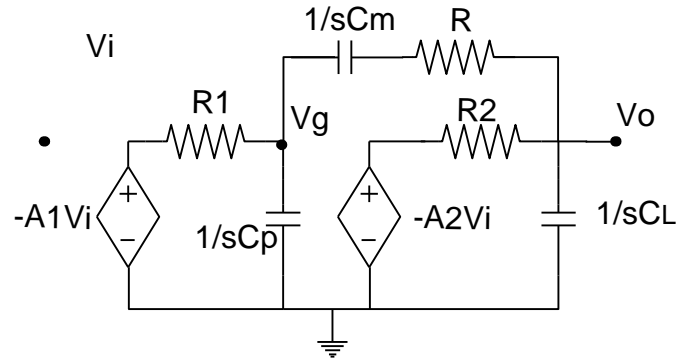
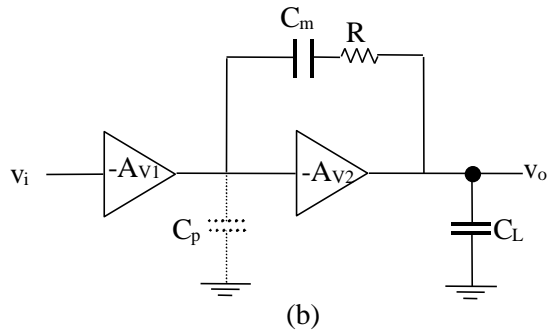
$$\frac{V_o}{V_i} = \frac{A_1(-A_2 + sC_m R_2)}{1 + s(C_p R_1 + C_L R_2 + C_m(R_1 A_1 + R_1 + R_2)) + s^2(C_p C_L + C_m(C_p + C_L))R_1 R_2}$$

$$D(s) = 1 + \frac{-s}{\omega_{p1}} + \frac{-s^2}{\omega_{p1}\omega_{p2}}$$

$$\omega_{p1} \approx \frac{-1}{C_p R_1 + C_L R_2 + C_m(A_2 R_1 + R_1 + R_2)} \approx \frac{-1}{R_1 A_2 C_m} = -\frac{g_{o1}}{A_2 C_m}$$

$$\omega_{p2} \approx \frac{-C_m A_2 \cdot g_{o2}}{C_p C_L + C_m(C_p + C_L)} \approx \frac{-g_{m2}}{C_p + C_L} \approx -\frac{g_{m2}}{C_L} \quad \omega_{z1} = +\frac{A_2}{C_m R_2} = \frac{g_{m2}}{C_m}$$

Pole splitting via RC feedback branch



$$\frac{V_o}{V_i} = \frac{A_1(A_2 + sC_m(A_2R_f s - R_2))}{(s^3 C_L R_2 C_p R_1 R_f C_m + s^2 (C_m(C_L R_2 R_f + C_p R_1 R_f + C_L R_2 R_1 + R_2 C_p R_1) + C_L R_2 C)}$$

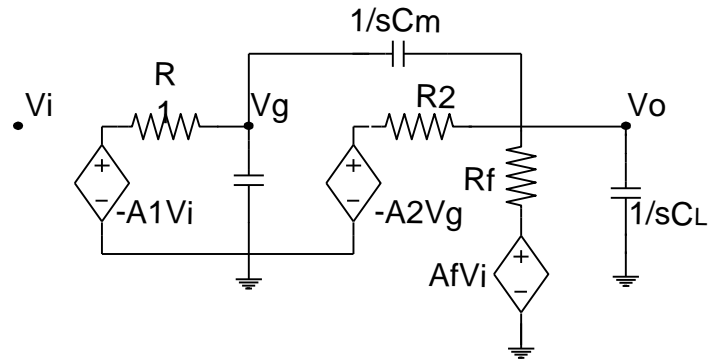
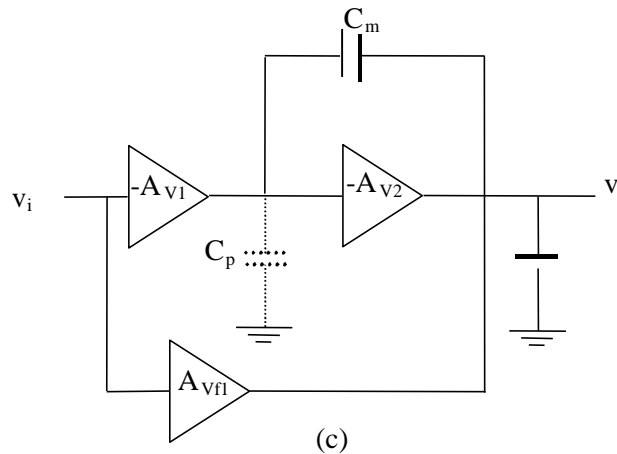
$$\frac{1}{+ s(R_f C_m + A_2 C_m R_1 + C_m R_1 + C_m R_2 + C_L R_2 + C_p R_1) + 1}$$

$$w_{p1} \approx \frac{-1}{C_p R_1 + C_L R_2 + C_m(A_2 R_1 + R_1 + R_2)} \approx \frac{-1}{R_1 A_2 C_m}$$

$$w_{p2} \approx \frac{-C_m A_2 \cdot g_{o2}}{C_p C_L + C_m(C_p + C_L)} \approx \frac{-g_{m2}}{C_p + C_L}$$

$$w_{z1} = + \frac{1}{C_m(R_2 / A_2 - R)} = \frac{1}{C_m(1 / g_{m2} - R)}$$

Review: Feedforward compensation



◦ Transfer Function

$$\frac{V_i}{V_o} = \frac{-(-R_2 A_f - A_1 R_f A_2 - s(C_p R_1 R_2 A_f + C_m R_2 R_f A_1 - R_2 A_f C_m R_1))}{s^2 (C_L R_2 R_f C_p R_1 + C_L R_2 R_f C_m R_1 + C_m R_2 R_f C_p R_1 + s(R_f C_p R_1 + R_f C_m R_1)) + s(C_L R_2 R_f + C_m R_2 R_f + R_2 C_p R_1 + R_2 C_m R_1 + R_f A_2 C_m R_1) + R_f + R_2}$$

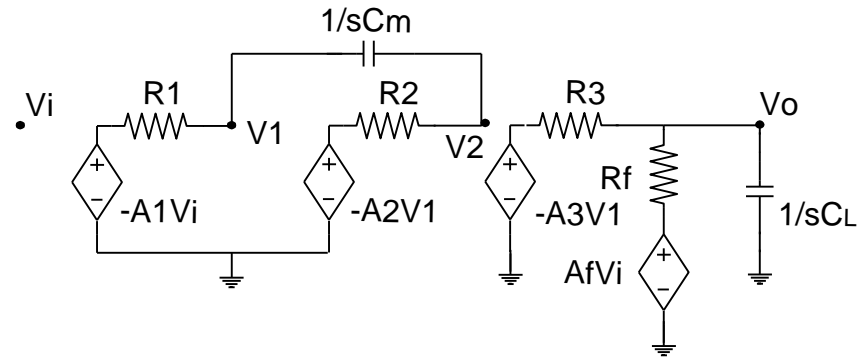
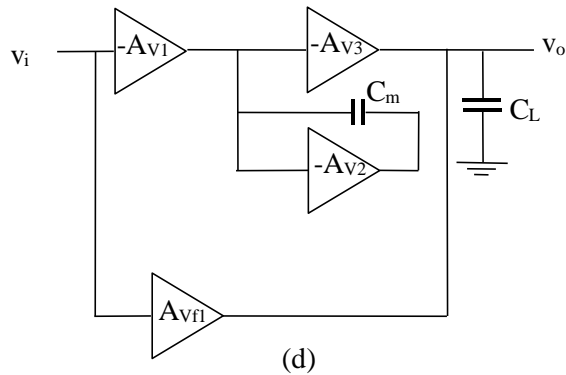
$$\frac{V_o}{V_i} \approx \frac{-g_{m1} g_{m2} + s C_m (g_{m1} - g_{mf})}{g_{o1} g_{o2} + s \cdot g_{m2} C_m + s^2 C_L C_m}$$

$$w_{p1} \approx \frac{-1}{g_{m2} R_2 C_m R_1} \approx \frac{-1}{A_2 C_m R_1}$$

$$w_{z1} \approx \frac{g_{m1} g_{m2}}{C_m (g_{m1} - g_{mf})}$$

$$w_{p2} \approx \frac{g_{m2}}{C_L}$$

Creating and internal zero cancellation DFCFC



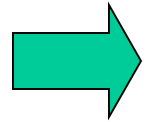
$$w_{p1} \approx \frac{-gm1}{CmR2(gm1 + gm2)} \Big|_{gm1=gm2} = -\frac{g02}{2Cm}$$

$$w_{p2} \approx \frac{-(Rf + R3)}{R3 \cdot Rf \cdot Cm} \Big|_{Rf=R3} = -\frac{2}{R3Cm}$$

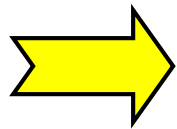
$$w_{z1} \approx -\frac{R1gmfgm1 + gm3}{Cm(R1gmfR2gm1 + R1gmfgm2R2 + gm3R1 + gm3R2)}$$

Damping factor frequency controlled compensation (DFCFC)

Amplifier Comparisons



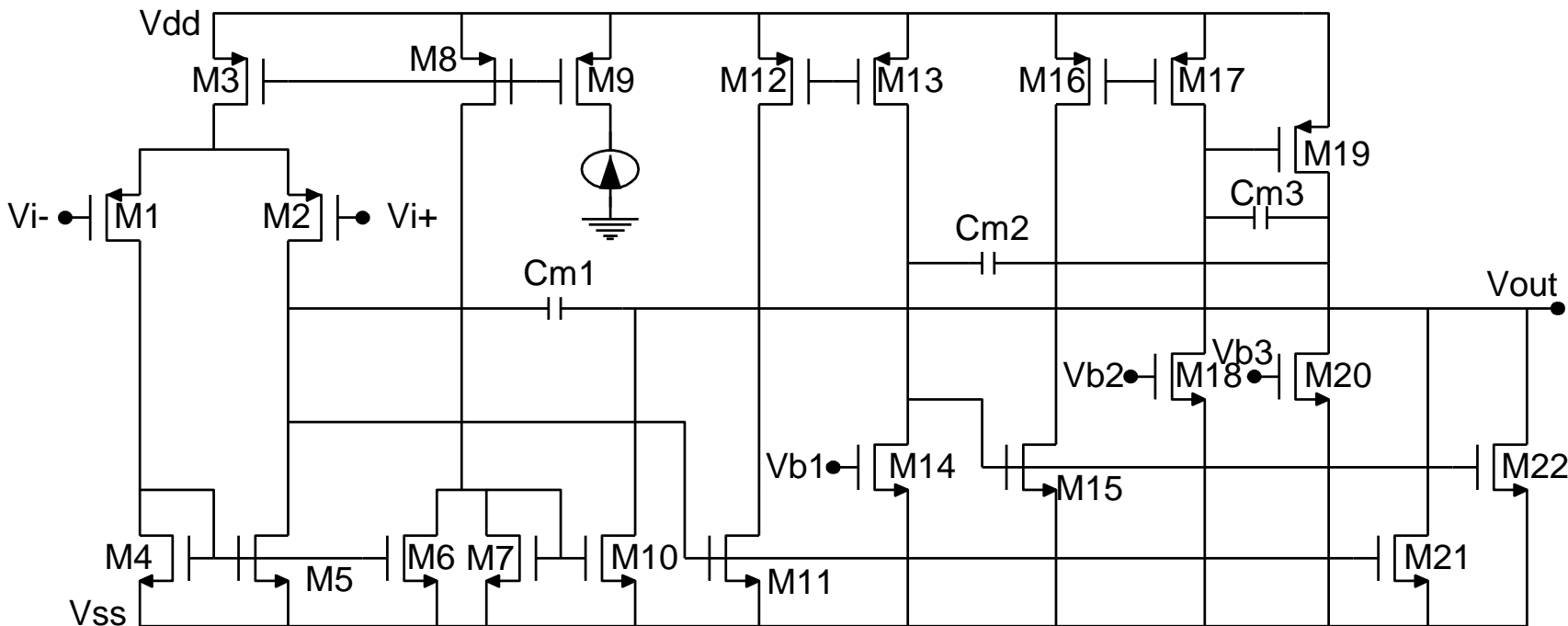
4 stage NGCC Amplifier.



3 stage DFCFC Amplifier

Parameters	NGCC	DFCFC
A_v (dB)	100.3	100.4
GBW (MHz)	8.21	8.23
Phase Margin($^{\circ}$)	70	75
0.2% Settling Time(ns)	373	398
Slew Rate(+) (V/us)	11.2	8.2
Slew Rate(-) (V/us)	-7.1	-6.7
CMR (V)	1.25	0.97
CMRR (dB)	63.02	28.55
PSRR+ (dB)	49.62	24.05
PSRR- (dB)	29.1	20.48
Input Referred Offset (v)	290n	-4.13u
Active Area (μm^2)	233.4	228.88
Power Consumption (mW)	1.2	0.4

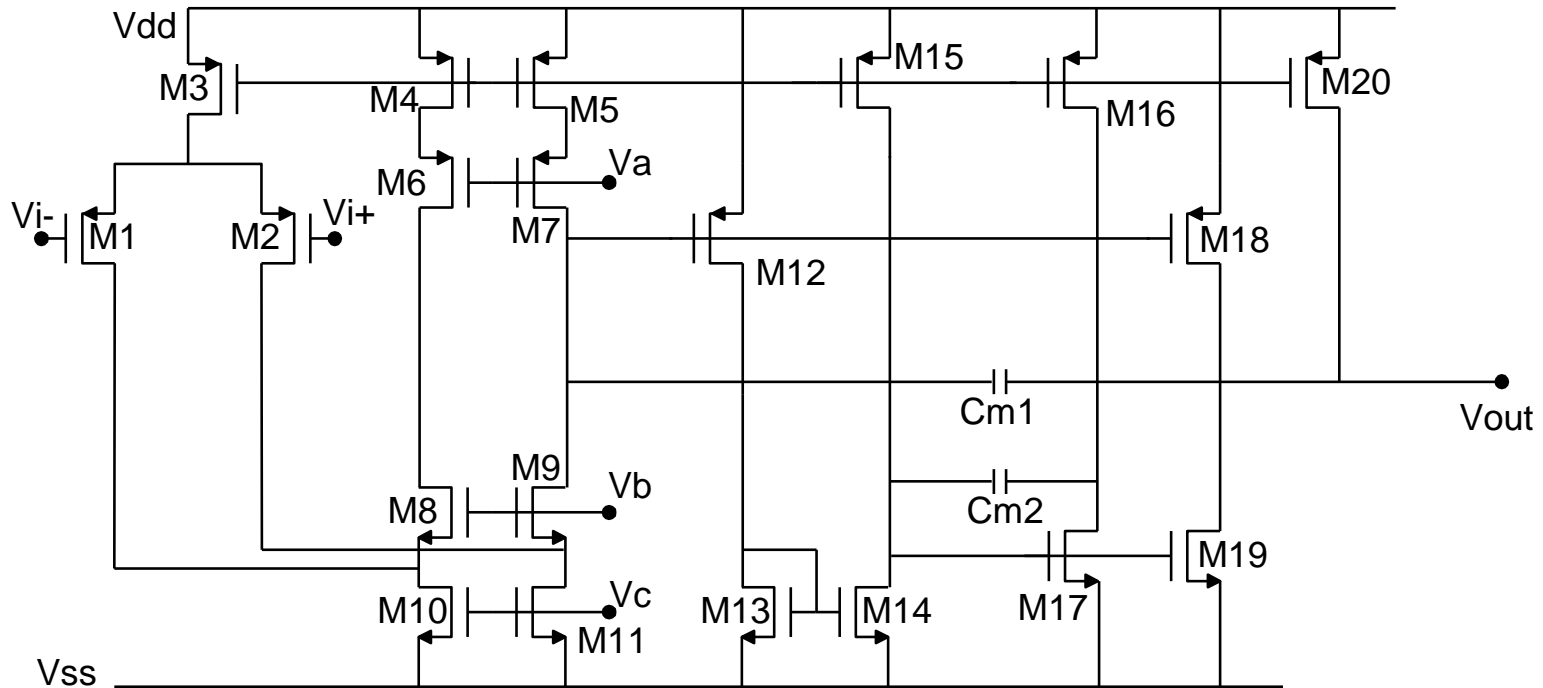
4 stage NGCC Amplifier.



Design Summary

#	M1	M2	M3	M4	M5	M6	M7	M8
Size	49/.4	46/.4	36/.4	10/.4	10/.4	38/.4	6.5/.4	38/.4
#	M9	M10	M11	M12	M13	M14	M15	M16
Size	38/.4	6.5/.4	22/.4	22/.4	22/.4	10/.4	20/.4	30/.4
#	M17	M18	M19	M20	M21	M22	•	•
Size	30/.4	20/.4	70/.4	20/.4	23/.4	44/.4		

3 stage DFCFC Amplifier



#	M1	M2	M3	M4	M5	M6	M7	M8	M9	M10
Size	38/.4	38/.4	48/.4	1.2/.4	1.2/.4	1.2/.4	1.2/.4	1.2/.4	1.2/.4	18/.4
#	M11	M12	M13	M14	M15	M16	M17	M18	M19	M20
Size	18/.4	30/.4	22/.4	45/.4	45/.4	9/.4	3/.4	31/.4	95/.4	53/.4

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Published: NOV 2011

Author(s): Peng Xiaohong; Sansen Willy; Hou Ligang; et al.

Impedance Adapting Compensation for Low-Power Multistage Amplifiers
Source: *IEEE JOURNAL OF SOLID-STATE CIRCUITS* Volume: 46 Issue: 2 Pages: 445-451 DOI: 10.1109/JSSC.2010.2090088 Published: FEB 2011

Author(s): Ito Rui; Itakura Tetsuro

Title: Phase Compensation Techniques for Low-Power Operational Amplifiers
Source: *IEICE TRANSACTIONS ON ELECTRONICS* Volume: E93C Issue: 6
Pages: 730-740 DOI: 10.1587/transele.E93.C.730 Published: JUN 2010
