

ECEN474: (Analog) VLSI Circuit Design

Fall 2011

Lecture 11: Frequency Response (cont.)



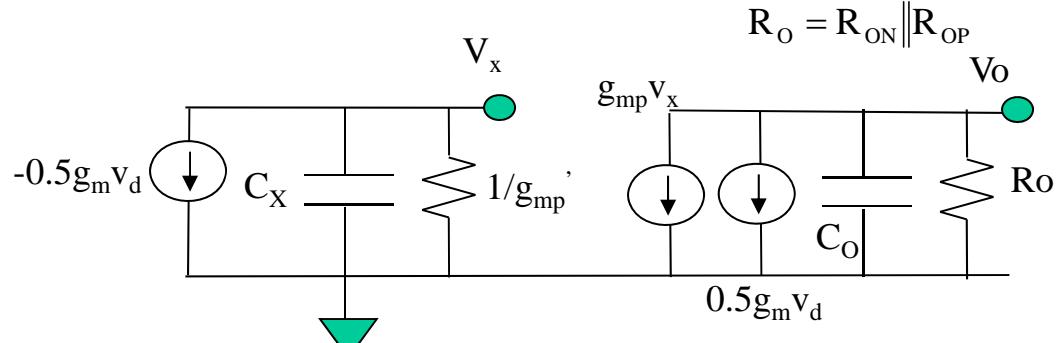
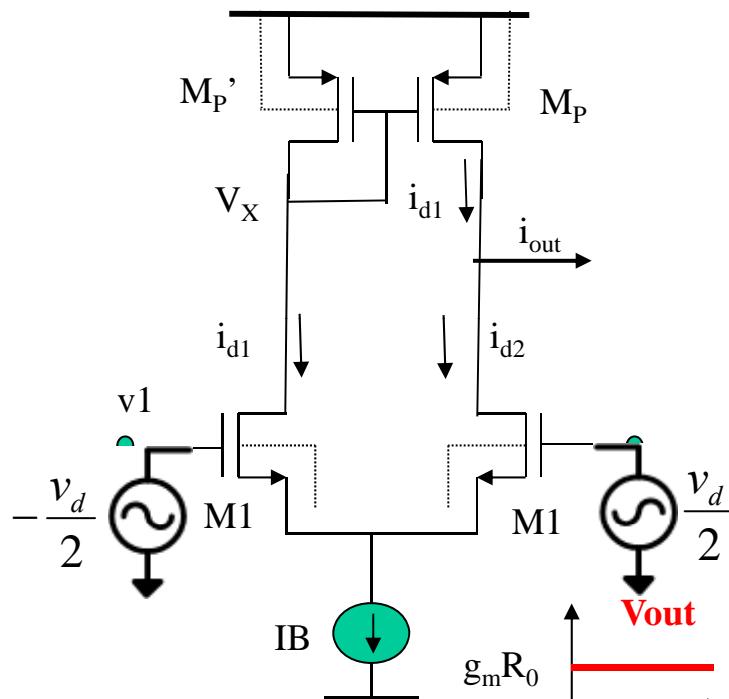
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Agenda

- Differential Pairs
- Common-Drain Amp Frequency Response
- Common-Gate Amp Frequency Response
- Cascode Amp Frequency Response

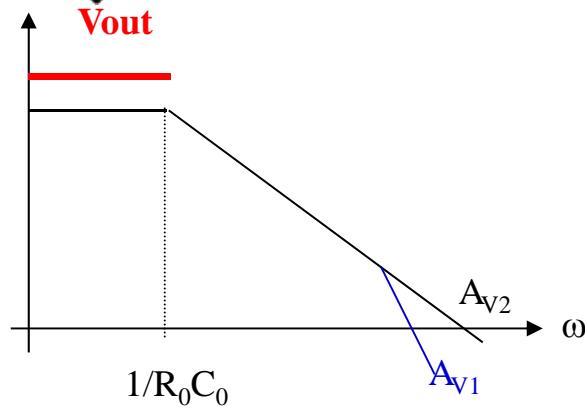
Low Frequency Response



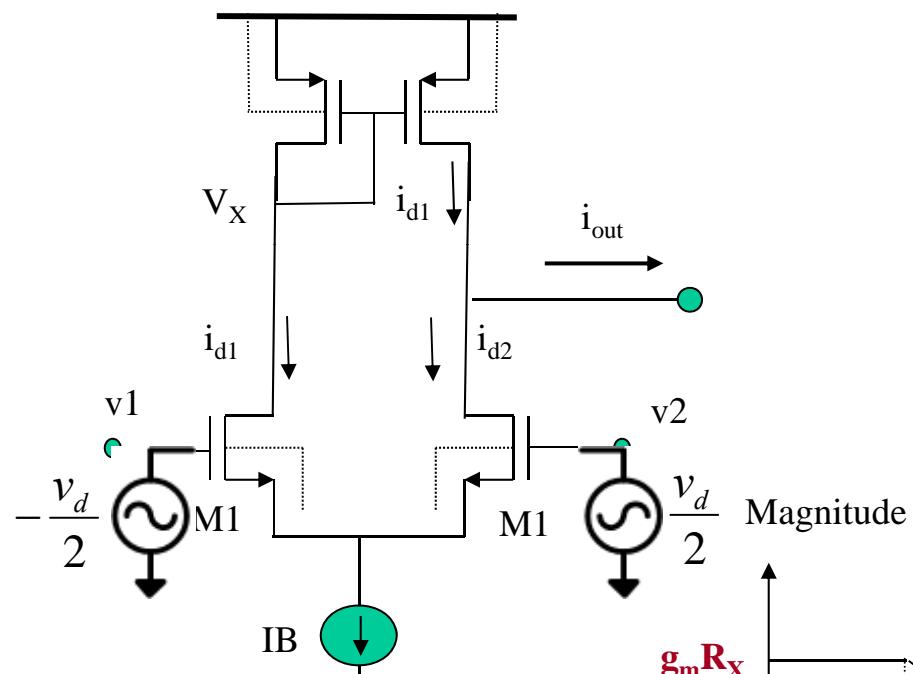
$$v_o = -g_m \left(\frac{v_d}{2} \right) R_o - g_m \left(-\frac{v_d}{2} \right) R_x \left(-g_{mp} R_o \right)$$

$$R_x \approx \frac{1}{g_{mp}}$$

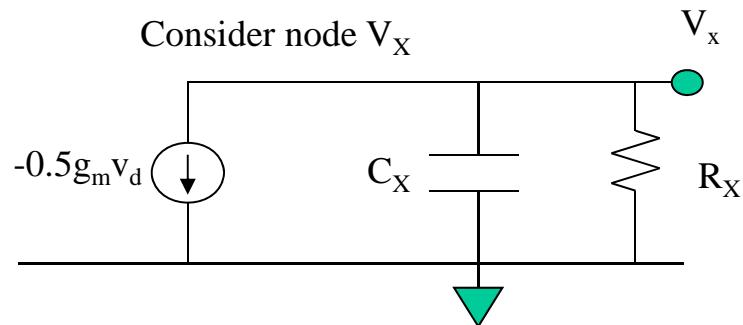
$$v_o = -g_m v_d R_o$$



Frequency Response



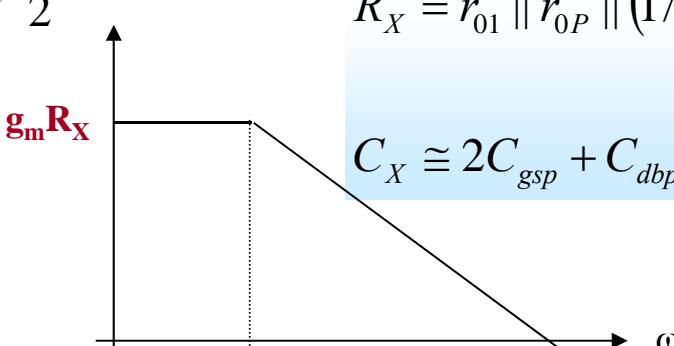
Consider node V_X



$$V_X = \frac{0.5g_m R_X}{1 + SR_X C_X} V_d$$

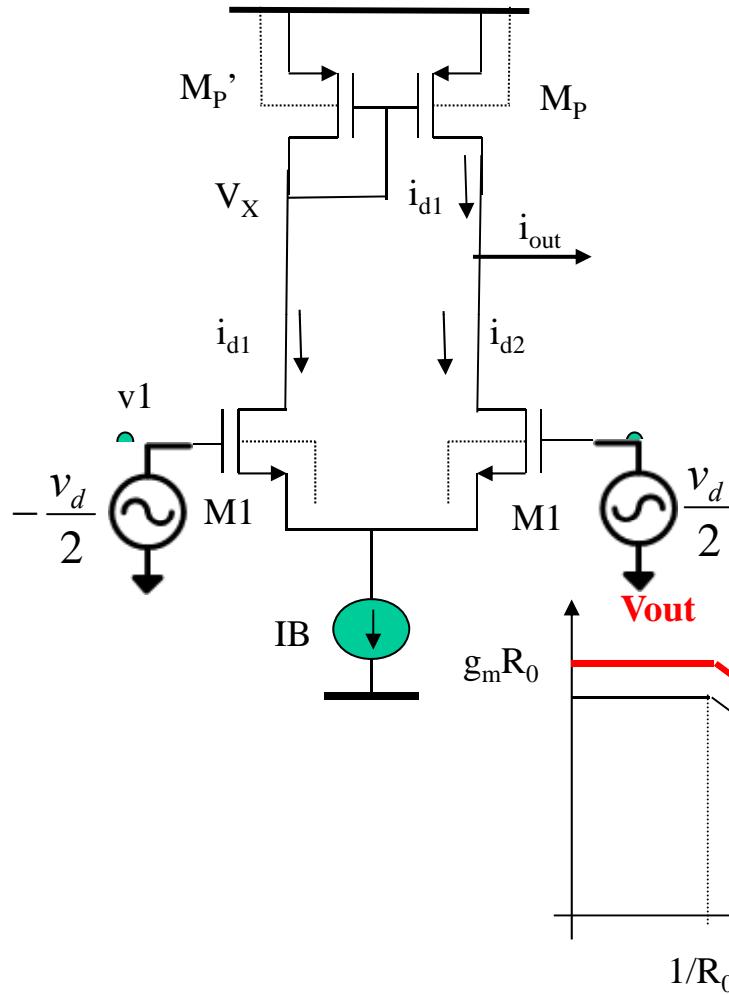
$$R_X = r_{01} \parallel r_{0P} \parallel (1/g_{mp})$$

$$C_X \cong 2C_{gsp} + C_{dbp} + (1 + \text{miller factor})C_{dgp} + C_{dbn}$$



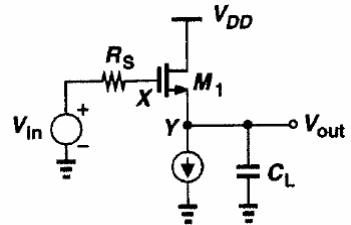
$$1/R_X C_X$$

Frequency Response



$$\begin{aligned}
 & R_o = R_{ON} \parallel R_{OP} \\
 & V_x \\
 & -0.5g_m v_d \quad C_x \quad 1/g_{mp} \\
 & g_{mp} V_x \quad 0.5g_m v_d \quad R_o \\
 & v_o = -g_m \left(\frac{v_d}{2} \right) \frac{R_o}{1 + sR_o C_o} - g_m \left(\frac{v_d}{2} \right) \left(\frac{1/g_{mp}}{1 + s \frac{C_x}{g_{mp}}} \right) \frac{g_{mp} R_o}{1 + sR_o C_o} \\
 & v_o = -g_m R_o \left(\frac{v_d}{2} \right) \frac{1}{1 + sR_o C_o} \left[1 + \frac{1}{1 + s \frac{C_x}{g_{mp}}} \right] \\
 & v_o = -g_m R_o \left(\frac{v_d}{2} \right) \frac{1}{1 + sR_o C_o} \left[\frac{2 + s \frac{C_x}{g_{mp}}}{1 + s \frac{C_x}{g_{mp}}} \right]
 \end{aligned}$$

Common-Drain Amplifier: High Frequency Response



$$\frac{V_{out}(s)}{V_{in}} = \frac{g_m + C_{GS}s}{R_s(C_{GS}C_L + C_{GS}C_{GD} + C_{GD}C_L)s^2 + (g_m R_s C_{GD} + C_L + C_{GS})s + g_m}$$

- From this simplified transfer function:

$$A_{dc} = \frac{g_m}{g_m} = 1 \quad (\text{Optimistic})$$

$$\text{Exact } A_{dc} = \frac{g_m}{g_m + g_o + g_{mb}}$$

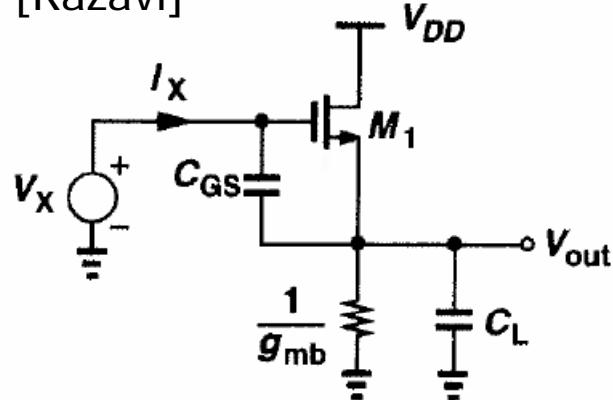
$$\omega_z = -\frac{g_m}{C_{gs}}$$

2 poles, If we assume that they are spaced far apart :

$$\omega_{p1} \approx \frac{g_m}{g_m R_s C_{GD} + C_L + C_{GS}} = \frac{1}{R_s C_{GD} + \frac{C_L + C_{GS}}{g_m}}$$

Common-Drain Amp Input Impedance

[Razavi]



$$Z_{in} = \frac{1}{C_{GS}s} + \left(1 + \frac{g_m}{C_{GS}s}\right) \frac{1}{g_{mb} + C_L s}$$

$$\text{Low Frequency: } Z_{in} \approx \frac{1}{C_{GS}s} \left(1 + \frac{g_m}{g_{mb}}\right) + \frac{1}{g_{mb}}$$

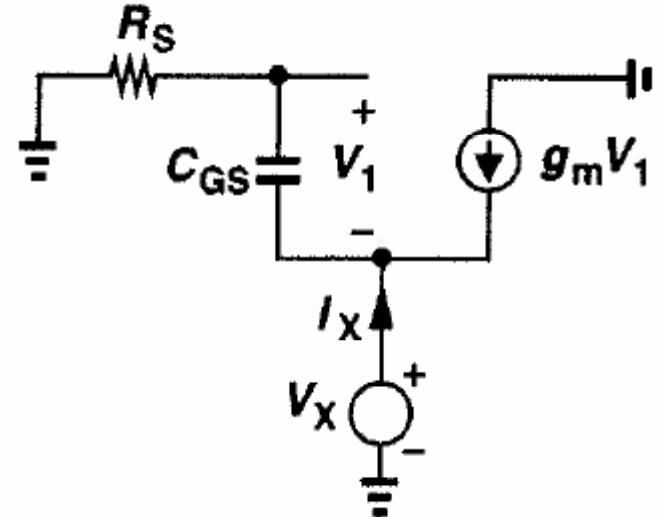
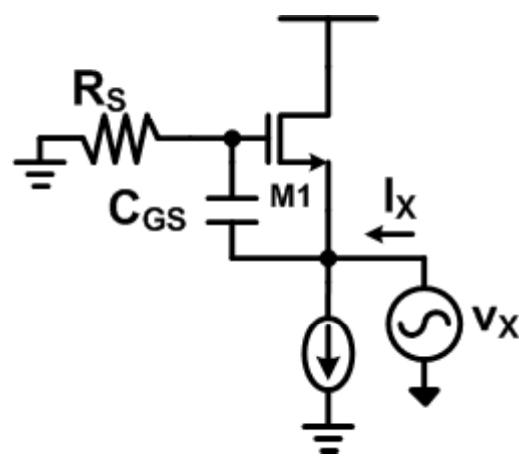
Equivalent to a series capacitive term $C_{gs} \left(\frac{g_{mb}}{g_m + g_{mb}} \right)$ and resistive term $\frac{1}{g_{mb}}$

$$\text{High Frequency: } Z_{in} \approx \frac{1}{C_{GS}s} + \frac{1}{C_L s} + \frac{g_m}{C_{GS} C_L s^2}$$

Series combination of C_{gs} and C_L and a negative resistance term $\left(-\frac{g_m}{C_{gs} C_L \omega^2} \right)$

The negative resistance term can be utilized in oscillator design

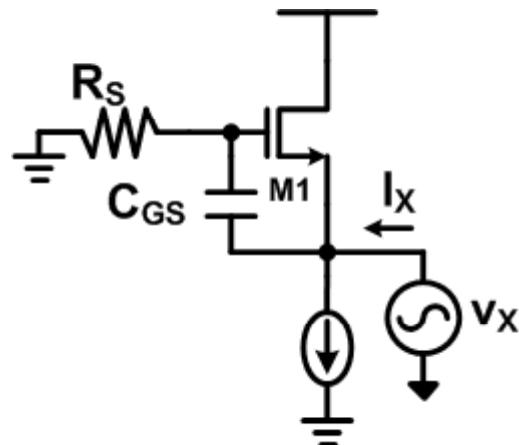
Common-Drain Amp Output Impedance



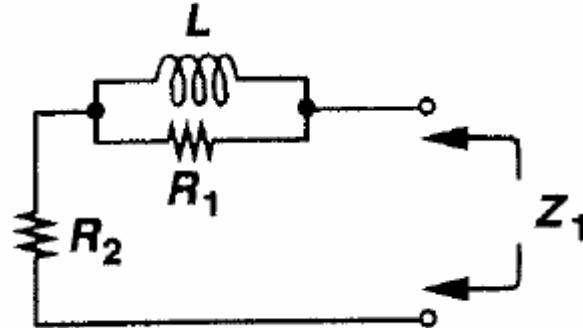
$$Z_{out} = \frac{V_x}{I_x} = \frac{R_s C_{GS}s + 1}{g_m + C_{GS}s}$$

- Pole at very high frequency
- Zero at potentially low frequency if R_s is large
 - Impedance can increase with frequency, i.e. display inductive behavior

Common-Drain Amp Output Impedance



$$Z_{out} = \frac{V_X}{I_X} = \frac{R_S C_{GS} s + 1}{g_m + C_{GS} s}$$

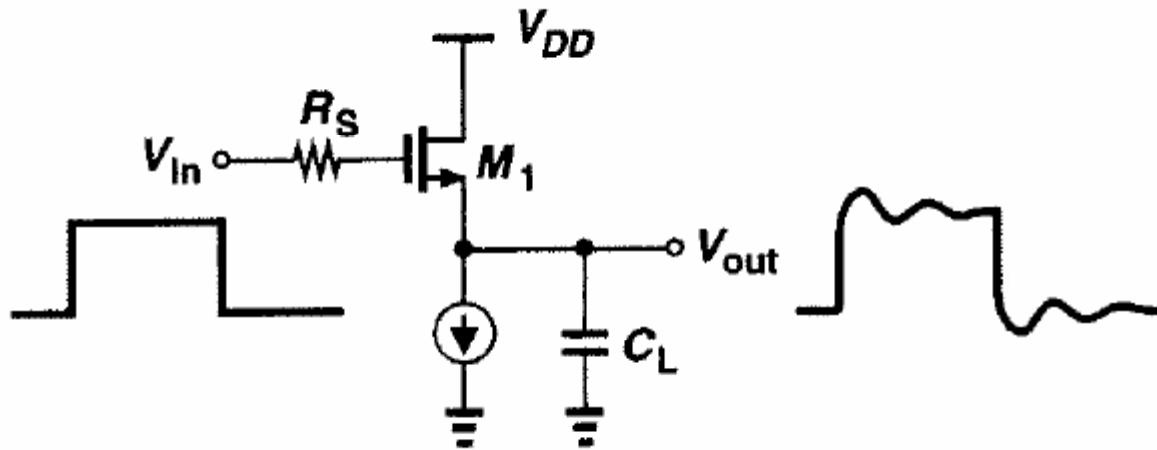


$$R_2 = \frac{1}{g_m}$$

$$R_1 = R_S - \frac{1}{g_m}$$

$$L = \frac{C_{GS}}{g_m} \left(R_S - \frac{1}{g_m} \right) \approx \frac{R_S C_{GS}}{g_m} \text{ if } R_S \gg \frac{1}{g_m}$$

Transient Behavior w/ Large C_L

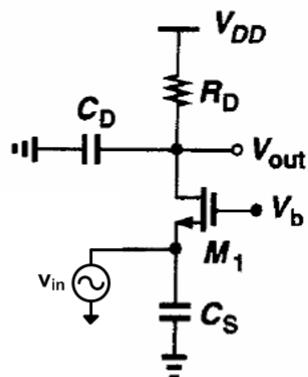


- Inductive output impedance in combination with a large load capacitance can create undesired “ringing” in the transient response
- If we have a large R_s and C_L , then the assumption that we have one dominant pole is no longer valid
- Both poles (potentially complex) should be considered in the analysis

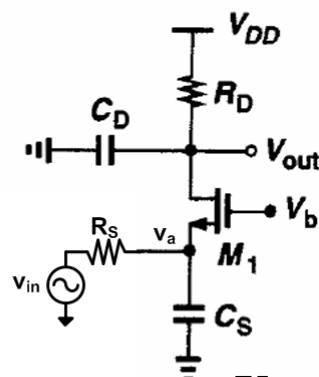
$$\frac{V_{out}}{V_{in}}(s) = \frac{g_m + C_{GS}s}{R_s(C_{GS}C_L + C_{GS}C_{GD} + C_{GD}C_L)s^2 + (g_m R_s C_{GD} + C_L + C_{GS})s + g_m}$$

Common-Gate Amp Low Frequency Response

- No R_S



- With R_S



$\frac{v_{out}}{v_a}$ is given from left

How to get from v_{in} to v_a ?

Use amplifier input impedance and voltage divider

Neglecting transistor r_o

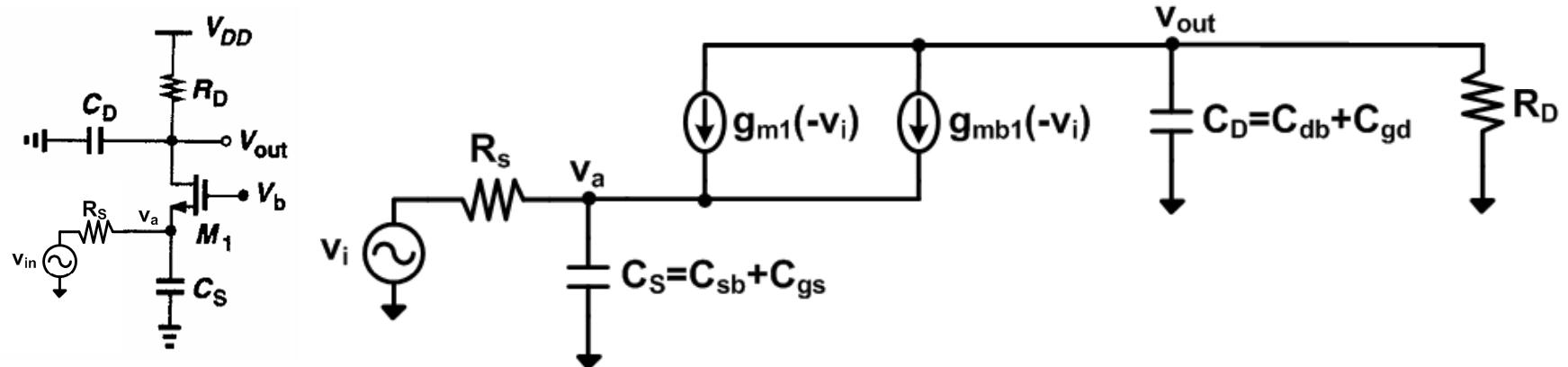
$$\frac{v_{out}}{v_{in}} = (g_m + g_{mb})R_D$$

$$R_{in} = \frac{1}{g_m + g_{mb}}$$

$$v_a = \frac{g_m + g_{mb}}{R_S + \frac{1}{g_m + g_{mb}}} v_{in} = \frac{1}{1 + (g_m + g_{mb})R_S} v_{in}$$

$$\frac{v_{out}}{v_{in}} = \frac{v_a}{v_{in}} \frac{v_{out}}{v_a} = \frac{(g_m + g_{mb})R_D}{1 + (g_m + g_{mb})R_S} \approx \frac{R_D}{R_S} \text{ if } R_S \text{ is large}$$

Common-Gate Amp Frequency Response

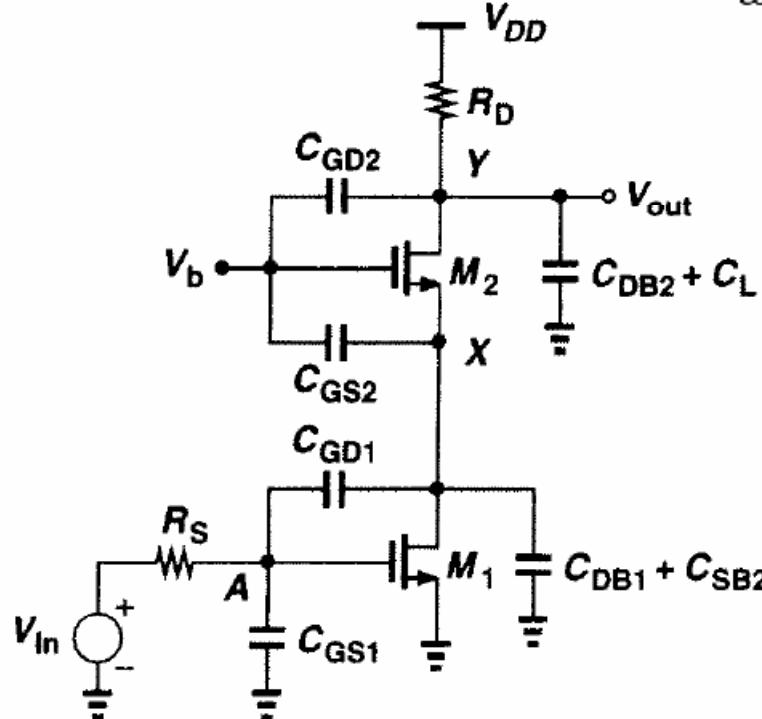


$$\frac{V_{out}}{V_{in}}(s) = \frac{(g_m + g_{mb})R_D}{1 + (g_m + g_{mb})R_s} \frac{1}{\left(1 + \frac{C_S}{g_m + g_{mb} + R_s^{-1}} s\right)(1 + R_D C_D s)}$$

- No zero
- No Miller capacitor multiplication
- Low input impedance limits effectiveness as a voltage amplifier
- Useful as a current-to-voltage (transimpedance) amplifier

Cascode Amp Frequency Response

- If we associate the poles with the nodes A, X, and Y
 - Note, this is only an approximation, as it ignores interactions caused by “feedforward” caps (C_{gd}) and resistors
- 3 pole system



Input Pole

$$\omega_{p,A} = \frac{1}{R_S \left[C_{GS1} + \left(1 + \frac{g_{m1}}{g_{m2} + g_{mb2}} \right) C_{GD1} \right]}$$

Internal Pole – High Frequency

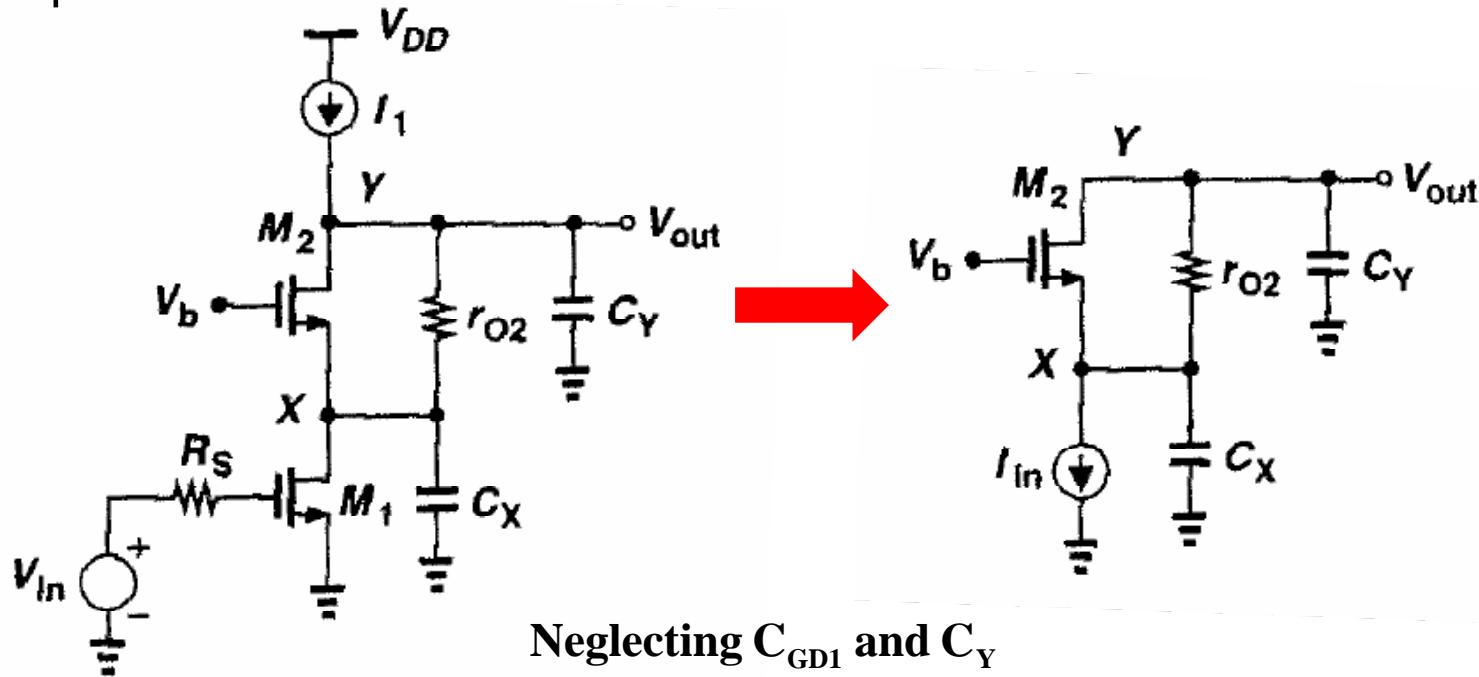
$$\omega_{p,X} = \frac{g_{m2} + g_{mb2}}{2C_{GD1} + C_{DB1} + C_{SB2} + C_{GS2}}$$

Output Pole

$$\omega_{p,Y} = \frac{1}{R_D(C_{DB2} + C_L + C_{GD2})}$$

Cascode Amp Output Impedance

- Simplified Model



$$Z_{out} = r_{o2} + Z_X + g_{m2}r_{o2}Z_X$$

$$\text{where } Z_X = r_{o1} \left\| \frac{1}{sC_X} \right.$$

$$\text{Output Impedance Pole } \omega_{Z_{out}} = \frac{1}{r_{o1}C_X}$$

Next Time

- Noise