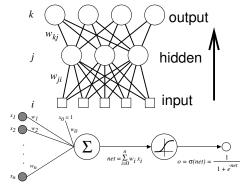
Deep Learning Overview

- Spring 2017
- Yoonsuck Choe

1

Brief Intro to Neural Networks



Deep learning is based on neural networks.

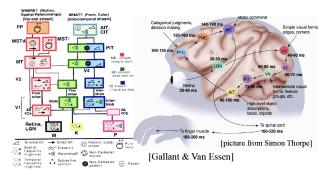
- Weighted sum followed by nonlinear activation function.
- Weights adjusted using *gradient descent* (η = learning rate):

$$w_{ij} \leftarrow w_{ij} + \eta \frac{\partial E}{\partial w_{ij}}$$

What Is Deep Learning?

- Learning higher level abstractions/representations from data.
- Motivation: how the brain represents and processes sensory information in a hierarchical manner.

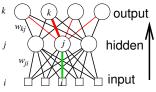
■ The ventral (recognition) pathway in the visual cortex has multiple stages
■ Retina - LGN - V1 - V2 - V4 - PIT - AIT



From LeCun's Deep Learning Tutorial

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Intro to Neural Network: Backpropagation



Weight w_{ji} is updated as: $w_{ji} \leftarrow w_{ji} + \eta \delta_j a_i$, where

- ullet a_i : activity at input side of weight w_{ji} .
- ullet Hidden to output weights (thick red weight). T_k is target value.

$$\delta_k = (T_k - a_k)\sigma'(net_k)$$

• Deeper weights (green line in figure above).

$$\delta_j = \left[\sum_k w_{kj} \delta_k\right] \sigma'(net_j)$$

Deep Learning

- Complex models with large number of parameters
 - Hierarchical representations
 - More parameters = more accurate on training data
 - Simple learning rule for training (gradient-based).
- Lots of data
 - Needed to get better generalization performance.
 - High-dimensional input need exponentially many inputs (curse of dimensionality).
- Lots of computing power: GPGPU, etc.
 - Training large networks can be time consuming.

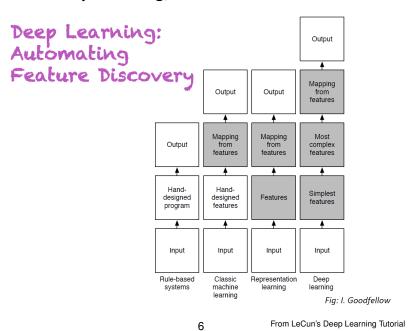
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The Rise of Deep Learning

Made popular in recent years

- Geoffrey Hinton et al. (2006).
- Andrew Ng & Jeff Dean (Google Brain team, 2012).
- Schmidhuber et al.'s deep neural networks (won many competitions and in some cases showed super human performance; 2011–). Recurrent neural networks using LSTM (Long Short-Term Memory).
- Google Deep Mind: Atari 2600 games (2015), AlphaGo (2016).
- ICLR, International Conference on Learning Representations:
 First meeting in 2013.
- First deep learning textbook (Goodfellow, Bengio, Courville, 2016).

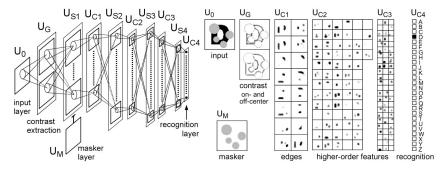
Deep Learning, in the Context of AI/ML



Long History (in Hind Sight)

- Fukushima's Neocognitron (1980).
- LeCun et al.'s Convolutional neural networks (1989).
- Schmidhuber's work on stacked recurrent neural networks (1993).
 Vanishing gradient problem.
- See Schmidhuber's extended review: Schmidhuber, J. (2015).
 Deep learning in neural networks: An overview. *Neural Networks*, 61, 85-117.

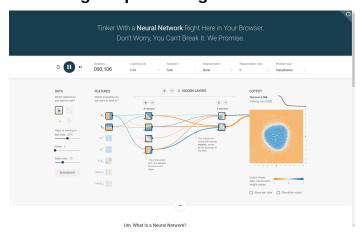
History: Fukushima's Neocognitron



- Appeared in journal *Biological Cybernetics* (1980).
- Multiple layers with local receptive fields.
- S cells (trainable) and C cells (fixed weight).
- Deformation-resistent recognition.

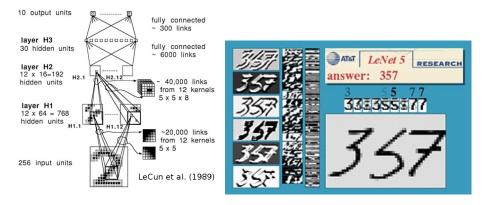
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Motivating Deep Learning: Tensorflow Demo



- http://playground.tensorflow.org
- Demo to explore why deep nnet is powerful and how it is limited.

History: LeCun's Colvolutional Neural Nets



- Convolution kernel (weight sharing) + Subsampling
- Fully connected layers near the end.
- Became a main-stream method in deep learning.

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Current Trends

- Deep belief networks (based on Boltzmann machine)
- Convolutional neural networks
- Deep Q-learning Network (extensions to reinforcement learning)
- Deep recurrent neural networks using (LSTM)
- Applications to diverse domains.
 - Vision, speech, video, NLP, etc.
- Lots of open source tools available.

Boltzmann Machine to Deep Belief Nets

 Haykin Chapter 11: Stochastic Methods rooted in statistical mechanics.

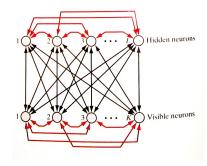
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Boltzmann Machine: Energy

- Network state: **x** from random variable **X**.
- $w_{ij} = w_{ji}$ and $w_{ii} = 0$.
- Energy (in analogy to thermodynamics):

$$E(\mathbf{x}) = -\frac{1}{2} \sum_{i} \sum_{j,i \neq j} w_{ji} x_i x_j$$

Boltzmann Machine



- Stochastic binary machine: +1 or -1.
- Fully connected symmetric connections: $w_{ij} = w_{ji}$.
- Visible vs. hidden neurons, clamped vs. free-running.
- Goal: Learn weights to model prob. dist of visible units.
- Unsupervised. Pattern completion.

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Boltzmann Machine: Prob. of a State x

• Probability of a state x given E(x) follows the *Gibbs distribution*:

$$P(\mathbf{X} = \mathbf{x}) = \frac{1}{Z} \exp\left(-\frac{E(\mathbf{x})}{T}\right),$$

- Z: partition function (normalization factor - hard to compute)

$$Z = \sum_{\forall \mathbf{x}} \exp(-E(\mathbf{x})/T)$$

- T: temperature parameter.
- Low energy states are exponentially more probable.
- State ${\bf x}$ changed over time following the probability distribution $P({\bf X}={\bf x}).$

Boltzmann Learning Rule

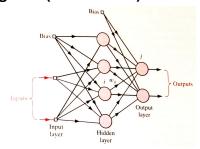
• Learning based on correlation ρ_{ji}^+ (clamped) and ρ_{ji}^- (free-running).

$$\Delta w_{ji} = \eta \frac{\partial L(\mathbf{w})}{\partial w_{ji}} = \eta \left(\rho_{ji}^+ - \rho_{ji}^- \right)$$

where $L(\mathbf{w})$ is the log likelihood of the pattern being any of the training patterns, and η is the learning rate. This is *gradient* ascent.

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Logistic (or Directed) Belief Net



Similar to Boltzmann Machine, but with directed, acyclic connections.

$$P(X_j = x_j | X_1 = x_1, ..., X_{j-1} = x_{j-1}) = P(X_j = x_j | parents(X_j))$$

• Same learning rule:

$$\Delta w_{ji} = \eta \frac{\partial L(\mathbf{w})}{\partial w_{ji}}$$

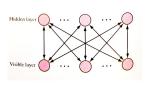
 $\bullet\,$ With dense connetions, calculation of P becomes intractable.

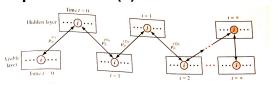
Boltzmann Machine Summary

- Theoretically elegant.
- Can be very slow.

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Deep Belief Net (1)





- Overcomes issues with Logistic Belief Net. Hinton et al. (2006)
- Based on Restricted Boltzmann Machine (RBM): visible and hidden layers, with layer-to-layer full connection but no within-layer connections.
- RBM Back-and-forth update: update hidden given visible, then update visible given hidden, etc., then train w based on

$$\frac{\partial L(\mathbf{w})}{\partial w_{ji}} = \rho_{ji}^{(0)} - \rho_{ji}^{(\infty)}$$

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Deep Belief Net (2)

Deep Belief Net = Layer-by-layer training using RBM.

Hybrid architecture: Top layer = undirected, lower layers directed.

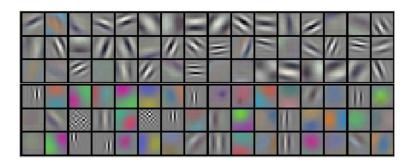
- 1. Train RBM based on input to form hidden representation.
- 2. Use hidden representation as input to train another RBM.
- 3. Repeat steps 2-3.

* Similar approach: Stacked denoising autoencoders.

Applications: NIST digit recognition, etc.

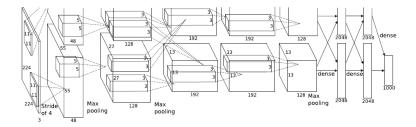
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Deep Convolutional Neural Networks (2)



- Learned kernels (first convolutional layer).
- Resembles mammalian RFs: oriented Gabor patterns, color opponency (red-green, blue-yellow).

Deep Convolutional Neural Networks (1)



- Krizhevsky et al. (2012)
- Applied to ImageNet competition (1.2 million images, 1,000 classes).
- Network: 60 million parameters and 650,000 neurons.
- Top-1 and top-5 error rates of 37.5% and 17.0%.
- Trained with backprop.

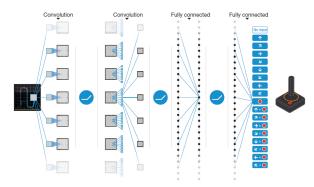
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Deep Convolutional Neural Networks (3)



- Left: text on top = correct label. 5 ranked labels: model's estimation.
- Right: Test (1st column) vs. training images with closest hidden representation to the test data.

Deep Q-Network (DQN)



Google Deep Mind (Mnih et al. Nature 2015).

- Latest application of deep learning to a reinforcement learning domain (Q as in Q-learning).
- Applied to Atari 2600 video game playing.

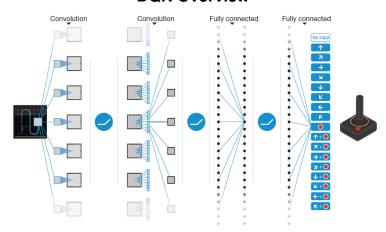
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DQN Overview

- Input preprocessing
- Experience replay (collect and replay state, action, reward, and resulting state)
- Delayed (periodic) update of Q.
- Moving target \hat{Q} value used to compute error (loss function L, parameterized by weights θ_i).
 - Gradient descent:

 $\frac{\partial L}{\partial \theta_i}$

DQN Overview



- Input: video screen; Output: Q(s, a); Reward: game score.
- Q(s, a): action-value function

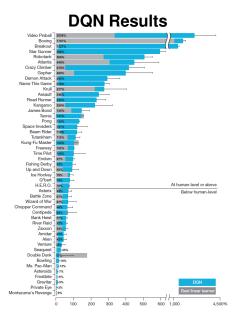
End For

- Value of taking action a when in state s.

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DQN Algorithm

Algorithm 1: deep Q-learning with experience replay. Initialize replay memory D to capacity NInitialize action-value function Q with random weights θ Initialize target action-value function \hat{Q} with weights $\theta^- = \theta$ For episode = 1, M do Initialize sequence $s_1 = \{x_1\}$ and preprocessed sequence $\phi_1 = \phi(s_1)$ For t = 1,T do With probability ε select a random action a_t otherwise select $a_t = \operatorname{argmax}_a Q(\phi(s_t), a; \theta)$ Execute action a_t in emulator and observe reward r_t and image x_{t+1} Set $s_{t+1} = s_t, a_t, x_{t+1}$ and preprocess $\phi_{t+1} = \phi(s_{t+1})$ Store transition $(\phi_t, a_t, r_t, \phi_{t+1})$ in DSample random minibatch of transitions $(\phi_i, a_i, r_j, \phi_{i+1})$ from Dif episode terminates at step j+1 $Set y_j = \begin{cases} r_j \\ r_j + \gamma \max_{a'} \hat{Q}(\phi_{j+1}, a'; \theta^-) \end{cases}$ otherwise Perform a gradient descent step on $(y_j - Q(\phi_j, a_j; \theta))^2$ with respect to the network parameters θ Every C steps reset $\hat{Q} = Q$ **End For**



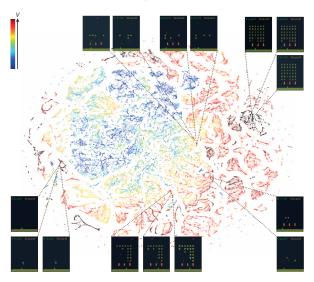
• Superhuman performance on over half of the games.

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DQN Operation a Dose silvery and the second secon

• Value vs. game state; Game state vs. action value.

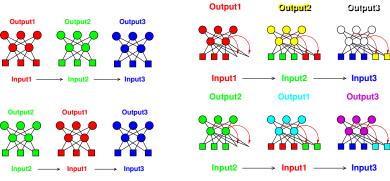
DQN Hidden Layer Representation (t-SNE map)



• Similar perception, similar reward clustered.

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Deep Recurrent Neural Networks



Recurrent

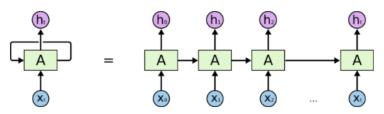
- Feedforward: No memory of past input.
- Recurrent:

Feedforward

- Good: Past input affects present output.
- Bad: Cannot remember far into the past.

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RNN Training: Backprop in Time



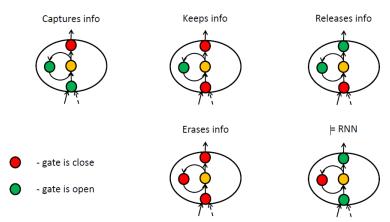
An unrolled recurrent neural network.

- Can unfold recurrent loop: Make it into a feedforward net.
- Use the same backprop algorithm for training.
- Again, cannot remember too far into the past.

Fig from http://colah.github.io/posts/2015-08-Understanding-LSTMs/

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Long Short-Term Memory

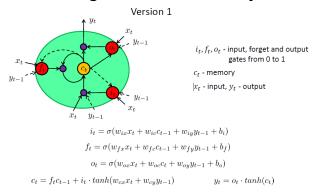


• Long-term retention possible with LSTM.

From http:

//www.machinelearning.ru/wiki/images/6/6c/RNN_and_LSTM_16102015.pdf

Long Short-Term Memory



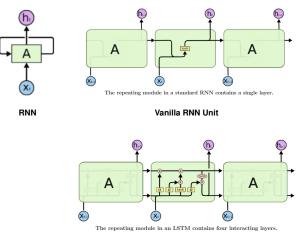
- LSTM to the rescue (Hochreiter and Schmidhuber, 2017).
- Built-in recurrent memory that can be written (Input gate), reset (Forget gate), and outputted (Output gate).

From http:

//www.machinelearning.ru/wiki/images/6/6c/RNN_and_LSTM_16102015.pdf

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Long Short-Term Memory in Action

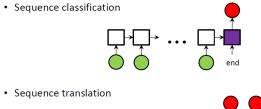


• Unfold in time and use backprop as usual.

Fig from http://colah.github.io/posts/2015-08-Understanding-LSTMs/

LSTM Unit

LSTM Applications



Input sequence

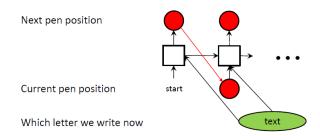
• Applications: Sequence classification, Sequence translation.

From http://machinelearning.ru

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LSTM Applications

text -> handwriting



 Applications: Sequence classification, Sequence prediction, Sequence translation.

From http://machinelearning.ru

LSTM Applications

handwriting -> handwriting

Next pen position (we predict parameters): x1,x2 - mixture of bivariate Gaussians x3 - Bernoulli distribution İstart

Current pen position: x1,x2 – pen offset x3 – is it end of the stroke

under

• Applications: Sequence prediction

From http://machinelearning.ru

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Deep Learning Applications: Vision

Give the name of the dominant object in the image

Top-5 error rates: if correct class is not in top 5, count as error

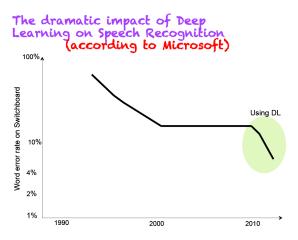
▶ Red:ConvNet, blue: no ConvNet

2012 Teams	%error		2013 Teams	%error		2014 Teams	%error
Supervision (Toronto)	15.3		Clarifai (NYU spinoff)	11.7		GoogLeNet	6.6
ISI (Tokyo)	26.1		NUS (singapore)	12.9		VGG (Oxford)	7.3
VGG (Oxford)	26.9	١	Zeiler-Fergus (NYU)	13.5	١	MSRA	8.0
XRCE/INRIA	27.0	١	A. Howard	13.5	١	A. Howard	8.1
UvA (Amsterdam)	29.6	١	OverFeat (NYU)	14.1	١	DeeperVision	9.5
INRIA/LEAR	33.4		UvA (Amsterdam)	14.2		NUS-BST	9.7
			Adobe	15.2		TTIC-ECP	10.2
			VGG (Oxford)	15.2		XYZ	11.2
			VGG (Oxford)	23.0		UvA	12.1

• ConvNet sweepting image recognition challenges.

From LeCun's Deep Learning Tutorial

Deep Learning Applications: Speech

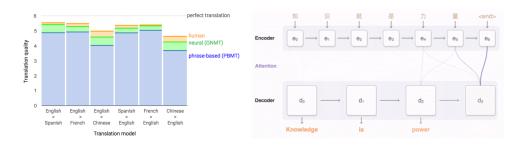


• Deep learning led to major improvement in speech recognition.

From LeCun's Deep Learning Tutorial

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Deep Learing Applications: NLP

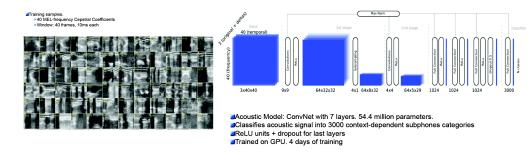


Based on encoding/decoding and attention.

From https:

//research.googleblog.com/2016/09/a-neural-network-for-machine.html

Deep Learning Applications: Speech

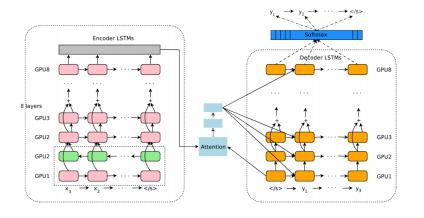


- ConvNet applied to speech recognition.
- Use spectrogram and treat it like a 2D image.

From LeCun's Deep Learning Tutorial

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Deep Learing Applications: NLP



• Google's LSTM-based machine translation.

Wu et al. arXiv:1609.08144 (2016).

Limitations

- Discriminative vs. generative learning.
 - Discriminative: P(class|data). Can easily be fooled with adversarial input.
 - Generative: $P(class,data) = P(class|data)P(data). \ \mbox{Explicitly}$ models the data.
- Deep neural nets mostly use discriminative learning, so can be fooled by adversarial input. Generative adversarial learning can overcome this (Goodfellow et al. arXiv:1406.2661 (2014)).

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Summary

- Deep belief network: Based on Boltzmann machine. Elegant theory, good performance.
- Deep convolutional networks: High computational demand, over the board great performance.
- Deep Q-Network: unique apporach to reinforcement learning.
 End-to-end machine learning. Super-human performance.
- Deep recurrent neural networks: sequence learning. LSTM a powerful mechanism.
- Diverse applications. Top performance.
- Flood of deep learning tools available.

Deep Learning Tools

- Kaffe: UC Berkeley's deep learning tool box
- TensorFlow (Google)
- Deep learning modules for Torch (Facebook)
- Microsoft CNTK (Computational Network Tool Kit)
- Other: Apache Mahout (MapReduce-based ML)

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