CSCE 636 Neural Networks (Deep Learning)

Lecture 16: Auto-Encoder

Anxiao (Andrew) Jiang

Based on the interesting lecture of Prof. Hung-yi Lee "Unsupervised Learning: Deep Auto-Encoder" https://www.youtube.com/watch?v=Tk5B4seA-AU&list=PLJV_el3uVTsPy9oCRY30oBPNLCo89yu49&index=25



Methods: (1) Make output data be as close to input data as possible (2) Limit the size of the encoder's output

Use of encoder: it can extract useful features from input data; the useful features can be used by many applications. Use of decoder: it can generate realistic data from random inputs.

Nice property of auto-encoder: it can be trained without labels for data.







• Of course, the auto-encoder can be deep



Reference: Hinton, Geoffrey E., and Ruslan R. Salakhutdinov. "Reducing the dimensionality of data with neural networks." *Science* 313.5786 (2006): 504-507

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Vector Space Model



Vector Space Model



Vector Space Model





Creat http:/

The documents talking about the same thing will have close code.





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Created with EverCam http://www.camdemy.c

Retrieved using Euclidean distance in pixel intensity space

Reference: Krizhevsky, Alex, and Geoffrey E. Hinton. "Using very deep autoencoders for content-based image retrieval." ESANN. 2011

Retrieved using Euclidean distance in pixel intensity space



(Images from Hinton's slides on Coursera)

Reference: Krizhevsky, Alex, and Geoffrey E. Hinton. "Using very deep autoencoders for content-based image retrieval." ESANN. 2011

http://www.camdemy.com

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(Images from Hinton's slides on Coursera)

Reference: Krizhevsky, Alex, and Geoffrey E. Hinton. "Using very deep autoencoders for content-based image retrieval." ESANN. 2011





Retrieved using Euclidean distance in pixel intensity space











dist: 3139.2







dist: 3154.8

retrieved using 256 codes of auto-encoder



dist: 66

dist: 67



dist: 67

dist: 65





Created with Eve http://www.cam

dist: 61





• Greedy Layer-wise Pre-training again



Pre-training: find good initial values for weights

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Greedy Layer-wise Pre-training again



Greedy Layer-wise Pre-training again



• Greedy Layer-wise Pre-training again



Greedy Layer-wise Pre-training again





• Greedy Layer-wise Pre-training again





Greedy Layer-wise Pre-training again





Pre-training is used much less often than before, Because today we have back-propagation algorithms that can train very deep networks.

However, if we have a large set of un-labelled data and only a small set of labelled data, we can use the large set of un-labelled data to pre-train all the layers other than the last layer, and then use the small set of labelled data to train the last layer and fine tune weights in all layers.

De-noising auto-encoder



Vincent, Pascal, et al. "Extracting and composing robust features with denoising autoencoders." *ICML*, 2008.



De-noising auto-encoder



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De-noising auto-encoder



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Learning More Methods for non-linear dimension-reduction - Restricted Boltzmann Machine

- Neural networks [5.1] : Restricted Boltzmann machine definition
 - https://www.youtube.com/watch?v=p4Vh_zMw-HQ&index=36&list=PL6Xpj9I5qXYEcOhn7TqghAJ6NAPrN mUBH
- Neural networks [5.2] : Restricted Boltzmann machine inference
 - https://www.youtube.com/watch?v=lekCh_i32iE&list=PL 6Xpj9I5qXYEcOhn7TqghAJ6NAPrNmUBH&index=37
- Neural networks [5.3] : Restricted Boltzmann machine free energy
 - https://www.youtube.com/watch?v=e0Ts_7Y6hZU&list= PL6Xpj9I5qXYEcOhn7TqghAJ6NAPrNmUBH&index=38

Learning More - Deep Belief Network

Graphical Model

- Neural networks [7.7] : Deep learning deep belief network
 - https://www.youtube.com/watch?v=vkb6AWYXZ5I&list= PL6Xpj9I5qXYEcOhn7TqghAJ6NAPrNmUBH&index=57
- Neural networks [7.8] : Deep learning variational bound
 - https://www.youtube.com/watch?v=pStDscJh2Wo&list= PL6Xpj9I5qXYEcOhn7TqghAJ6NAPrNmUBH&index=58
- Neural networks [7.9] : Deep learning DBN pre-training
 - https://www.youtube.com/watch?v=35MUIYCColk&list= PL6Xpj9I5qXYEcOhn7TqghAJ6NAPrNmUBH&index=59

Autoencoder for CNN



Autoencoder for CNN



Autoencoder for CNN



As close as possible

CNN - Unpooling



Source of image :

https://leonardoaraujosantos.gitbooks.io/artificialinteligence/content/image_segmentat

CNN - Unpooling







CNN - Deconvolution

- Deconvolution



- Deconvolution

convolution





- Deconvolution

convolution



- Deconvolution

convolution



- Deconvolution

convolution deconvolution

Intuitively, in deconvolution, every left node should correspond to 3 right node.

Actually, deconvolution is convolution.









How to know which region to sample, if the code has more than 2 dimensions? We can use L2 regularization during training,

