CSCE 636 Neural Networks (Deep Learning)

Lecture 11: Deep Reinforcement Learning

Anxiao (Andrew) Jiang

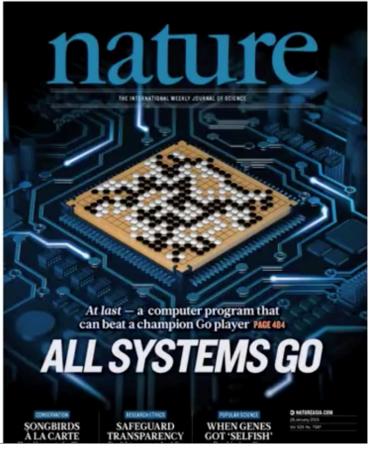
Based on the interesting lecture of Prof. Hung-yi Lee "Deep Reinforcement Learning" https://www.youtube.com/watch?v=W8XF3ME8G2I&list=PLJV_eI3uVTsPy9oCRY30oBPNLCo89yu49&index=33

Deep Reinforcement Learning

Scratching the surface

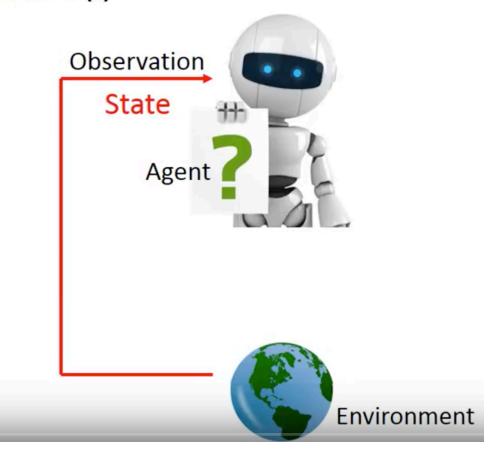
Deep Reinforcement Learning

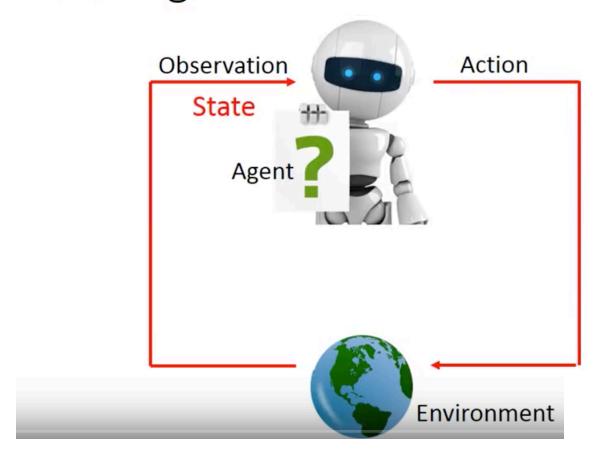


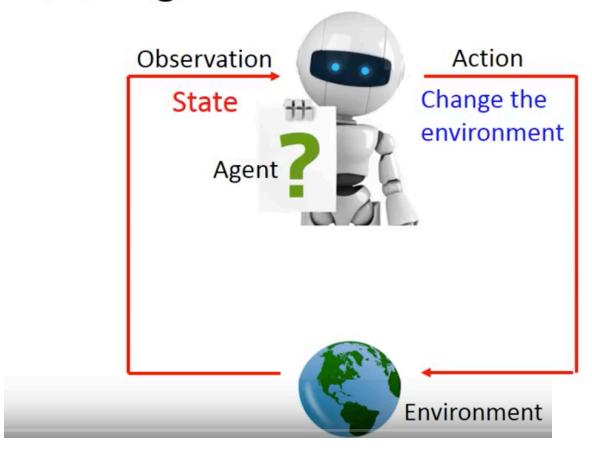


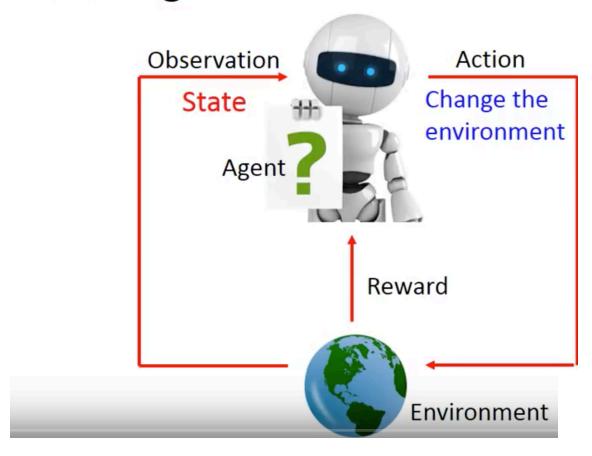


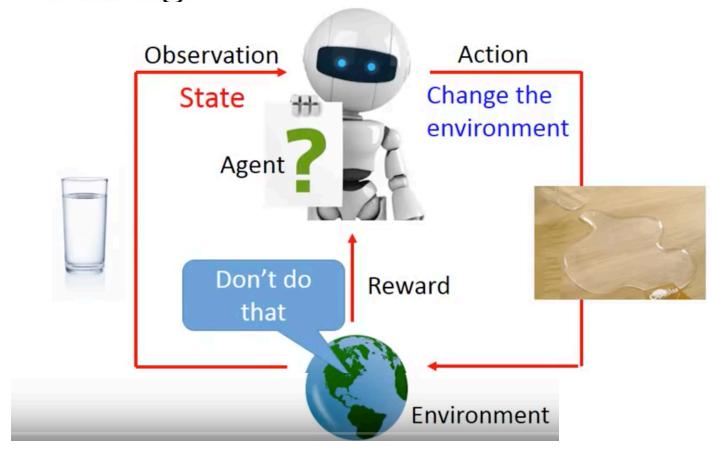


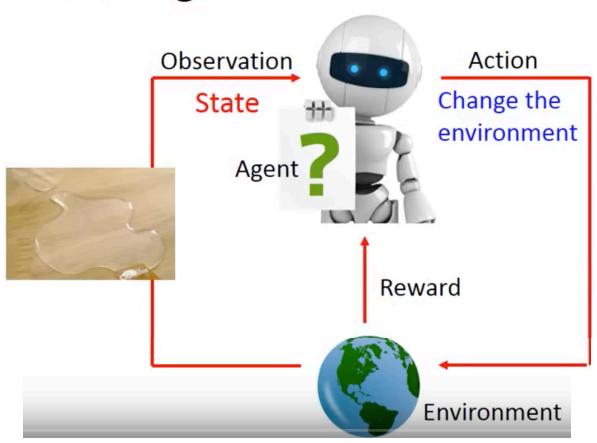


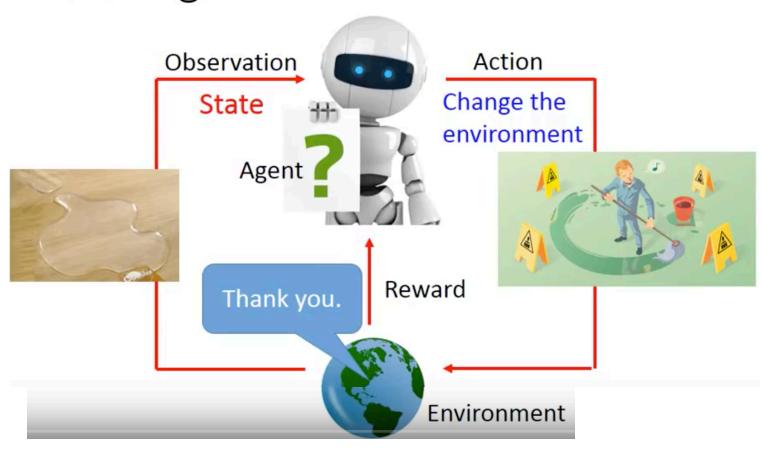






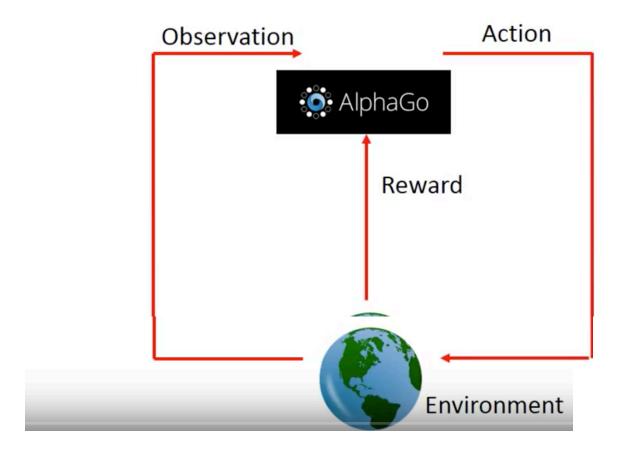


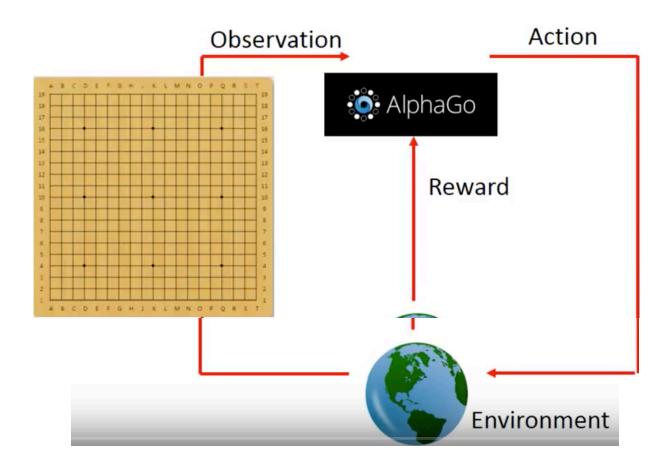


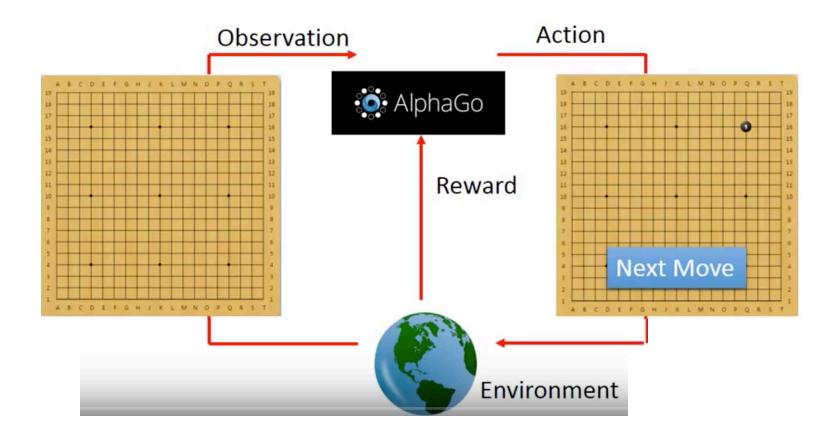


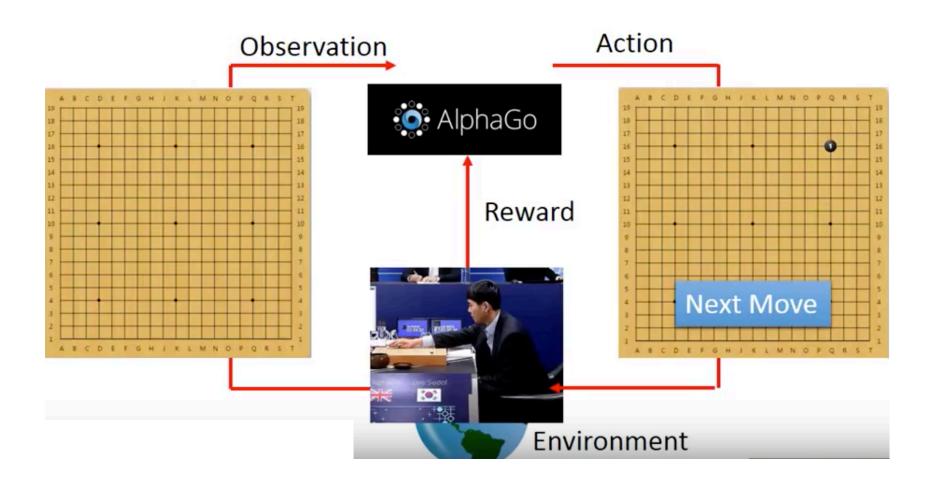
Scenario of Reinforcement

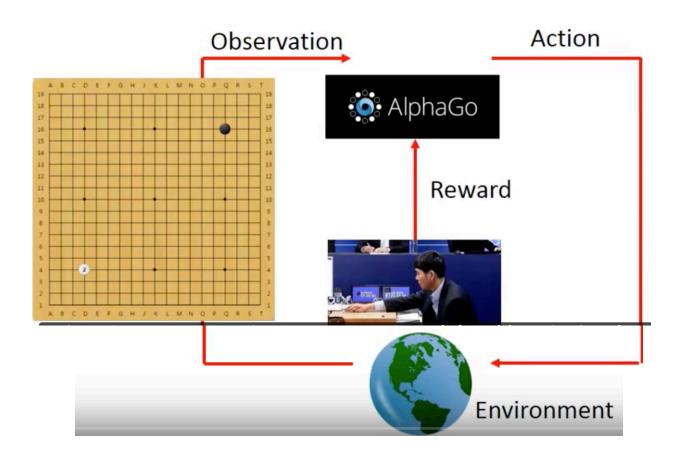


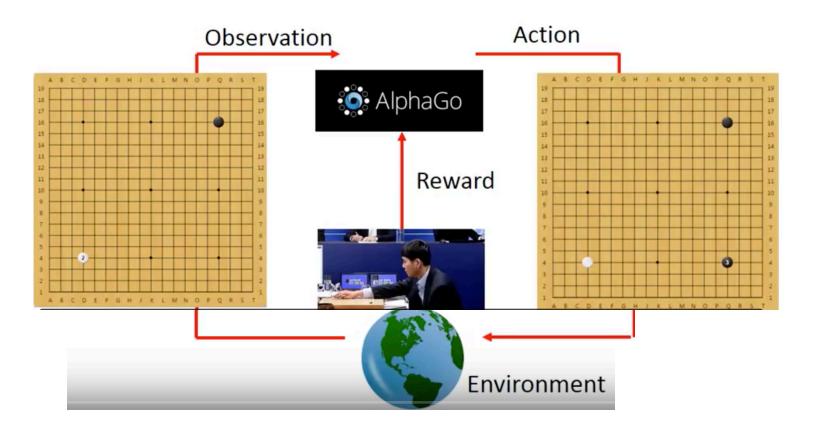


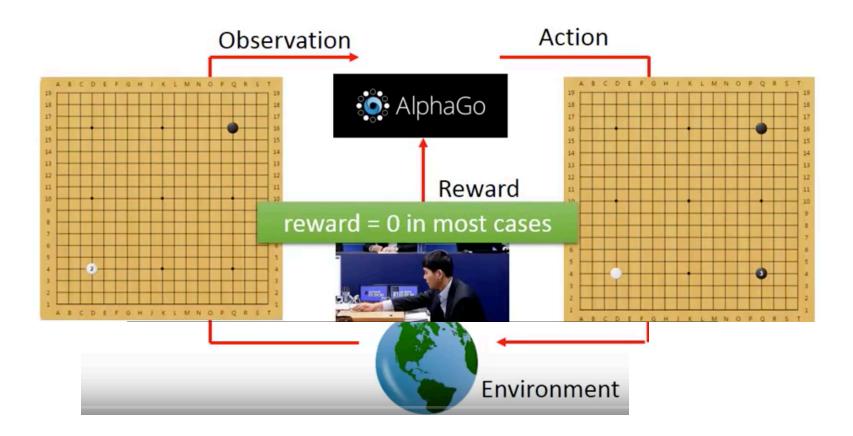


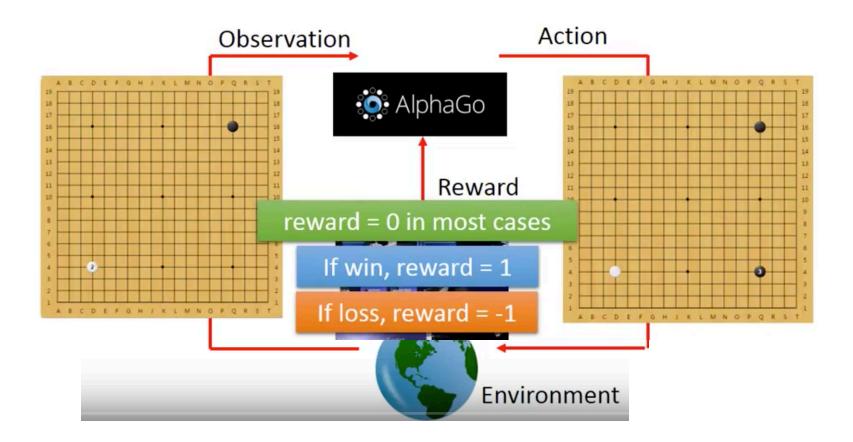




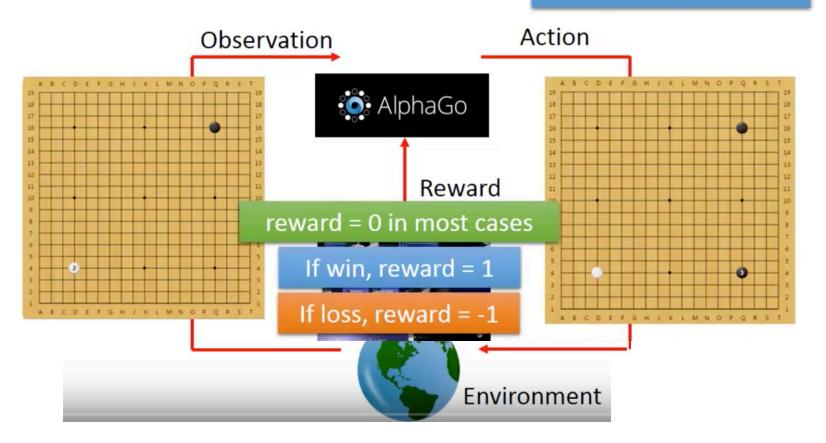








Agent learns to take actions to maximize expected reward.



- Supervised v.s. Reinforcement
- Supervised:

- Supervised v.s. Reinforcement
- Supervised:



Next move: "5-5"



Next move: "3-3"

- Supervised v.s. Reinforcement
- Supervised: Learning from teacher



Next move: "5-5"



Next move: "3-3"

- Supervised v.s. Reinforcement
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Next move: "5-5"



Next move: "3-3"

Reinforcement Learning

First move many moves

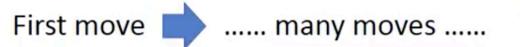
- Supervised v.s. Reinforcement
- Supervised: Learning from teacher



Next move: "5-5"



Next move: "3-3"





- Supervised v.s. Reinforcement
- Supervised: Learning from teacher



Next move: "5-5"



Next move: "3-3"

Reinforcement Learning

Learning from experience

First move



..... many moves



Win!

- Supervised v.s. Reinforcement
- Supervised: Learning from teacher



Next move: "5-5"



Next move: "3-3"

Reinforcement Learning

Learning from experience



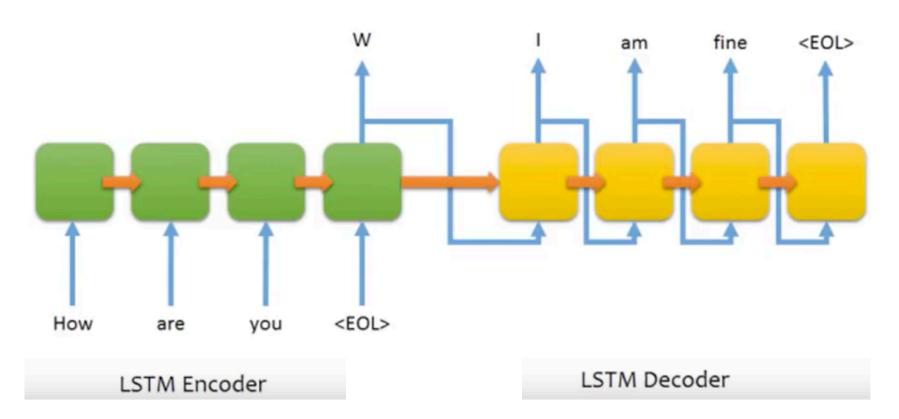
First move many moves



(Two agents play with each other.)

Alpha Go is supervised learning + reinforcement learning.

Sequence-to-sequence learning



- Supervised v.s. Reinforcement

Supervised



Reinforcement

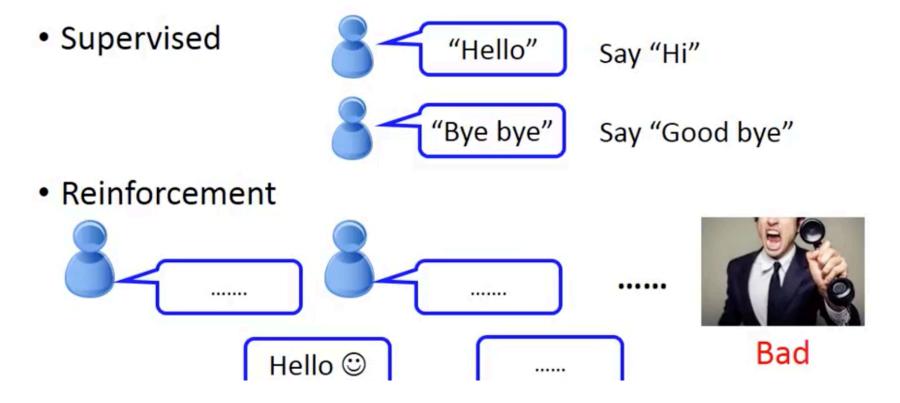
- Supervised v.s. Reinforcement

Supervised



Reinforcement

- Supervised v.s. Reinforcement



More applications

- Flying Helicopter
 - https://www.youtube.com/watch?v=0JL04JJjocc
- Driving
 - https://www.youtube.com/watch?v=0xo1Ldx3L5Q
- Google Cuts Its Giant Electricity Bill With DeepMind-Powered AI
 - http://www.bloomberg.com/news/articles/2016-07-19/google-cuts-itsgiant-electricity-bill-with-deepmind-powered-ai
- Text generation
 - Hongyu Guo, "Generating Text with Deep Reinforcement Learning", NIPS, 2015
 - Marc'Aurelio Ranzato, Sumit Chopra, Michael Auli, Wojciech Zaremba, "Sequence Level Training with Recurrent Neural Networks", ICLR, 2016

Example: Playing Video Game

- Widely studies:
 - Gym: https://gym.openai.com/
 - Universe: https://openai.com/blog/universe/



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 - Gym: https://gym.openai.com/
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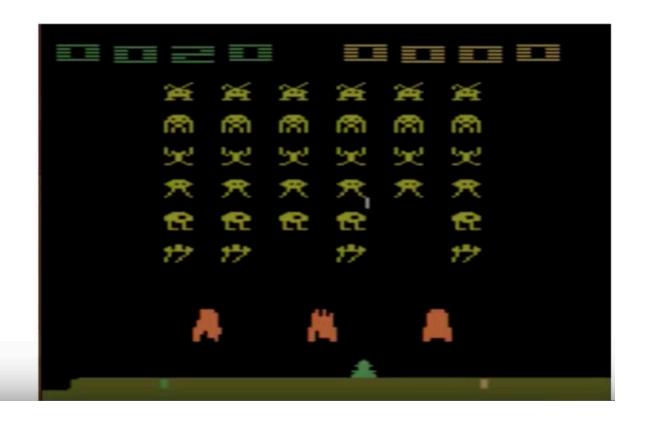
Machine learns to play video games as human players

What machine observes is pixels

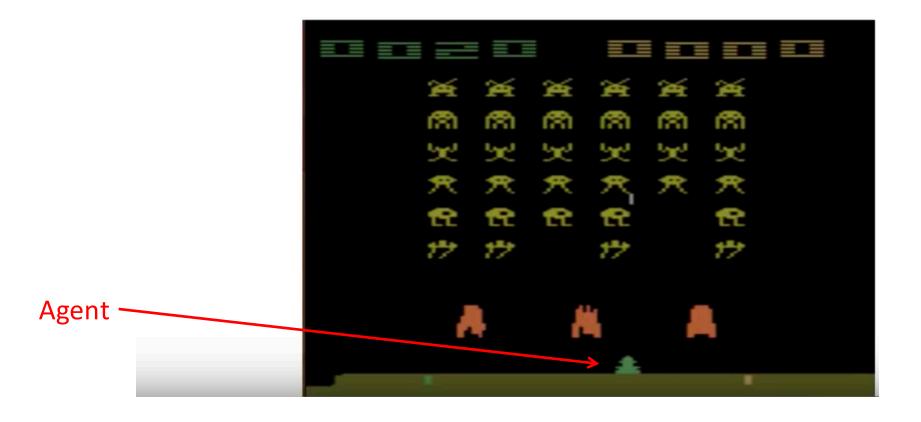


Example: Playing Video Game

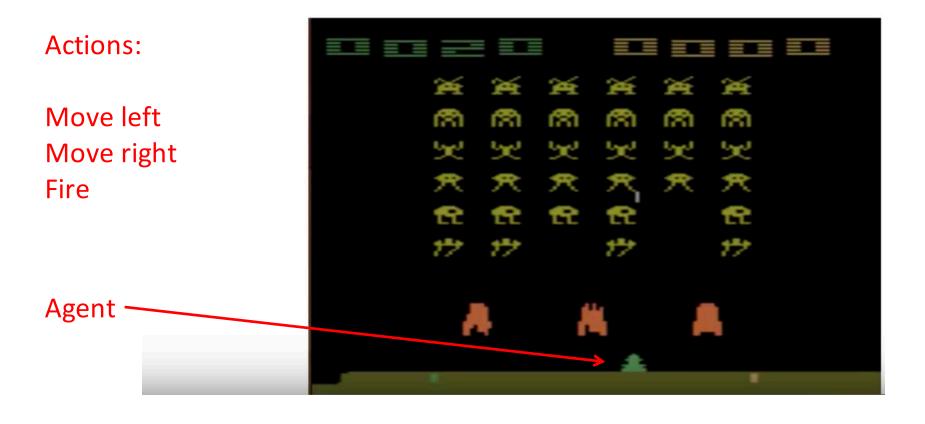
Space invader



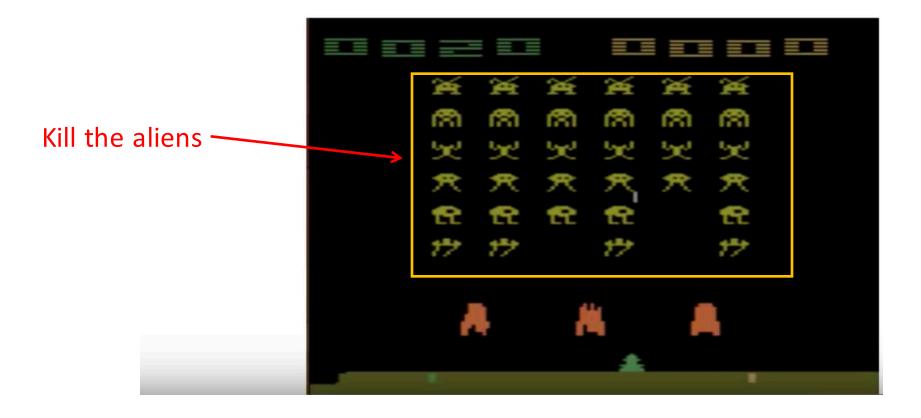
Space invader



Space invader

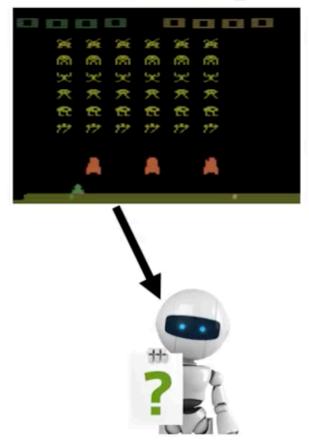


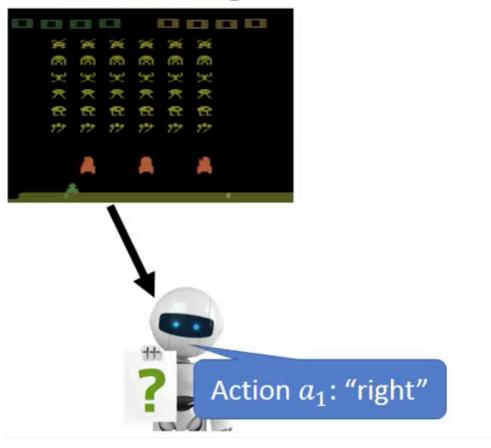
Space invader

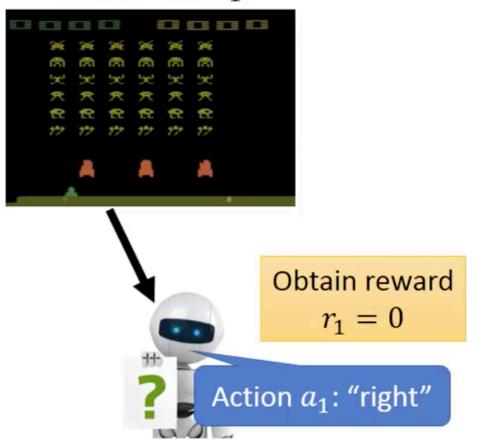


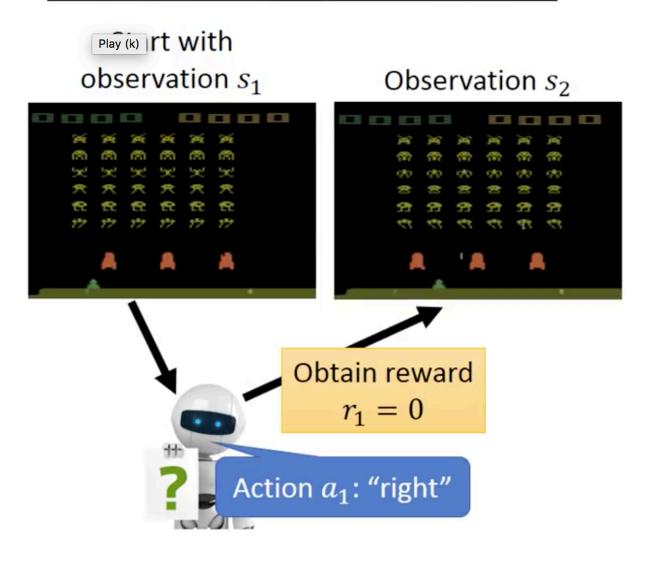
https://www.youtube.com/watch?v= ftVrgJTl4w

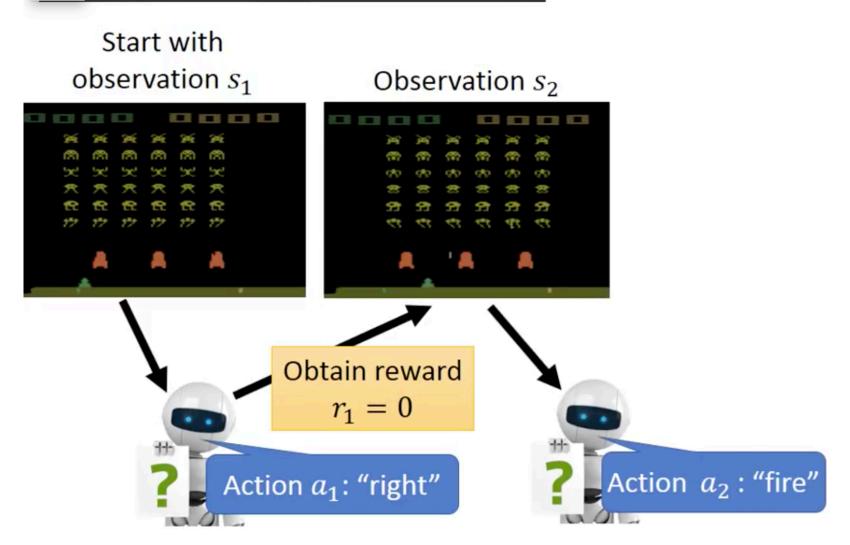


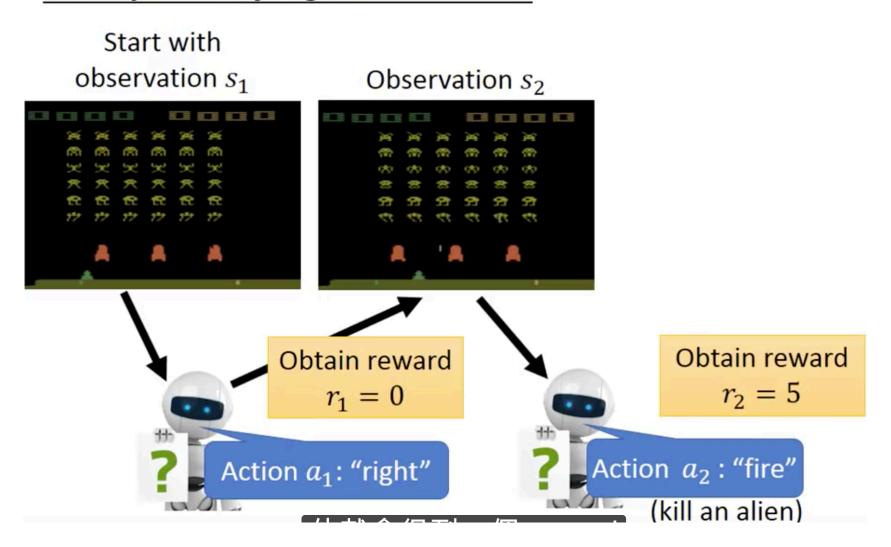


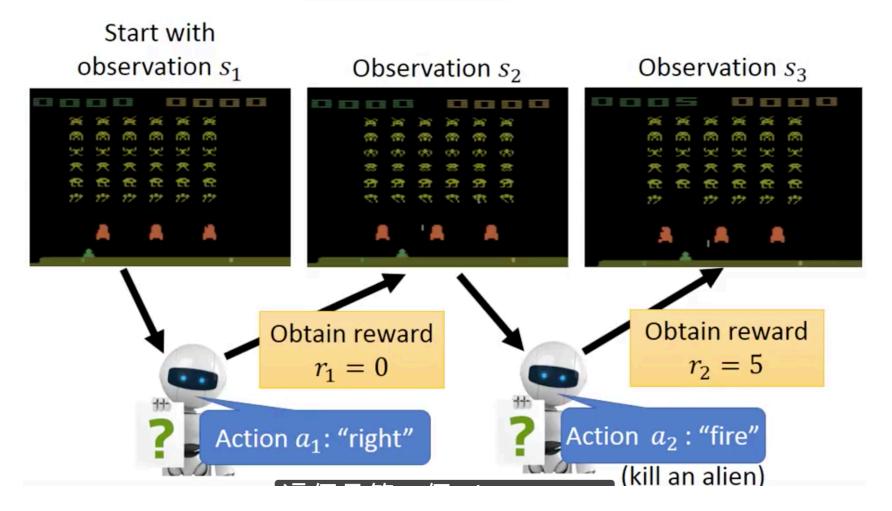








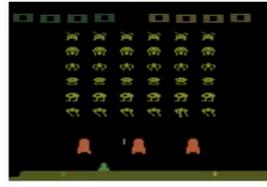




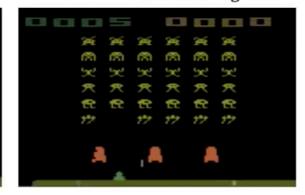
Start with observation s_1



Observation s_2



Observation s_3

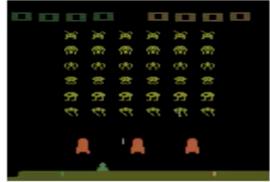


After many turns

Start with observation s_1



Observation s_2



Observation s_3

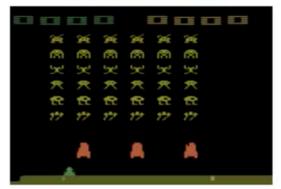


After many turns

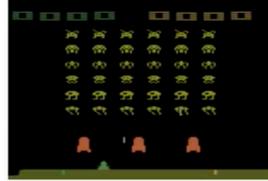


One "Episode"

Start with observation s_1







Observation s_3



After many turns



This is an episode.

Learn to maximize the expected cumulative reward per episode

Difficulties of Reinforcement Learning



Difficulties of Reinforcement Learning

- Reward delay
 - In space invader, only "fire" obtains reward
 - Although the moving before "fire" is important
 - In Go playing, it may be better to sacrifice immediate reward to gain more long-term reward

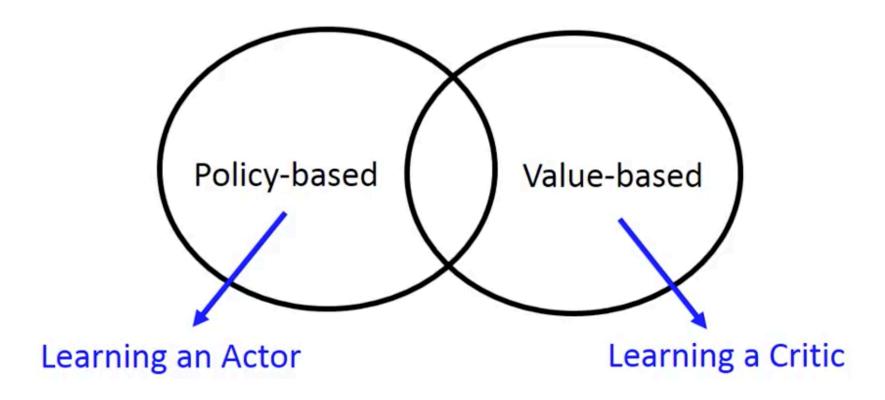


Difficulties of Reinforcement Learning

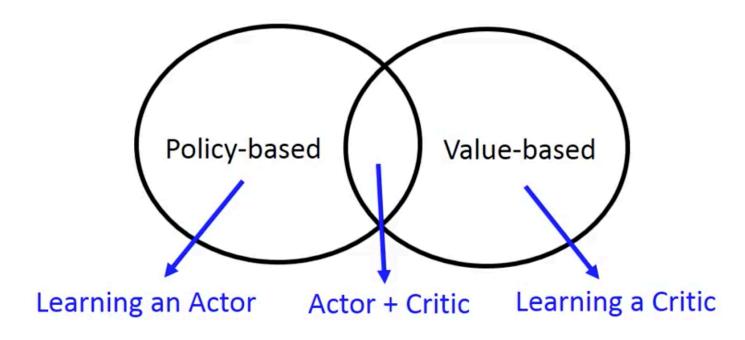
- Reward delay
 - · In space invader, only "fire" obtains reward
 - Although the moving before "fire" is important
 - In Go playing, it may be better to sacrifice immediate reward to gain more long-term reward
- Agent's actions affect the subsequent data it receives



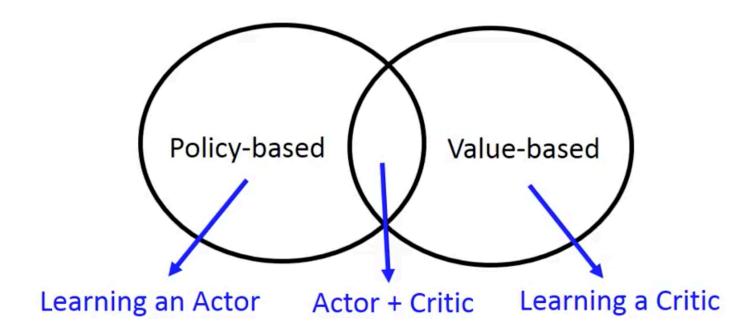
Outline



Outline

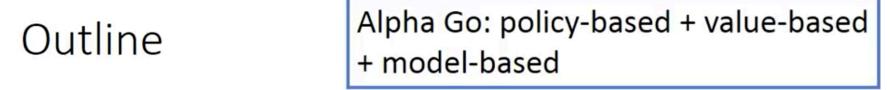


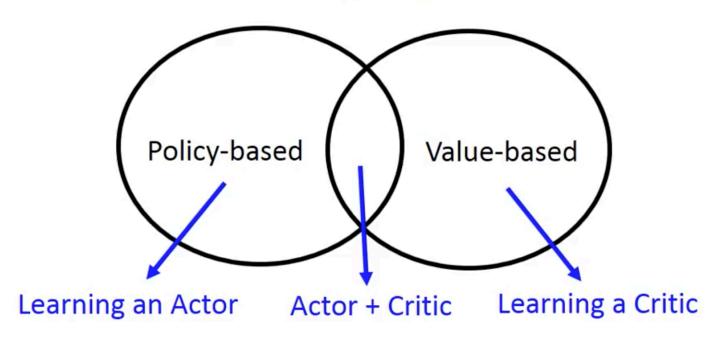
Outline



Asynchronous Advantage Actor Critic (A3C)

Volodymyr Mnih et al., "Asynchronous Methods for Deep Reinforcement Learning," ICML, 2016.





Asynchronous Advantage Actor Critic (A3C)

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To learn deep reinforcement learning

- Textbook: Reinforcement Learning: An Introduction
 - https://webdocs.cs.ualberta.ca/~sutton/book/thebook.html
- Lectures of David Silver
 - http://www0.cs.ucl.ac.uk/staff/D.Silver/web/Teaching.ht ml (10 lectures, 1:30 each)
 - http://videolectures.net/rldm2015_silver_reinforcement_learning/ (Deep Reinforcement Learning)
- Lectures of John Schulman
 - https://youtu.be/aUrX-rP_ss4

Policy-based Approach Learning an Actor

Note: Actor means "Agent"