CSCE 636 Neural Networks (Deep Learning)

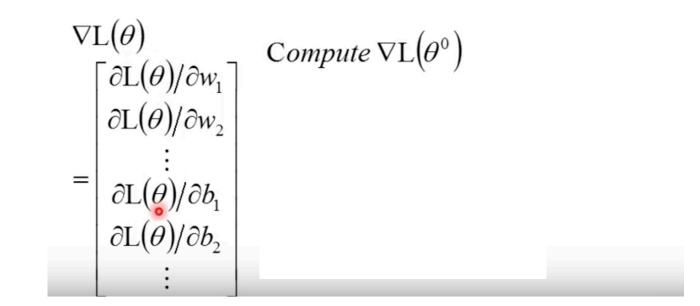
Lecture 3: Gradient Descent and Backpropagation Algorithm

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Based on interesting lecture by Prof. Hung-yi Lee, https://www.youtube.com/watch?v=ibJpTrp5mcE

Gradient Descent

Network parameters $\theta = \{w_1, w_2, \cdots, b_1, b_2, \cdots\}$ Starting Parameters θ^0



Gradient Descent

Network parameters
$$\theta = \{w_1, w_2, \dots, b_1, b_2, \dots\}$$

Starting
Parameters $\theta^0 \longrightarrow \theta^1$
 $\nabla L(\theta)$
 $\begin{bmatrix} \partial L(\theta) / \partial w_1 \\ \partial L(\theta) / \partial w_2 \\ \vdots \\ \partial L(\theta) / \partial b_1 \\ \partial L(\theta) / \partial b_2 \end{bmatrix}$
 $ext{Compute } \nabla L(\theta^0)$
 $\theta^1 = \theta^0 - \eta \nabla L(\theta^0)$
 $\theta^1 = \theta^0 - \eta \nabla L(\theta^0)$
 $ext{learning rate} (such as 0.001)$

Gradient Descent

Network parameters
$$\theta = \{w_1, w_2, \dots, b_1, b_2, \dots\}$$

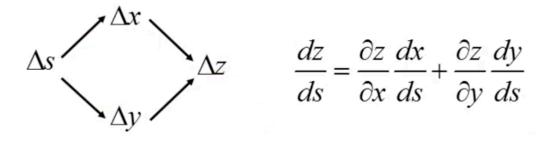
Starting
Parameters $\theta^0 \longrightarrow \theta^1 \longrightarrow \theta^2 \longrightarrow \dots$
 $\nabla L(\theta)$
 $\begin{bmatrix} \partial L(\theta) / \partial w_1 \\ \partial L(\theta) / \partial w_2 \\ \vdots \\ \partial L(\theta) / \partial b_1 \\ \partial L(\theta) / \partial b_2 \\ \vdots \end{bmatrix}$
Compute $\nabla L(\theta^1)$ $\theta^1 = \theta^0 - \eta \nabla L(\theta^0)$
 $Compute \nabla L(\theta^1)$ $\theta^2 = \theta^1 - \eta \nabla L(\theta^1)$
Millions of parameters
To compute the gradients efficiently
we use backpropagation.

Chain Rule

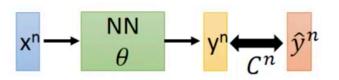
Case 1
$$y = g(x)$$
 $z = h(y)$
 $\Delta x \to \Delta y \to \Delta z$ $\frac{dz}{dx} = \frac{dz}{dy}\frac{dy}{dx}$

Case 2

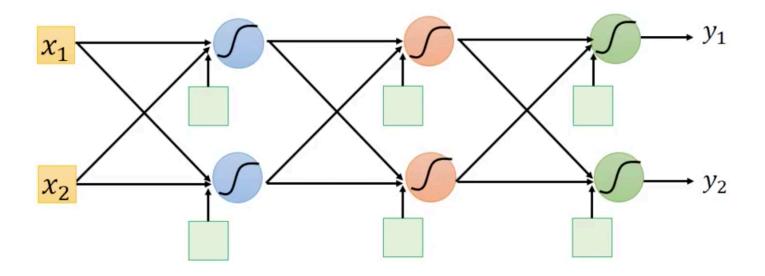
$$x = g(s)$$
 $y = h(s)$ $z = k(x, y)$

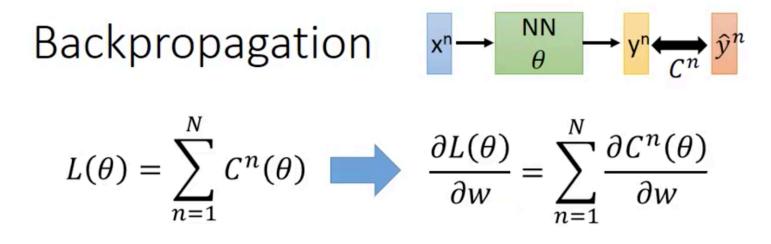


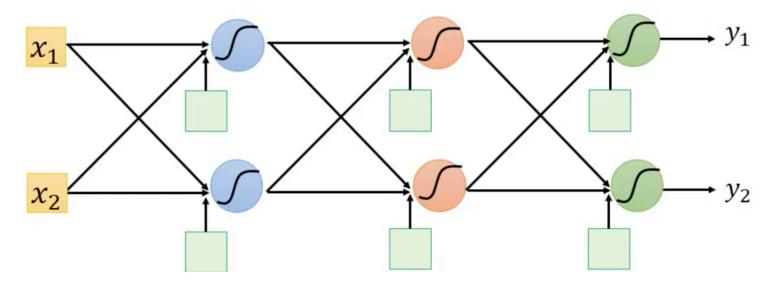


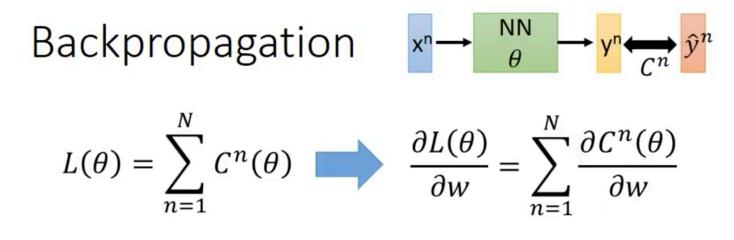


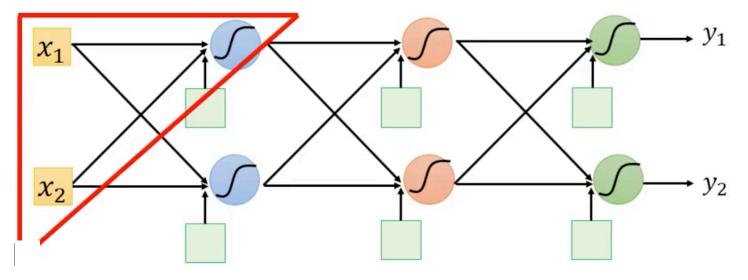
$$L(\theta) = \sum_{n=1}^{N} C^{n}(\theta)$$

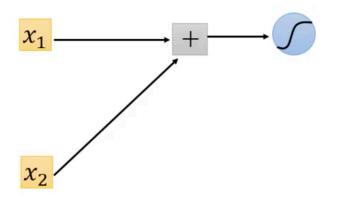


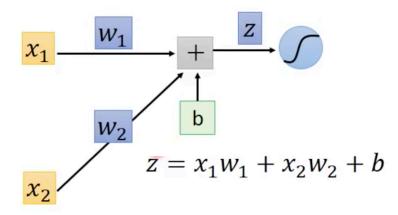


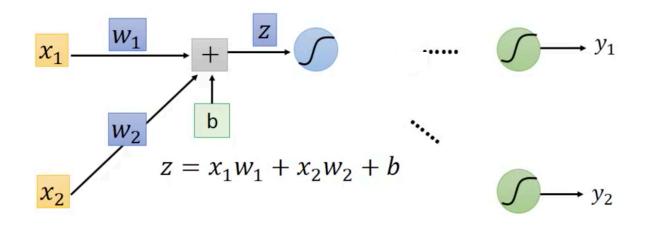


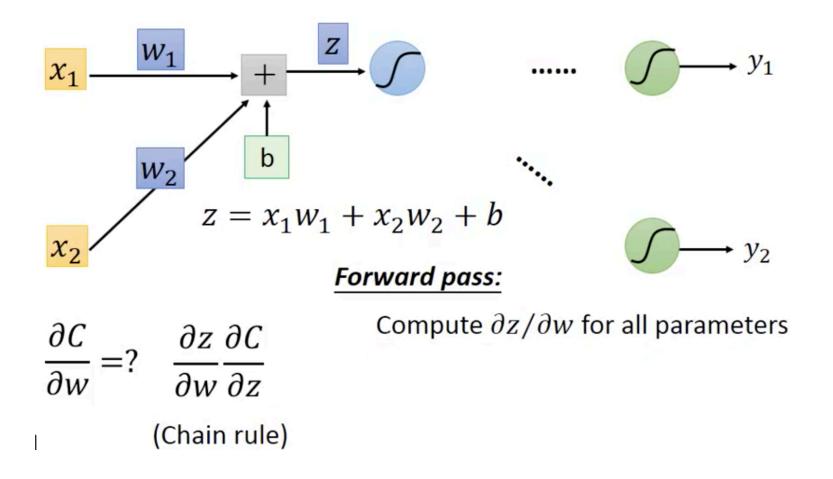


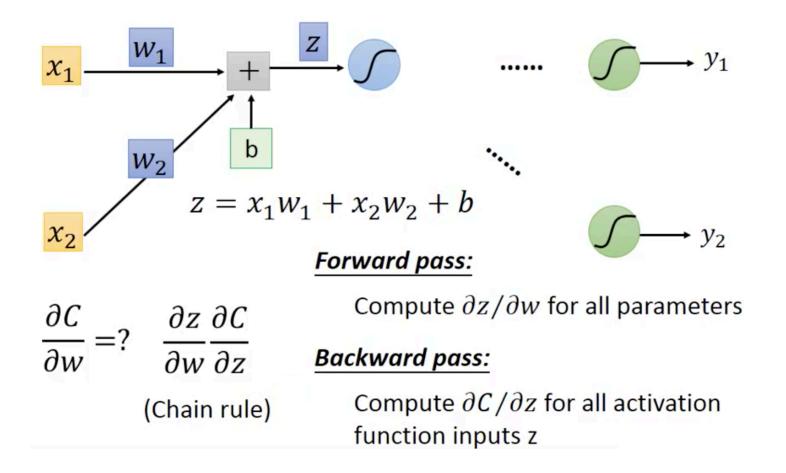




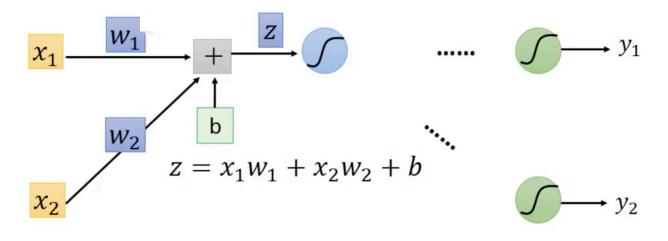






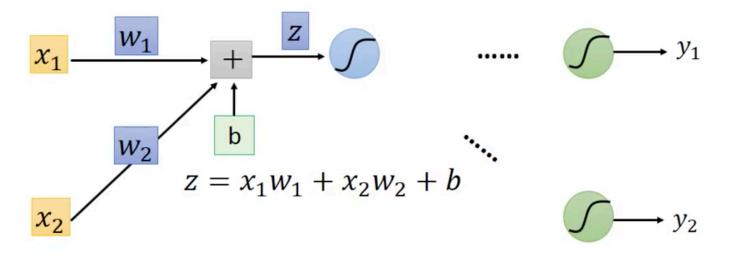


Compute $\partial z / \partial w$ for all parameters

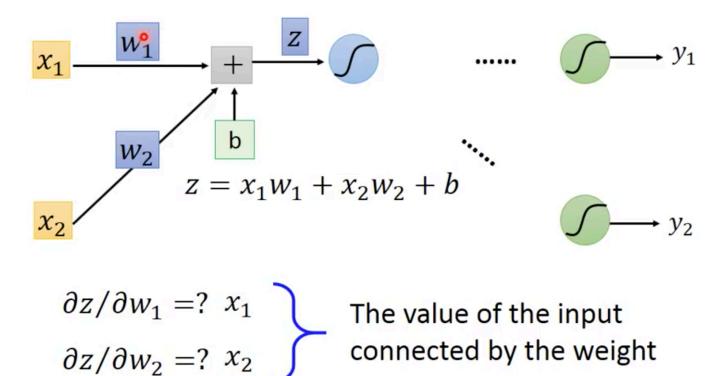


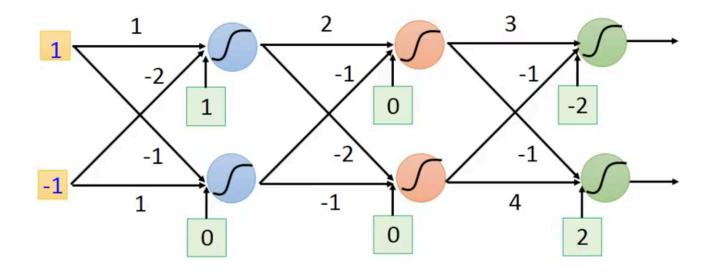
 $\partial z / \partial w_1 = ?$

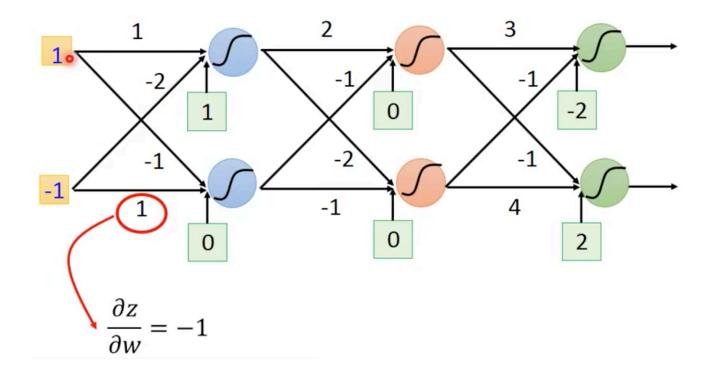
Compute $\partial z / \partial w$ for all parameters

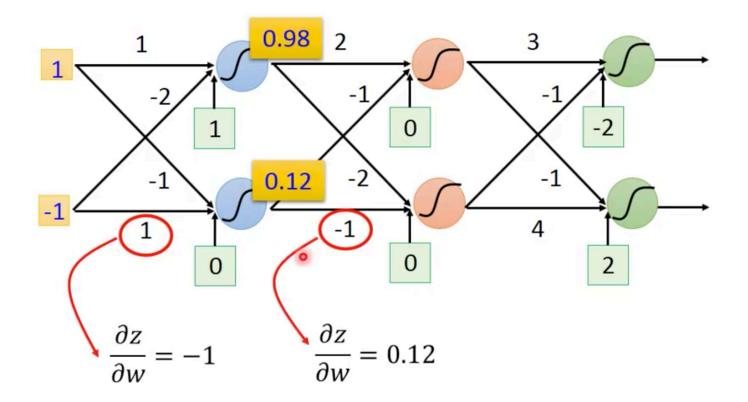


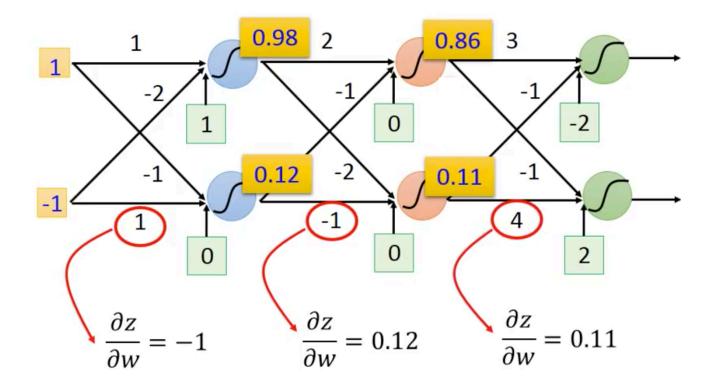
 $\partial z / \partial w_1 = ? x_1$ $\partial z / \partial w_2 = ? x_2$



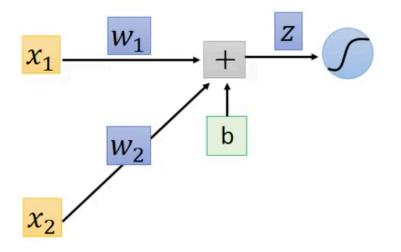




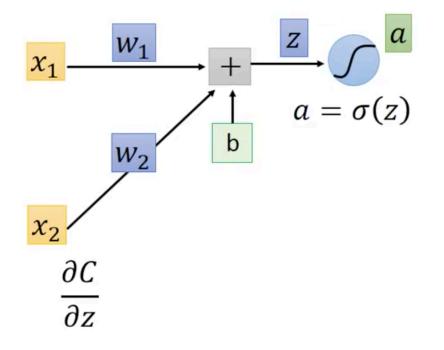




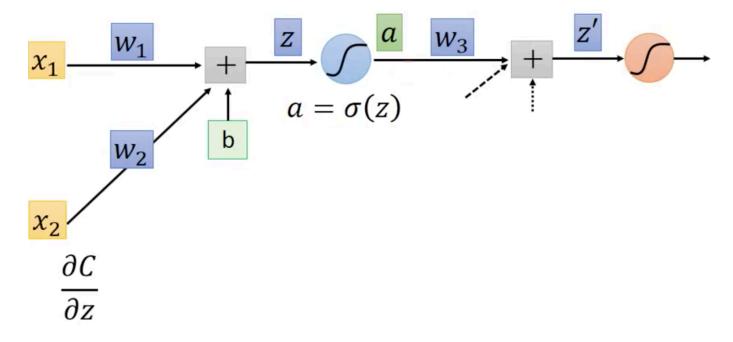
Compute $\partial C / \partial z$ for all activation function inputs z



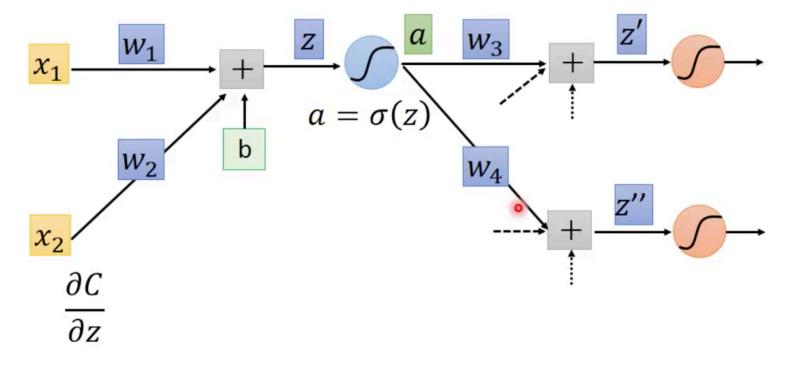
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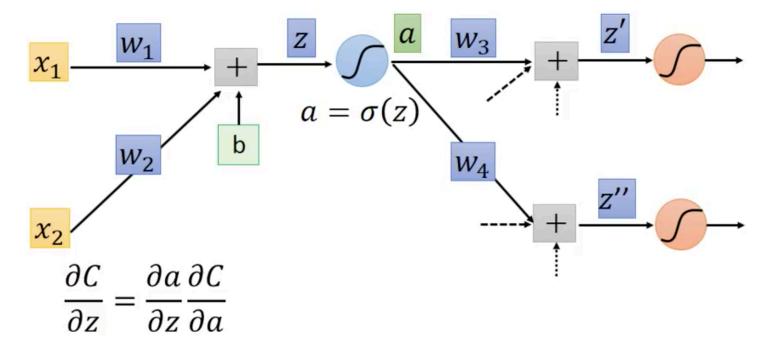
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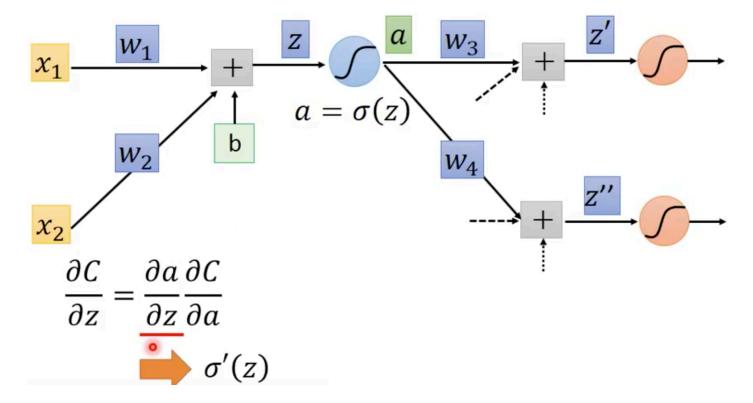
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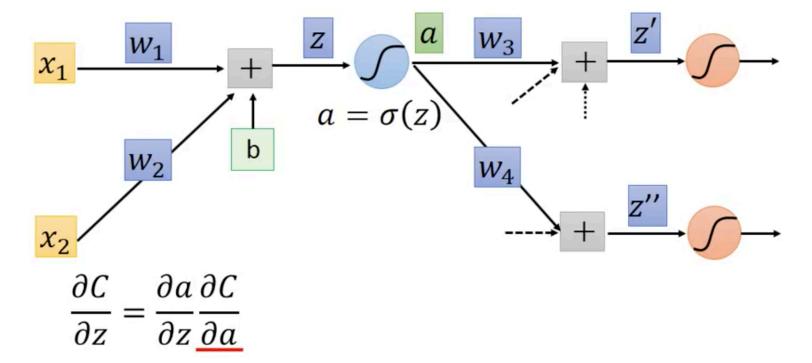
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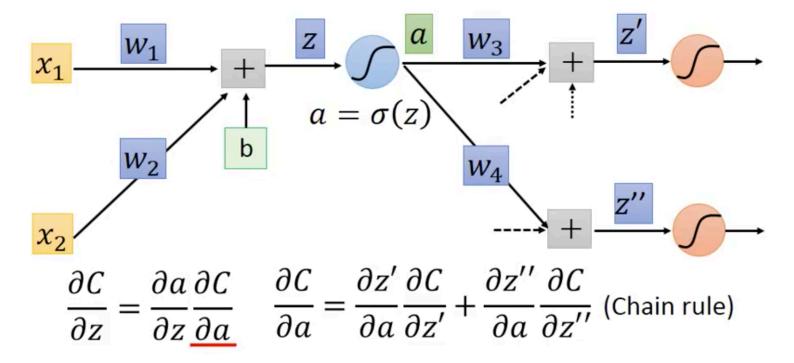
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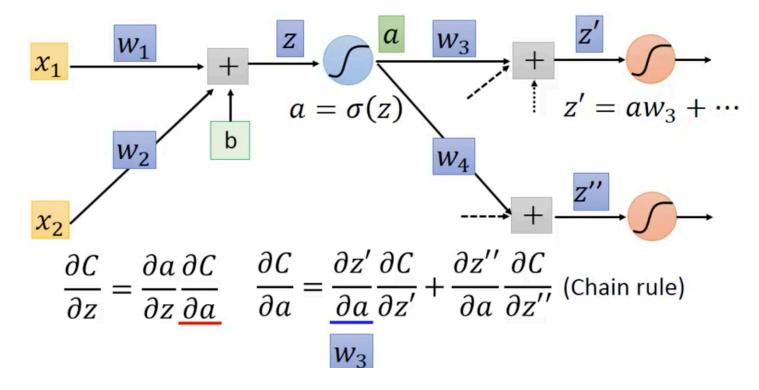
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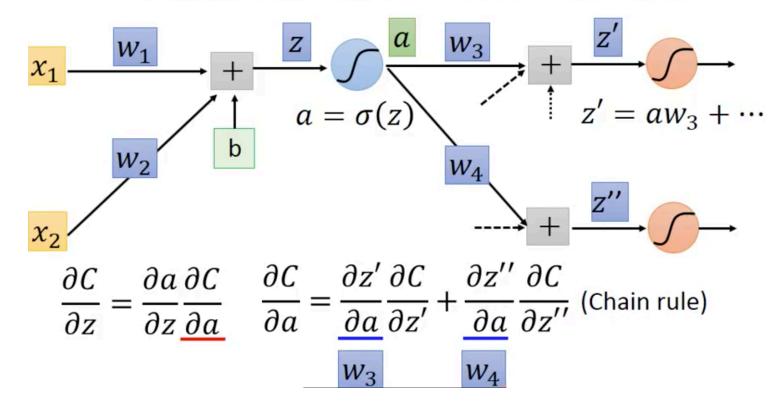
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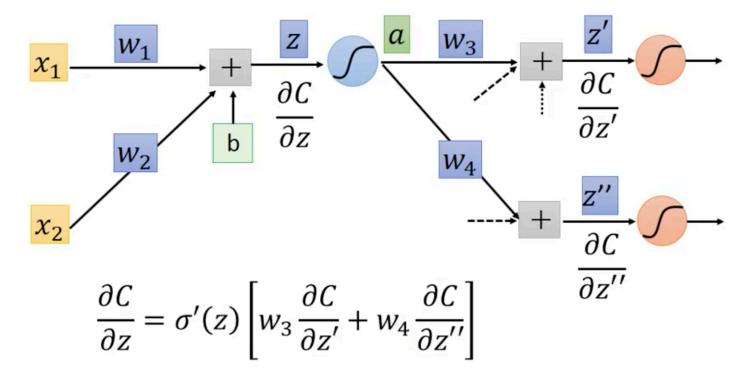
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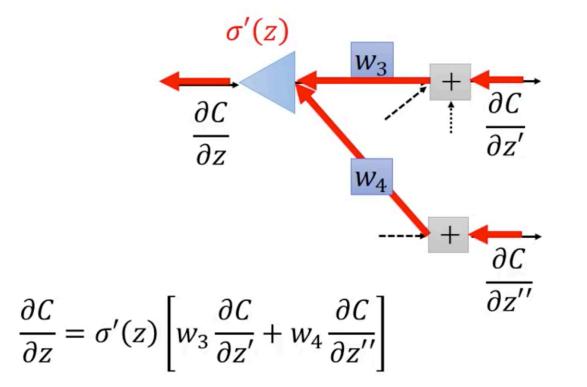


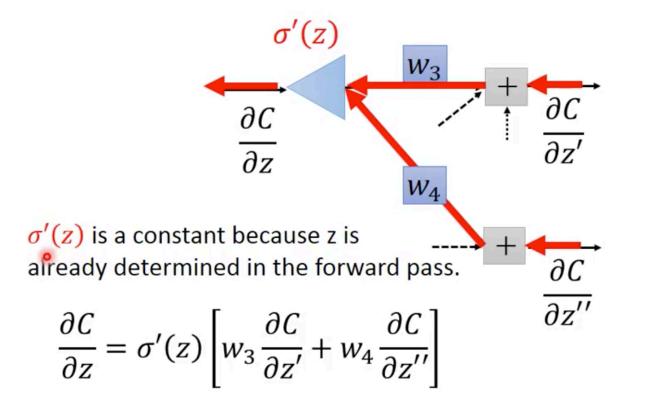
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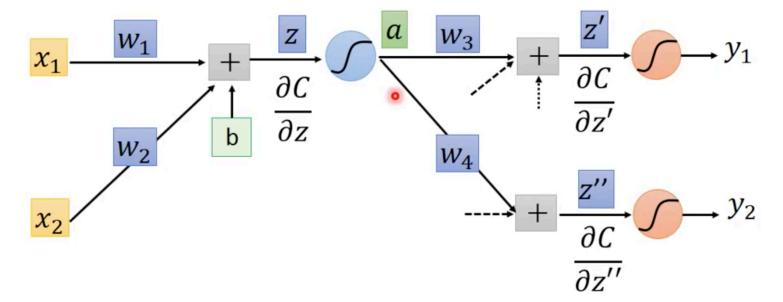
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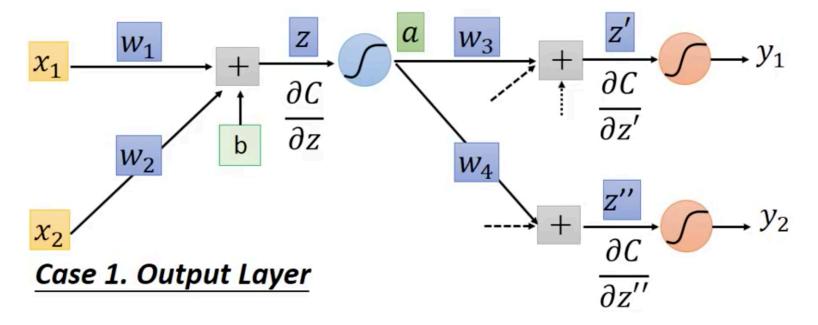




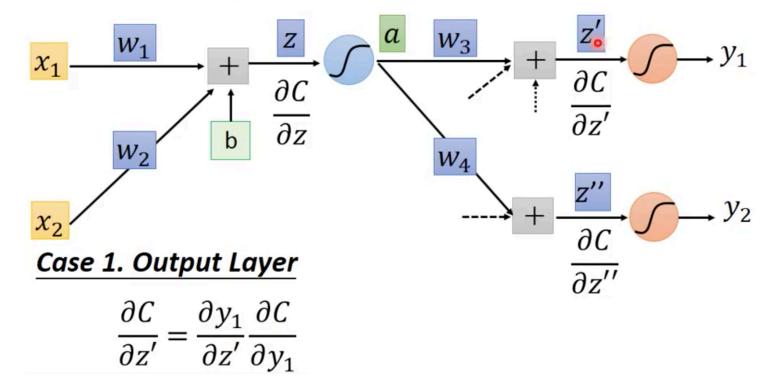
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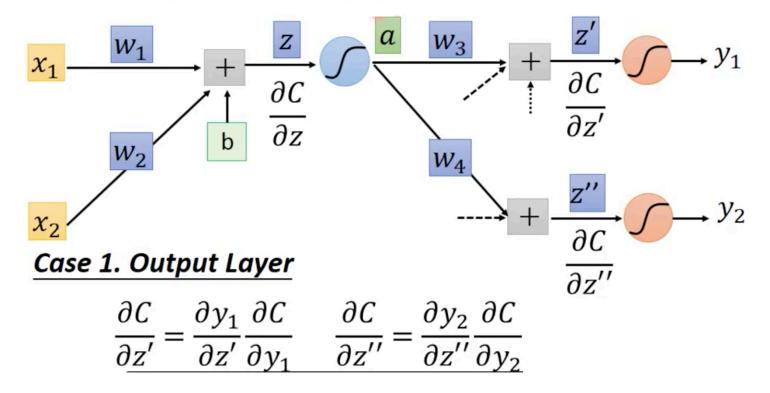
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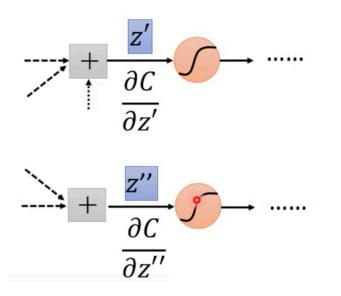
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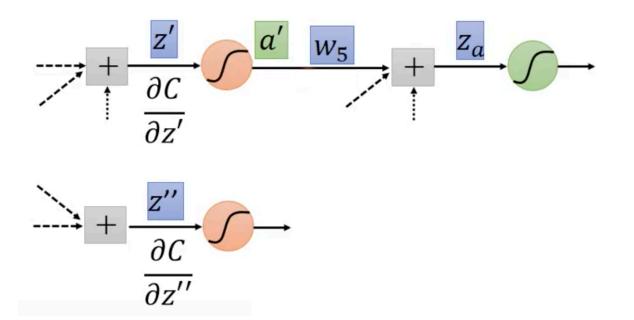
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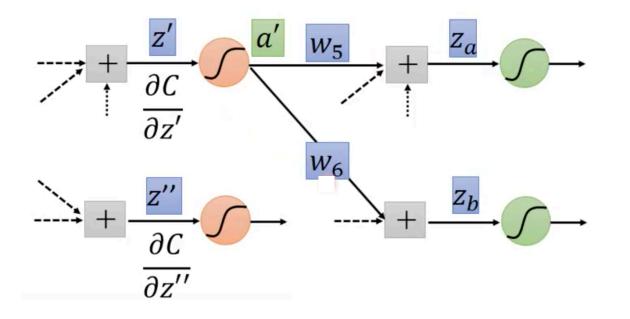
Compute $\partial C / \partial z$ for all activation function inputs z



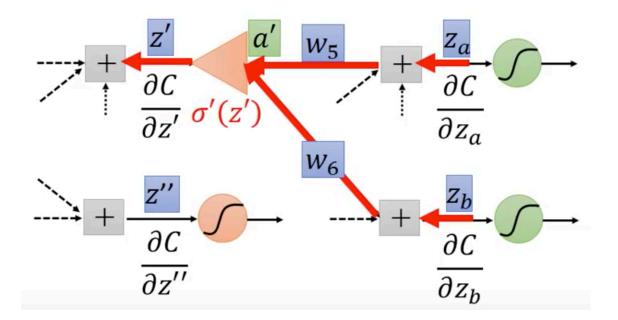
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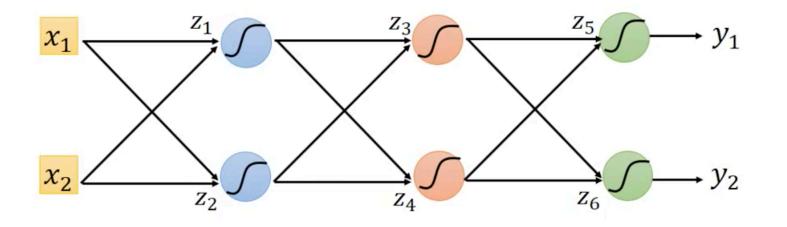
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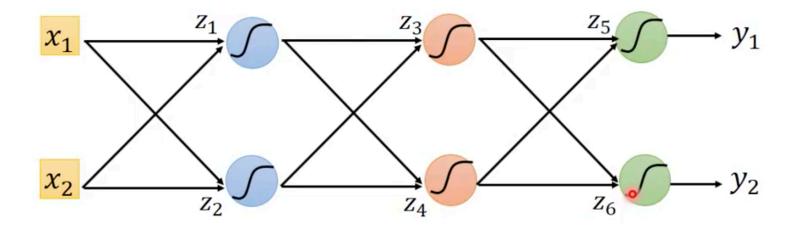


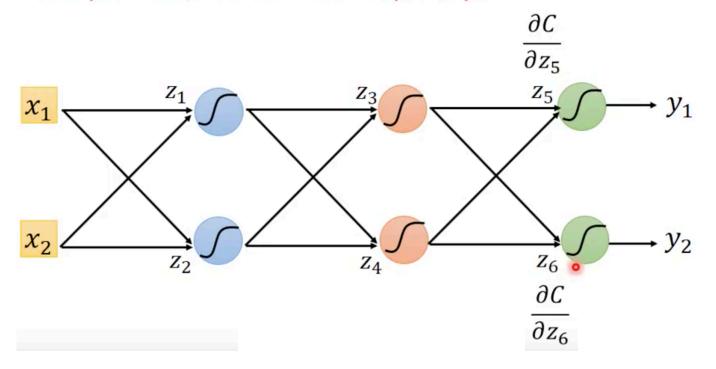
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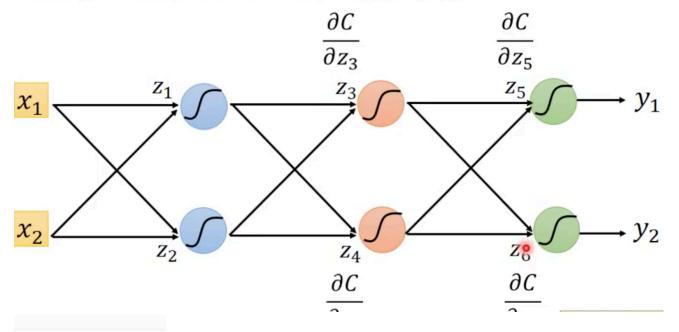


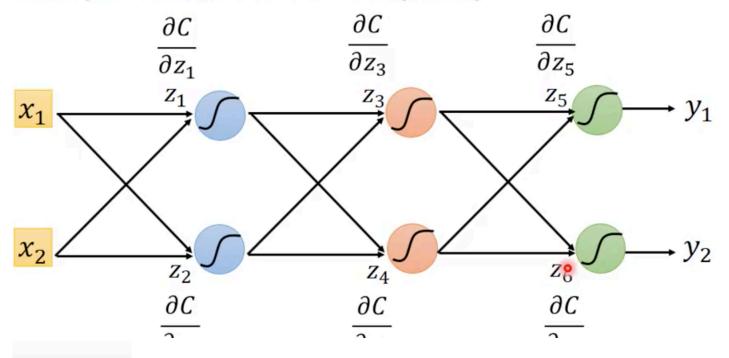
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Forward Pass

Backward Pass

