

# Principled Reasoning and Practical Applications of Alert Fusion in Intrusion Detection Systems

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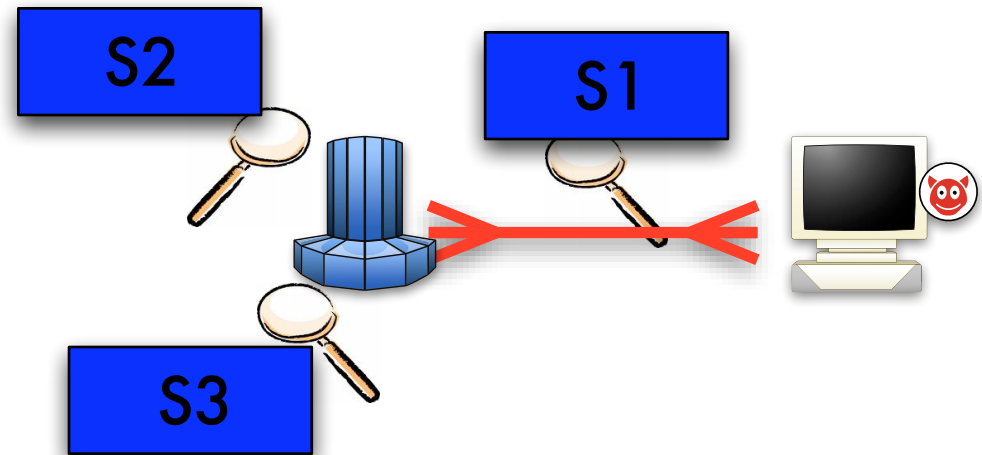
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# “OR” Rule for Combining Alerts

- Alerts of the same event can be raised by different methods

- Input string length
- Character distribution
- Token finder etc...



- OR Rule:
  - Alert iff S1 OR S2 OR S3 Alerts
- Analyst is overwhelmed by the number of alarms
- String length might give many false alerts

# “AND” Rule for Combining Alerts

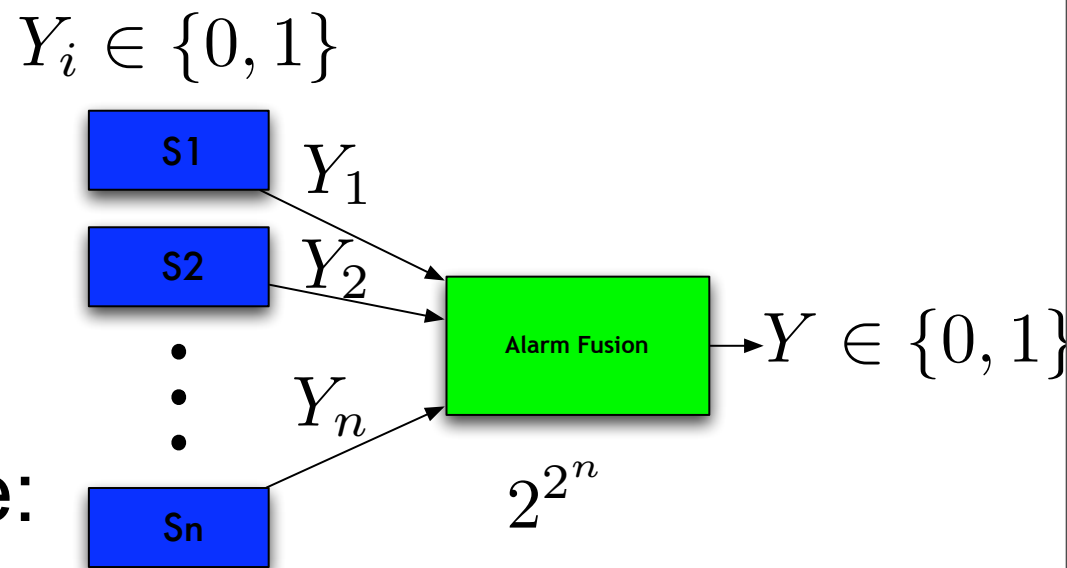
- Polygraph<sup>1</sup>: Automatic Generation of Signatures.
- Signature: Conjunction of all tokens
  - AND Rule:
    - Alert iff token1 AND token2 AND ... AND tokenN found in network flow.
- More false negatives: token observed in suspicious, but not in every real worm

Tokens: All distinct substrings of a minimum length:  
e.g., If there are K occurrences of “http” “ttp” will not be considered unless it appears another K times and not as part of http

Token observed in all samples of the suspicious flow, but does not appear in every sample of the worm.

# Our Goal: Study Design Space for Combining Alerts

- With  $n$  tokens (or sensors) there are  $2^{2^n}$  possible fusion rules
- AND-rules and OR-rules are only 2 of them
- But there are many more: Majority voting, Select only one, etc...



# Which Fusion Rule is the Best?

- We want to find the “best” fusion rule(s):

$$g^* = \arg \max_{f \in \{g: \{0,1\}^n \rightarrow \{0,1\}\}} \Phi(f)$$

- Problem 1: Find the rules that give an optimal ROC curve
- Problem 2: Find the rules that minimize the operational “cost” of an IDS
- Problem 3: Prioritize alerts

# Our Solution: Likelihood Ratio Test (LRT)

- Each rule has a different False Alarm vs. False Negative tradeoff (we obtain a LRT estimate).
- LRT-Rule is optimal for Problem 1 (best ROC), Problem 2 (minimize costs) and Problem 3 (ranking of alarms).
- Principled (theoretically sound) and practical (useful and intuitive) way of combining intrusion detection sensors.

# Agenda

- Metric 1: Optimal ROC curve
- Metrics 2 & 3: Minimum cost and ranking
- Experiments
- Conclusions and Future Work

# Notation and Definitions

- Intrusion  $I=1$ , otherwise  $I=0$
- Output is  $Y=1$  (alarm),  $Y=0$  (no alarm)
- $P_F = \Pr[Y=1|I=0]$  and  $P_D = \Pr[Y=1|I=1]$
- There is a tradeoff between  $P_F$  and  $P_D$
- The ROC curve shows points  $(P_{FA}, P_D)$  for different “configurations” of an IDS



# Metric 1: Receiver Operating Characteristic (ROC) Curve

$$P_D = P[Y = 1 | \mathcal{H}_1]$$

Decision rate,  
True positive,  
Power

1

An ROC curve shows the tradeoff between the probability of false positives and the probability of true positives

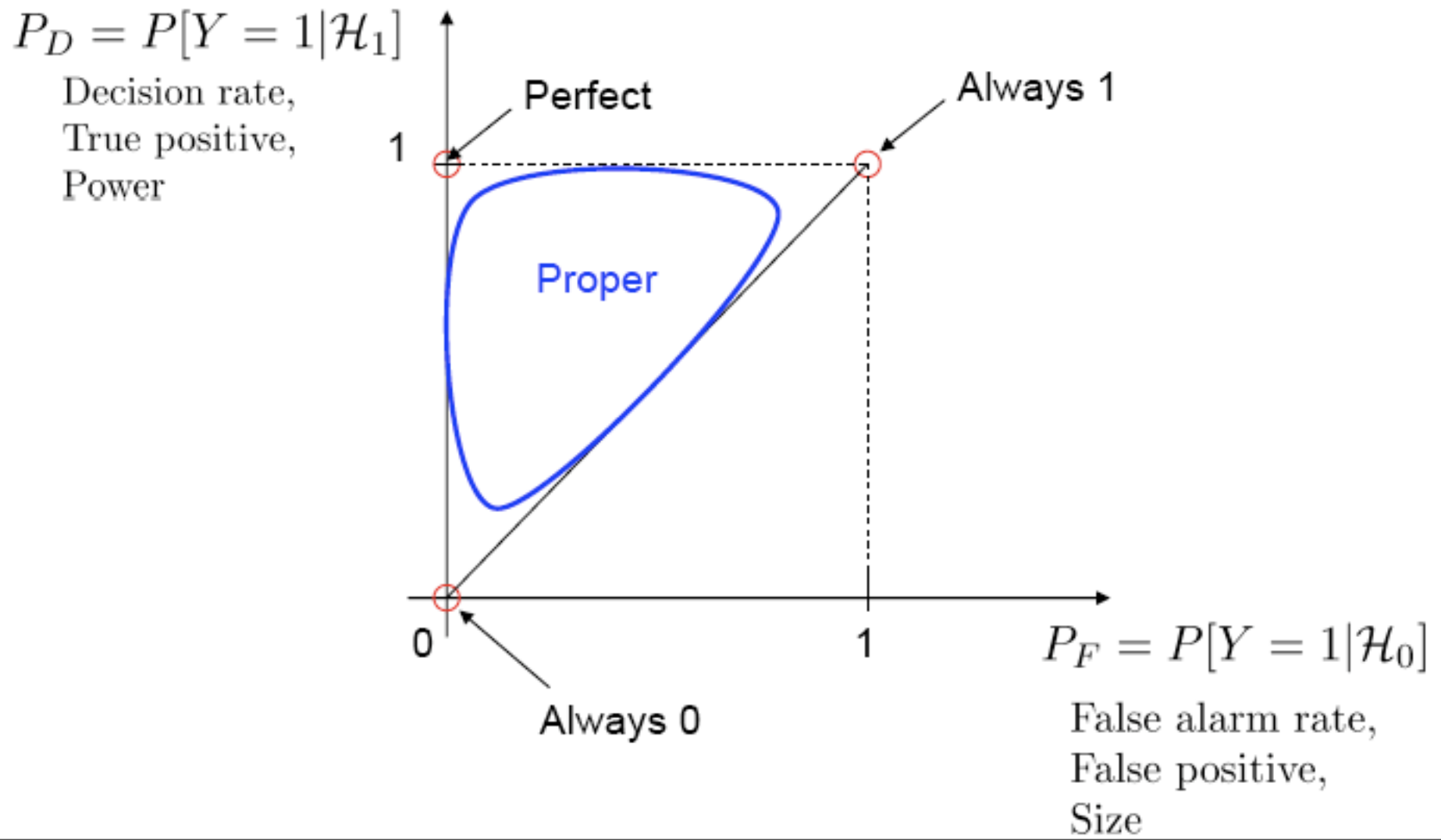
0

1

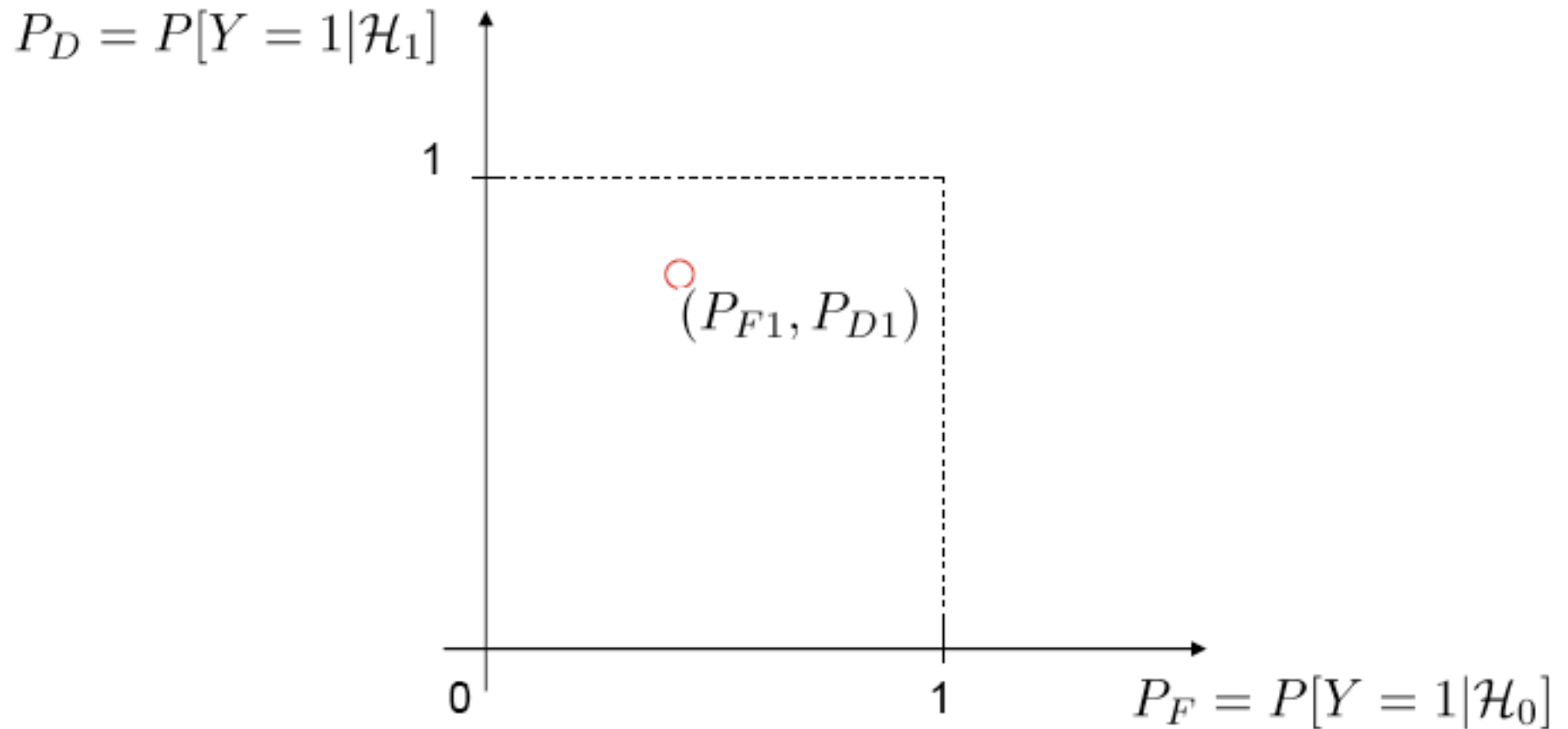
$$P_F = P[Y = 1 | \mathcal{H}_0]$$

False alarm rate,  
False positive,  
Size

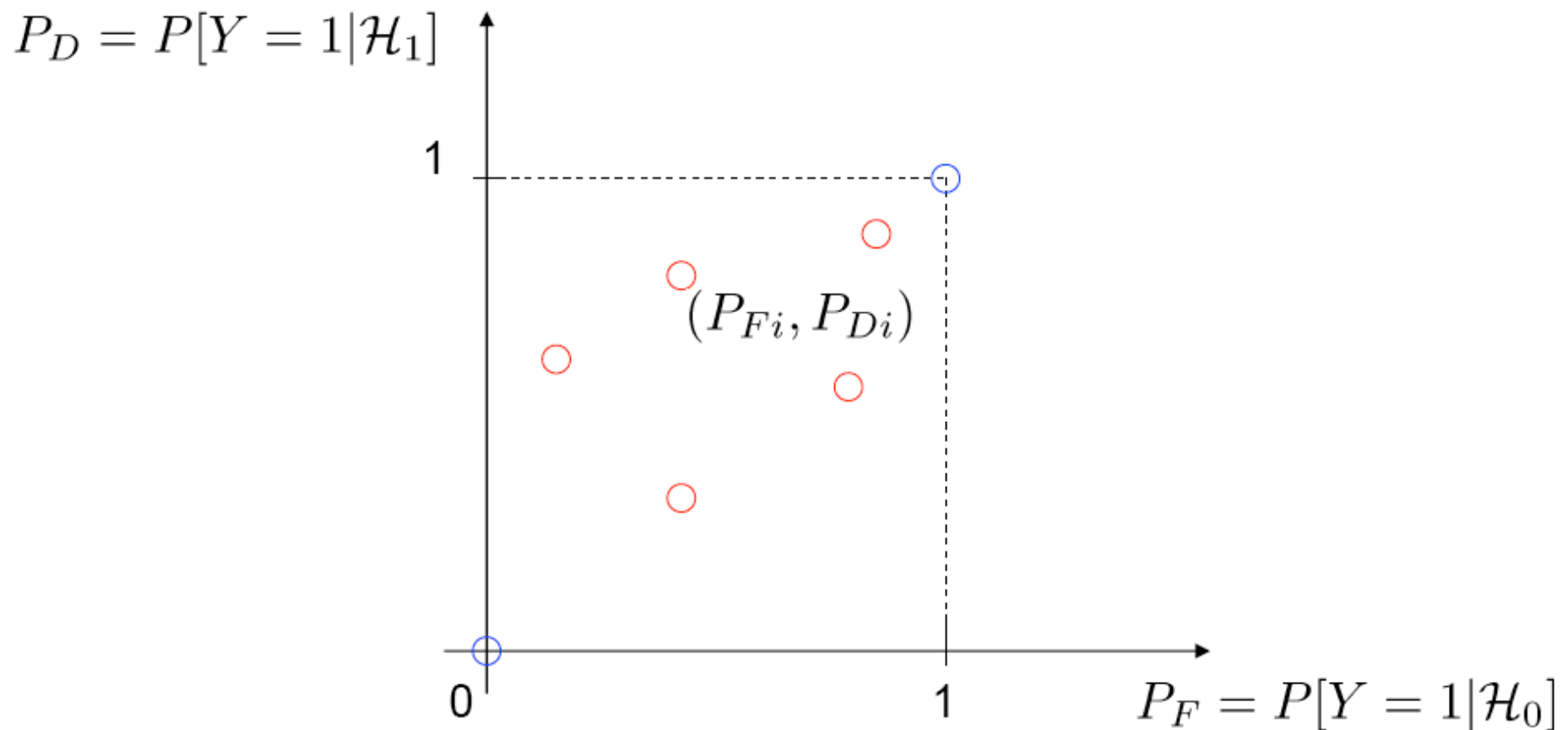
# Metric 1: Receiver Operating Characteristic (ROC) Curve



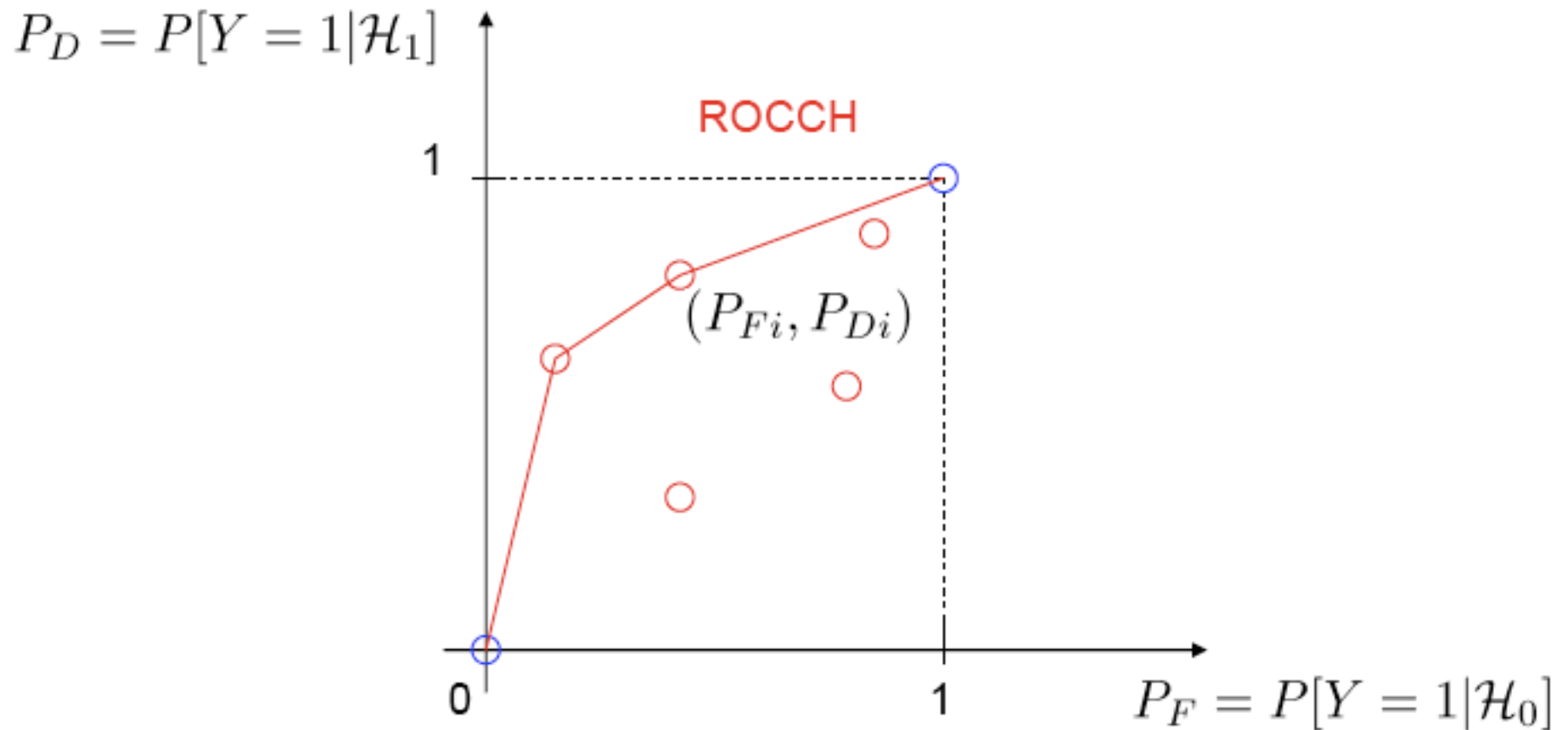
# Performance of Sensor\_1



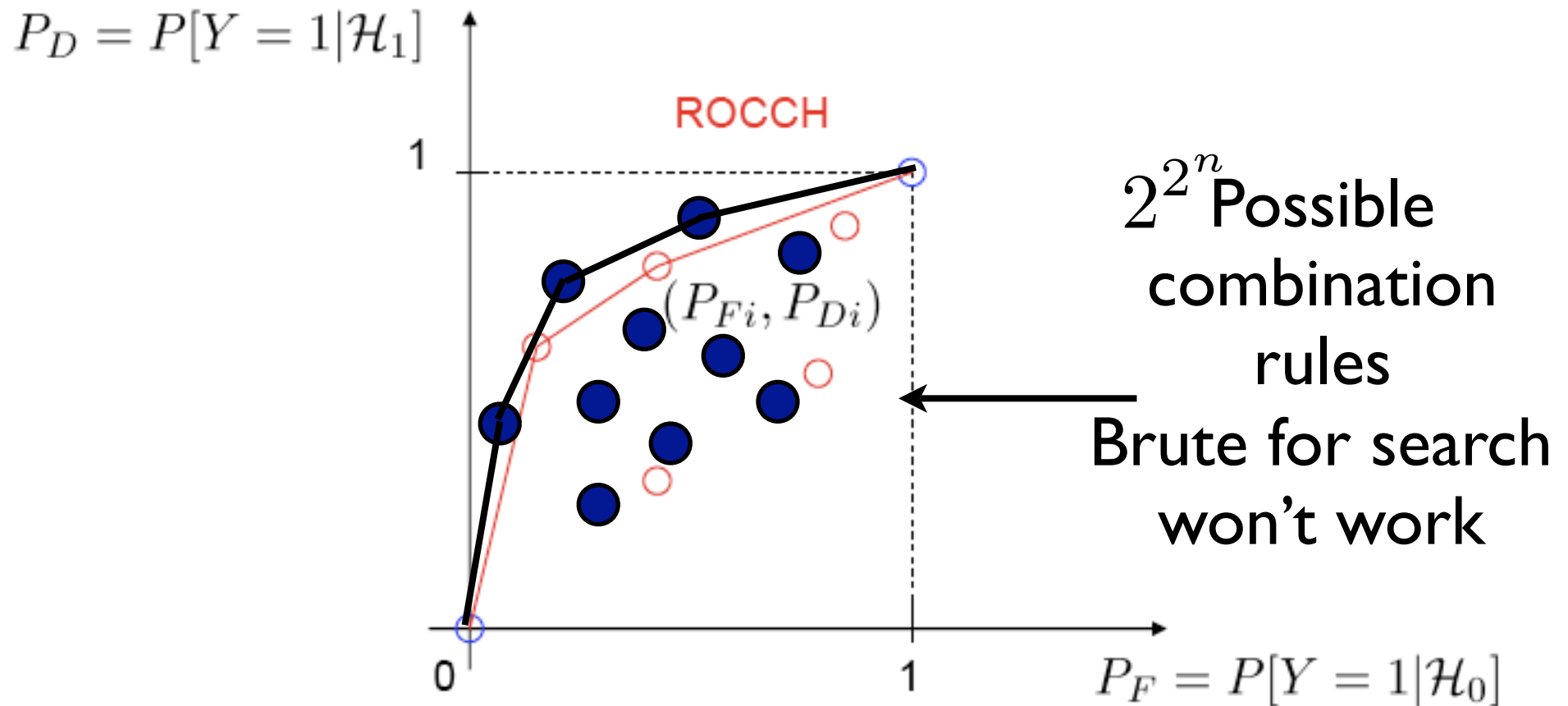
# $P_{Fi}$ and $P_{Di}$ estimates for multiple sensors



# Previous Work: The ROC Convex Hull (ROCCH)<sup>2</sup>



# ROCCH Gives Suboptimal ROC



# Neyman-Pearson Theory

- Given observation  $Y$ : test Null Hypothesis  $H_0$  vs. alternative  $H_1$
- If we know  $P(Y|H_0)$  and  $P(Y|H_1)$ , then the test  $D(Y)$  that maximizes  $P[D(Y)=H_1|H_1]$  for a fixed  $P[D(Y)=H_1|H_0]$  is:

$$D(Y) = \begin{cases} 1 & \text{if } \ell(Y) > \tau \\ \gamma & \text{if } \ell(Y) = \tau \\ 0 & \text{if } \ell(Y) < \tau \end{cases},$$

- Where  $l(Y) = P(Y|H_1)/P(Y|H_0)$  is the likelihood ratio.

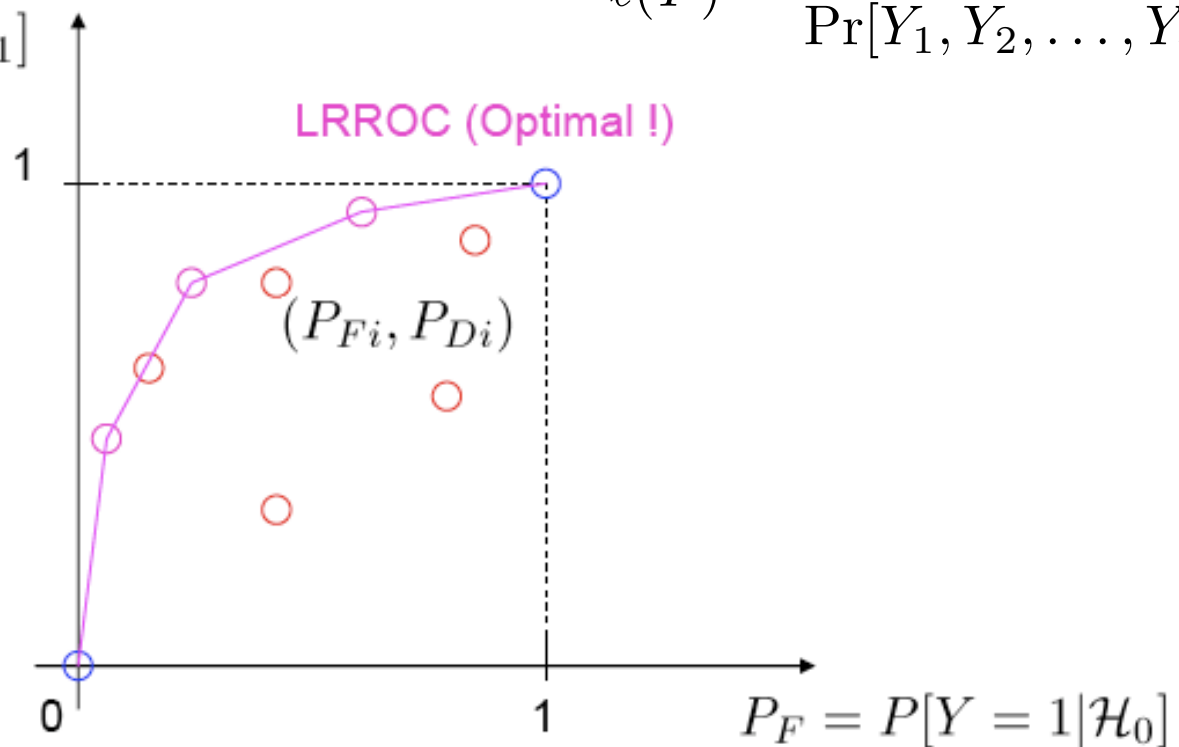
# Our Work: The Likelihood Ratio Test for Fusing Alarms

$$\mathcal{D}(\mathbf{Y}) = \begin{cases} 1 & \text{if } \ell(\mathbf{Y}) > \tau \\ \gamma & \text{if } \ell(\mathbf{Y}) = \tau \\ 0 & \text{if } \ell(\mathbf{Y}) < \tau \end{cases}, \quad \text{independence assumption} \quad \ell(\vec{1}) = \frac{P_{D1} \dots P_{Dn}}{P_{F1} \dots P_{Fn}}$$

$$P_D = P[Y = 1 | \mathcal{H}_1]$$

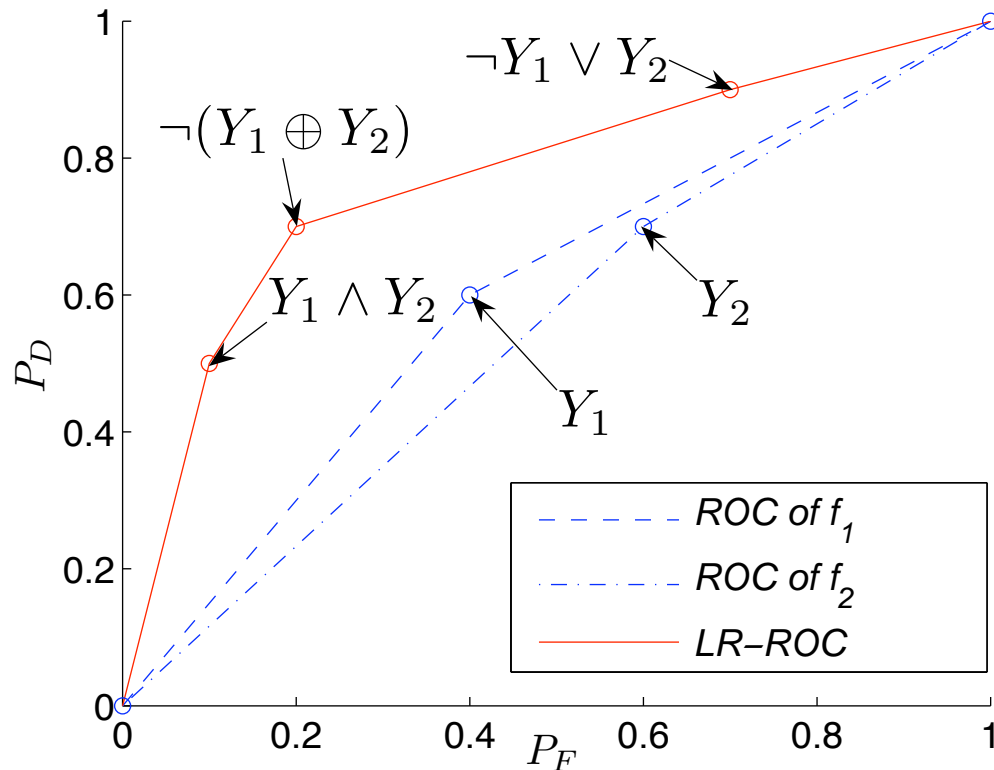
no independence  $\ell(\vec{Y}) = \frac{\Pr[Y_1, Y_2, \dots, Y_n | H_1]}{\Pr[Y_1, Y_2, \dots, Y_n | H_0]}$

Theorem: In general, optimal ROC has  $2^n + 1$  rules





# Example of the Likelihood-Ratio Test

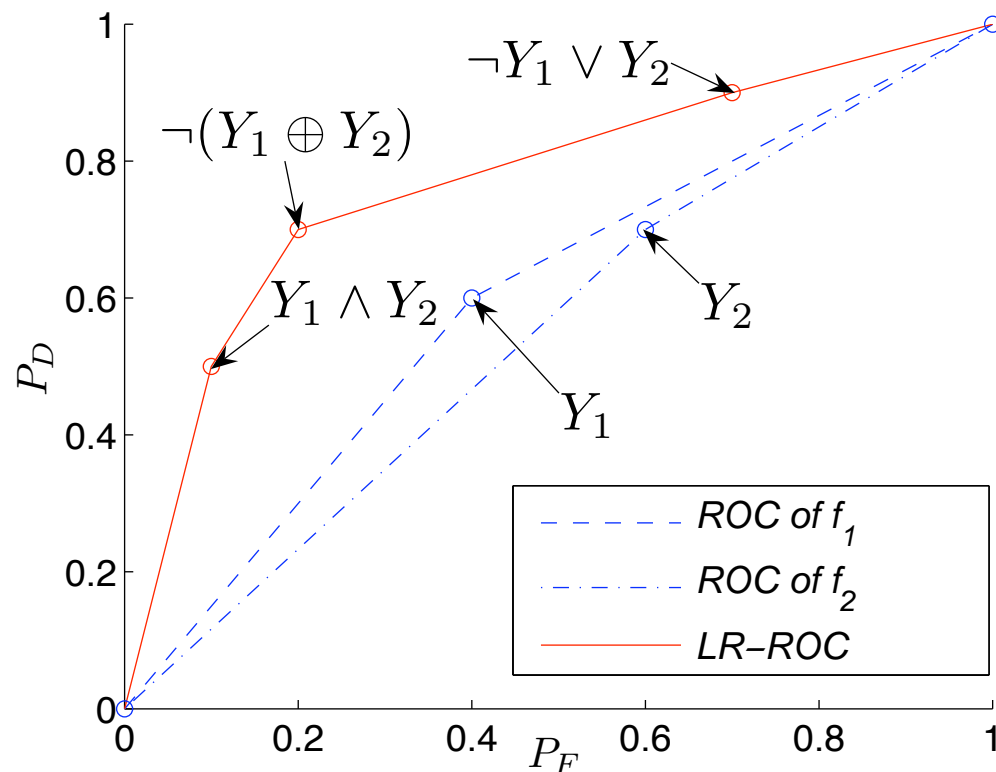


		Class 1 ( $H_1$ )	
		$Y_1$	
$Y_2$		0	1
0		0.2	0.1
1		0.2	0.5

		Class 0 ( $H_0$ )	
		$Y_1$	
$Y_2$		0	1
0		0.1	0.3
1		0.5	0.1

$$\ell(00)=2$$

# Example of the Likelihood-Ratio Test

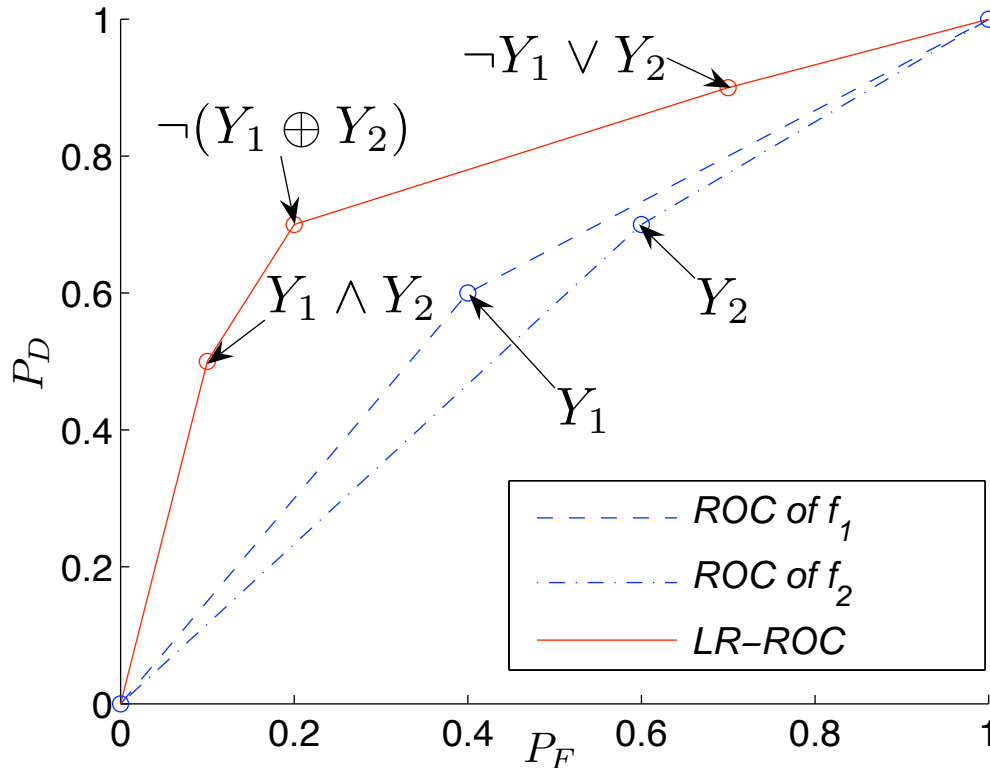


		Class 1 ( $H_1$ )	
		$Y_1$	
$Y_2$		0	1
0		0.2	0.1
1		0.2	0.5

		Class 0 ( $H_0$ )	
		$Y_1$	
$Y_2$		0	1
0		0.1	0.3
1		0.5	0.1

$$\ell(01) = 2/5 < \ell(00) = 2$$

# Example of the Likelihood-Ratio Test

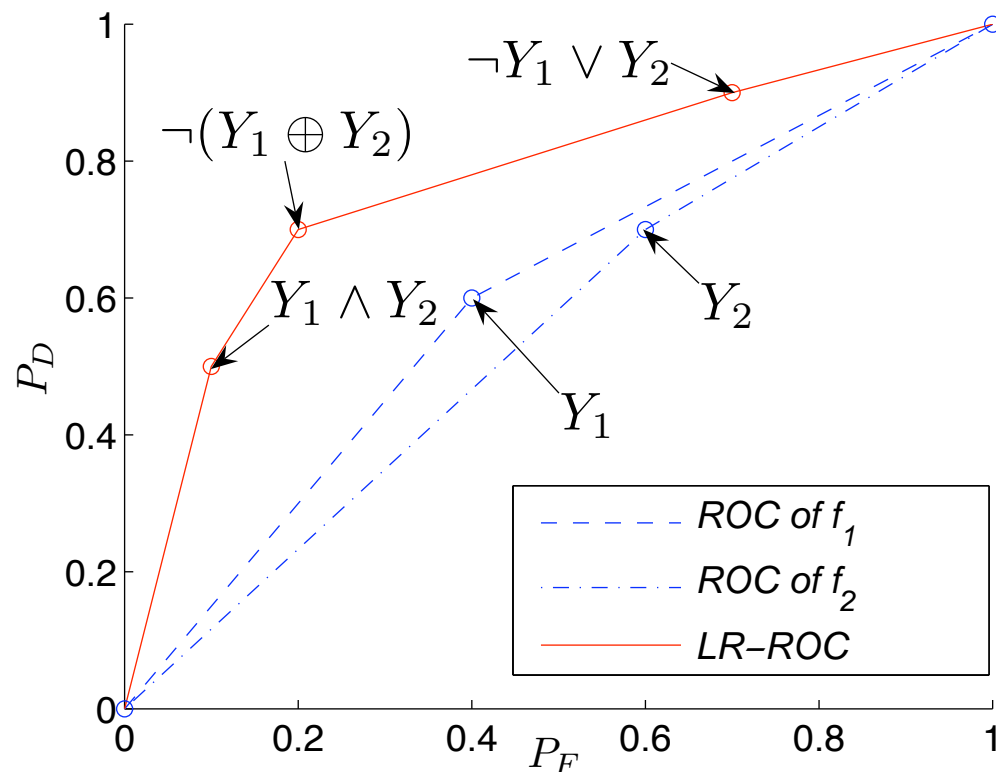


		Class 1 ( $H_1$ )		Class 0 ( $H_0$ )	
		$Y_1$		$Y_1$	
$Y_2$		0	1	0	1
0		0.2	0.1	0.1	0.3
1		0.2	0.5	0.5	0.1

$$\ell(10) = 1/3 <$$

$$\ell(01) = 2/5 < \ell(00) = 2$$

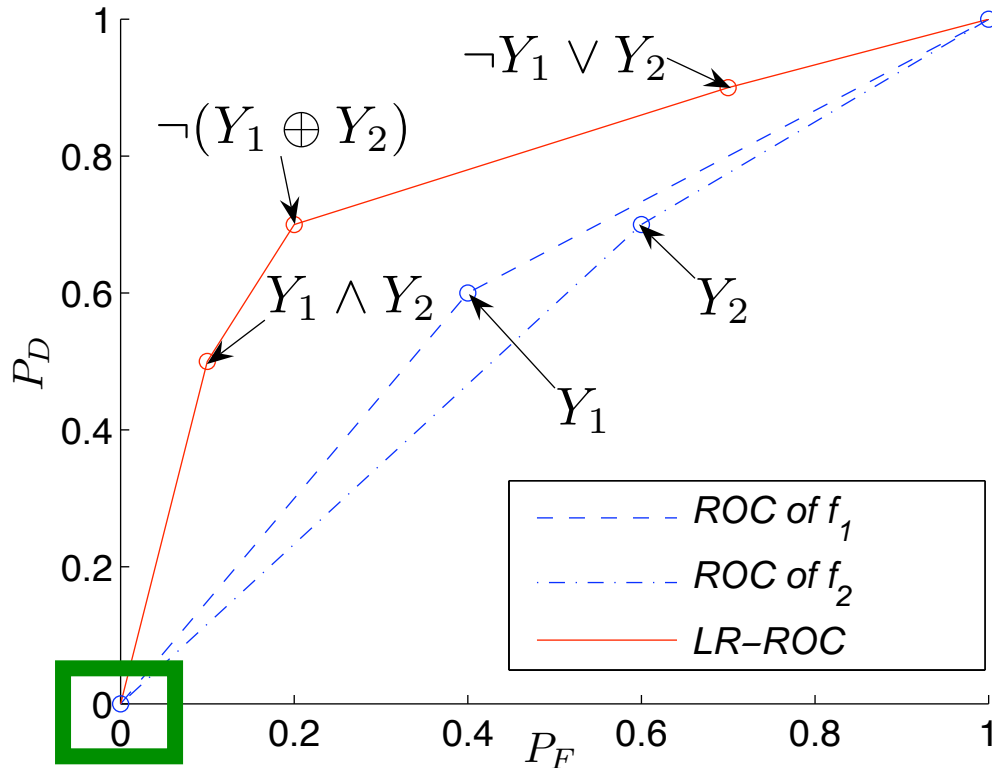
# Example of the Likelihood-Ratio Test



	Class 1 ( $H_1$ )		Class 0 ( $H_0$ )	
	$Y_1$		$Y_1$	
$Y_2$	0	1	0	1
0	0.2	0.1	0.1	0.3
1	0.2	0.5	0.5	0.1

$$\ell(10) = 1/3 < \ell(01) = 2/5 < \ell(00) = 2 < \ell(11) = 5$$

# Example of the Likelihood-Ratio Test



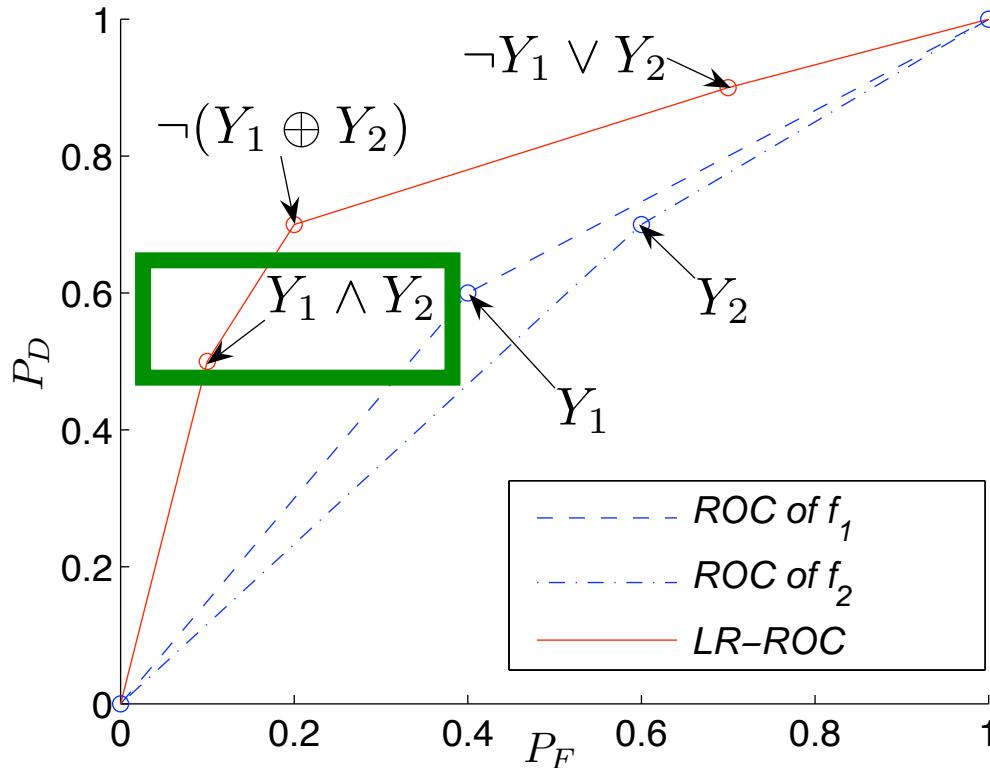
	Class 1 ( $H_1$ )		Class 0 ( $H_0$ )	
	$Y_1$		$Y_1$	
$Y_2$	0	1	0	1
0	0.2	0.1	0.1	0.3
1	0.2	0.5	0.5	0.1

$$l(10) < l(01) < l(00) < l(11)$$

$$Y_0 = 0$$

$\tau$

# Example of the Likelihood-Ratio Test



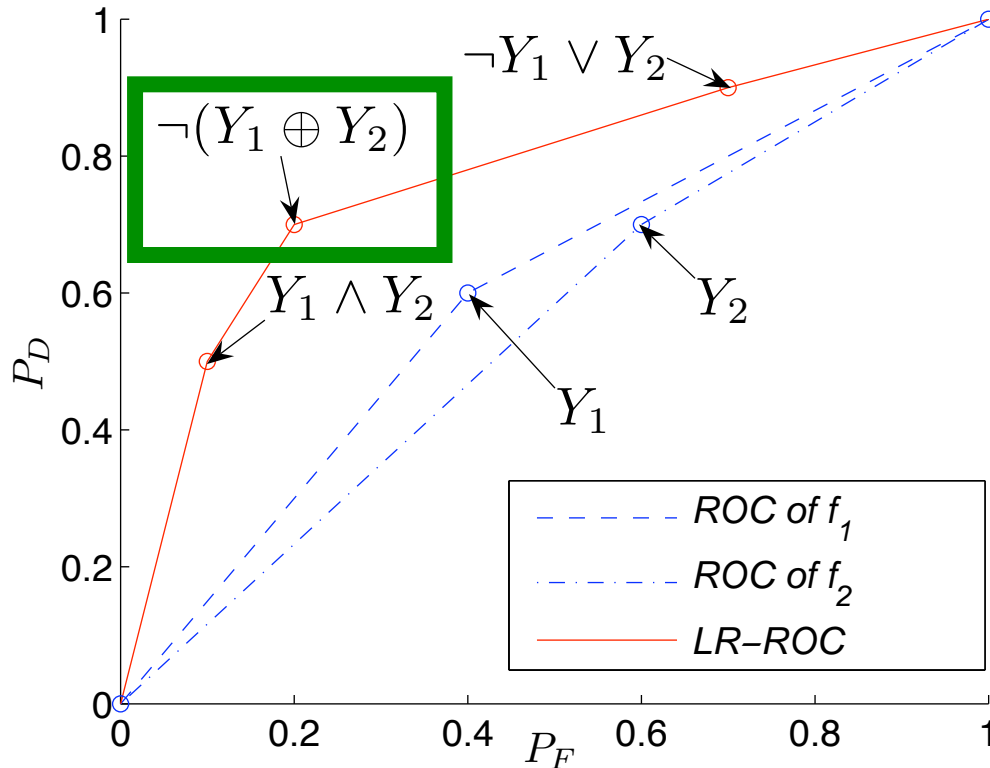
		Class 1 ( $H_1$ )	
		$Y_1$	
$Y_2$		0	1
0		0.2	0.1
1		0.2	0.5

		Class 0 ( $H_0$ )	
		$Y_1$	
$Y_2$		0	1
0		0.1	0.3
1		0.5	0.1

$$l(10) < l(01) < l(00) < l(11)$$

$$Y_0 = Y_1 \wedge Y_2$$

# Example of the Likelihood-Ratio Test



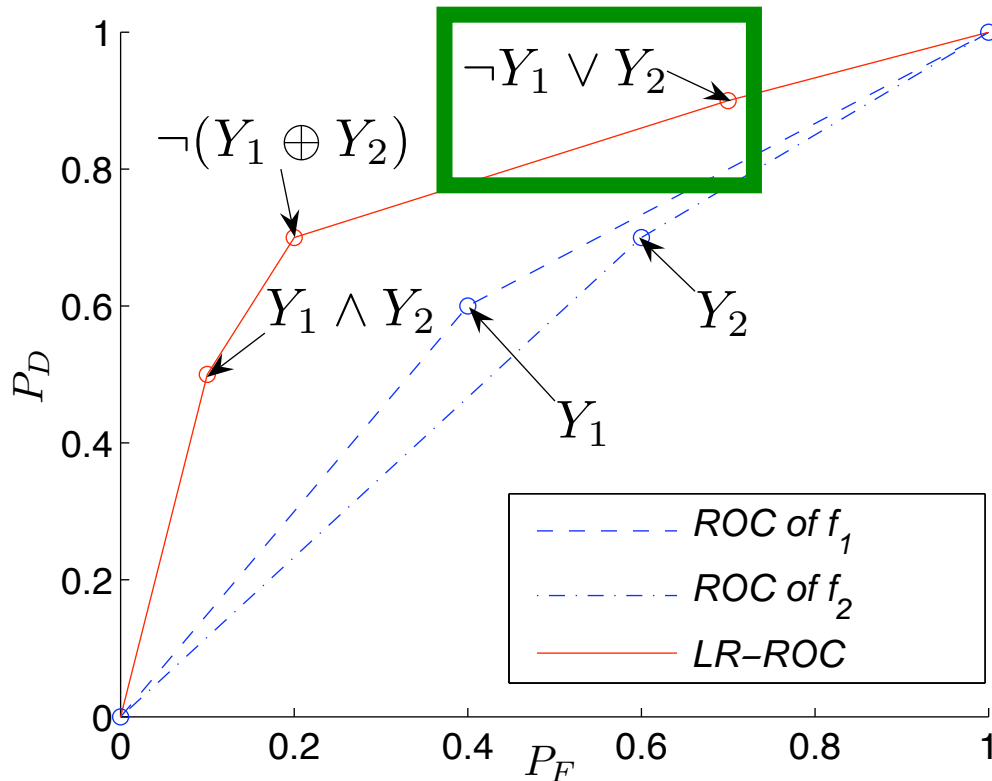
	Class 1 ( $H_1$ )		Class 0 ( $H_0$ )	
	$Y_1$		$Y_1$	
$Y_2$	0	1	0	1
0	0.2	0.1	0.1	0.3
1	0.2	0.5	0.5	0.1

$$l(10) < l(01) < l(00) < l(11)$$

$\tau$

$$\begin{aligned}
 Y_0 &= \bar{Y}_1 \bar{Y}_2 + Y_1 Y_2 \\
 &= \neg(Y_1 \oplus Y_2)
 \end{aligned}$$

# Example of the Likelihood-Ratio Test



	Class 1 ( $H_1$ )		Class 0 ( $H_0$ )	
	$Y_1$		$Y_1$	
$Y_2$	0	1	0	1
0	0.2	0.1	0.1	0.3
1	0.2	0.5	0.5	0.1

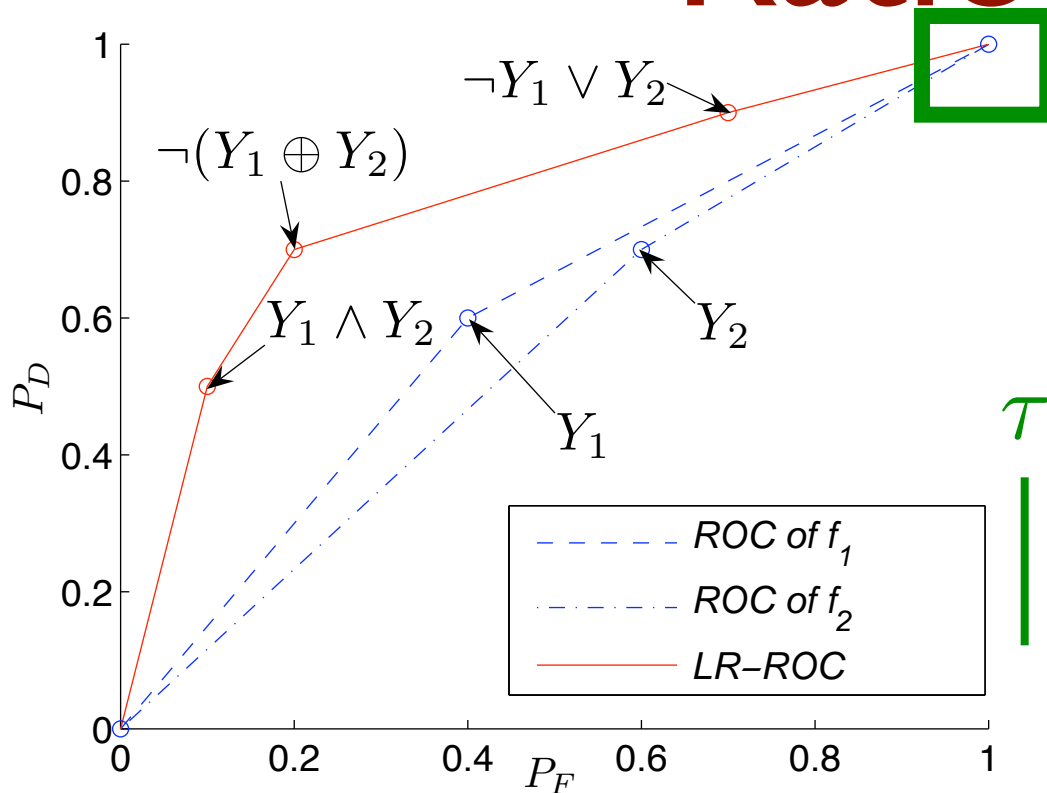
$\tau$

$$l(10) < l(01) < l(00) < l(11)$$

$$\begin{aligned}
 Y_0 &= \bar{Y}_1 Y_2 + \bar{Y}_1 \bar{Y}_2 + Y_1 Y_2 \\
 &= \neg Y_1 \vee Y_2
 \end{aligned}$$



# Example of the Likelihood-Ratio Test



		Class 1 ( $H_1$ )	
		$Y_1$	
$Y_2$		0	1
0		0.2	0.1
1		0.2	0.5

		Class 0 ( $H_0$ )	
		$Y_1$	
$Y_2$		0	1
0		0.1	0.3
1		0.5	0.1

$\tau$

$$l(10) < l(01) < l(00) < l(11)$$

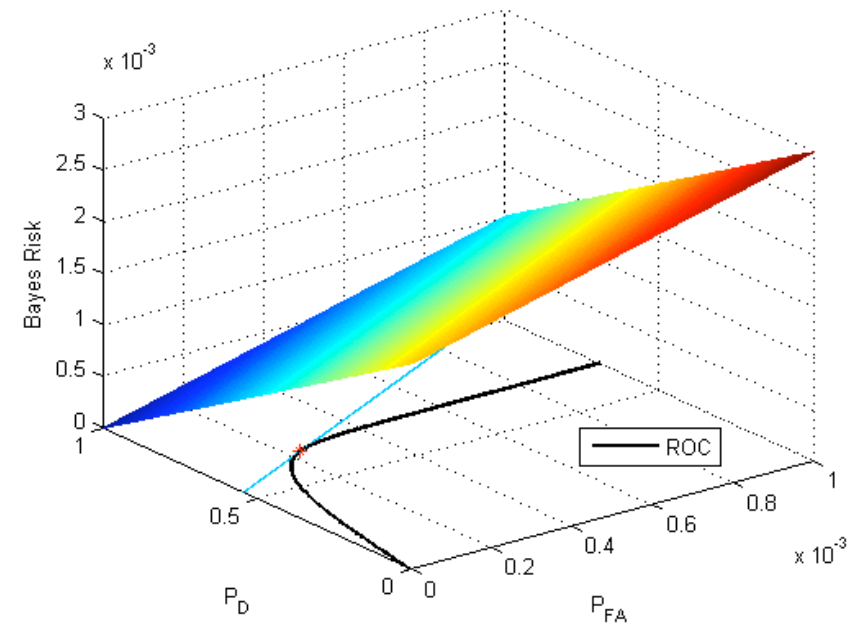
$$\begin{aligned}
 Y_0 &= Y_1 \bar{Y}_2 + \bar{Y}_1 Y_2 + \bar{Y}_1 \bar{Y}_2 + Y_1 Y_2 \\
 &= 1
 \end{aligned}$$

# Agenda

- Metric 1: Optimal ROC curve
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# Metric 2: Expected Cost

- $C_{01}$ =Cost of a false alarm
- $C_{10}$ =Cost of a missed intrusion
- Expected Cost is a function of  $P_F$  and  $P_D$
- The rule that minimizes the expected cost will lie in the ROC curve



# Metric 3: Prioritization of Alerts

- The likelihood ratio is an estimate of the confidence for hypothesis  $H_1$
- Example:  $l(01) < l(10) \Rightarrow$
- The alert given by  $Y_1=1, Y_2=0$  should take priority over  $Y_1=0, Y_2=1$ .

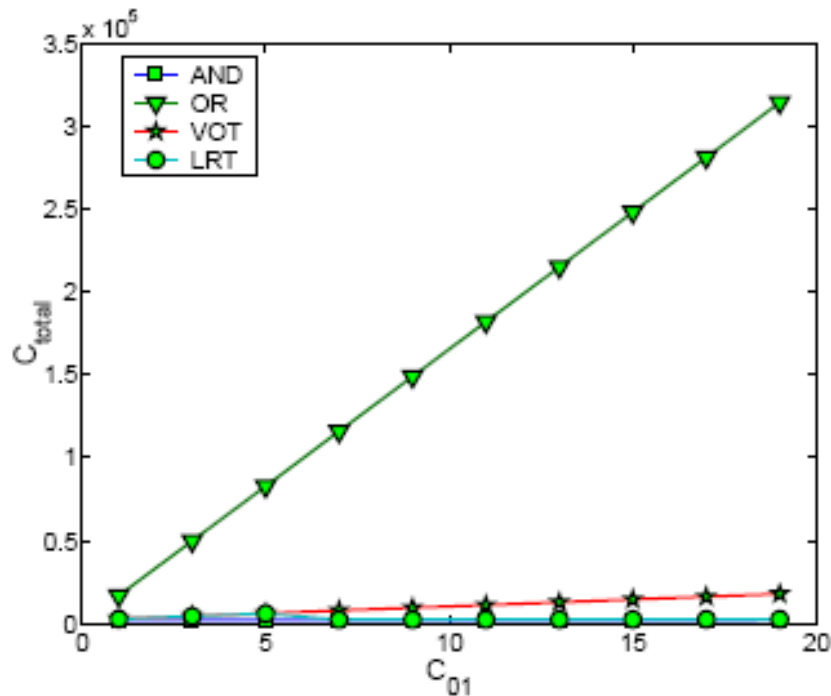
# Agenda

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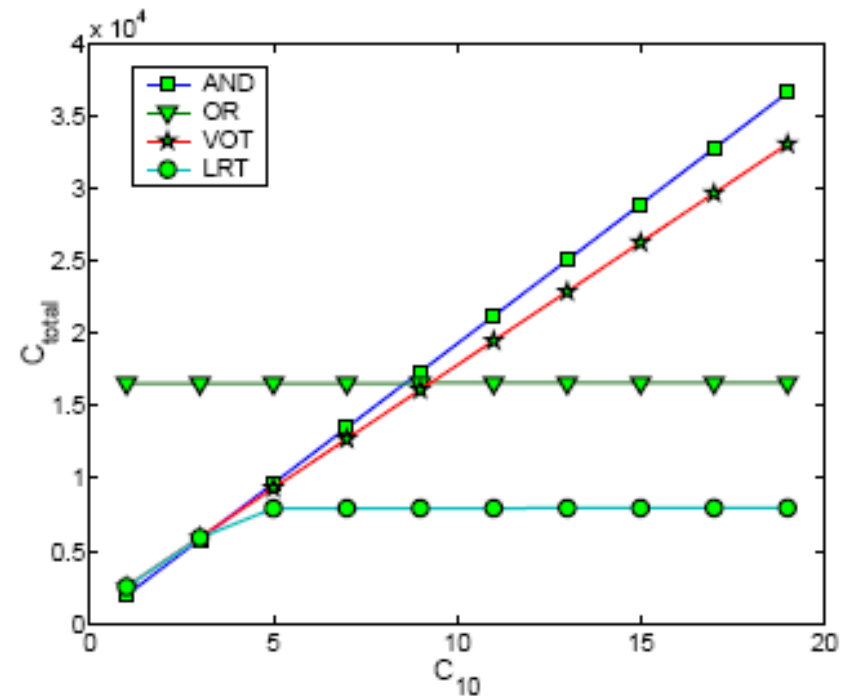
# Experiment Setup

- Dataset
  - Collected 30 minute HTTP trace (5 million packets) at College of Computing, Georgia Tech
  - Divided into two halves: training and testing set
  - Injected web attacks into testing set using tools, e.g., libwhisker (*base rate* 0.00082)
- Real-world IDSs
  - Snort (V2.3): signature based detection
  - PAYL: anomaly detector based on byte frequency within the payload
  - NetAD: modeling 48 attributes (48 bytes at fixed locations), summing up anomaly score based on byte frequency (within history, at the same location)

# Experiment: Result



(a) Fix the cost of  $FN$  ( $C_{10} = 1$ ) in all the cases, change the cost of  $FP$  ( $C_{01}$ ).



(b) Fix the cost of  $FP$  ( $C_{01} = 1$ ) in all the cases, change the cost of  $FN$  ( $C_{10}$ ).

# Experiment: Prioritization of Alerts

- Example: When PAYL raises an alarm alone, it should take precedence over when Snort and NetAD raise an alarm, but PAYL does not:

$$l(000) < l(001) < l(100) < l(101) < l(010) < l(011) < l(110) < l(111)$$

	Snort	PAYL	NetAD
$P_D$	0.016	0.99896	0.1037
$P_F$	0.0000237	0.00336	0.004

$$\begin{aligned} \text{Snort} &= Y_1 \\ \text{PAYL} &= Y_2 \\ \text{NetAD} &= Y_3 \end{aligned}$$



# Conclusions and Future Work

- We presented a theoretically sound and intuitive method for fusing alerts
- We generalized and improved previous work
- We plan to extend work to probabilistic IDS, and anomaly detectors